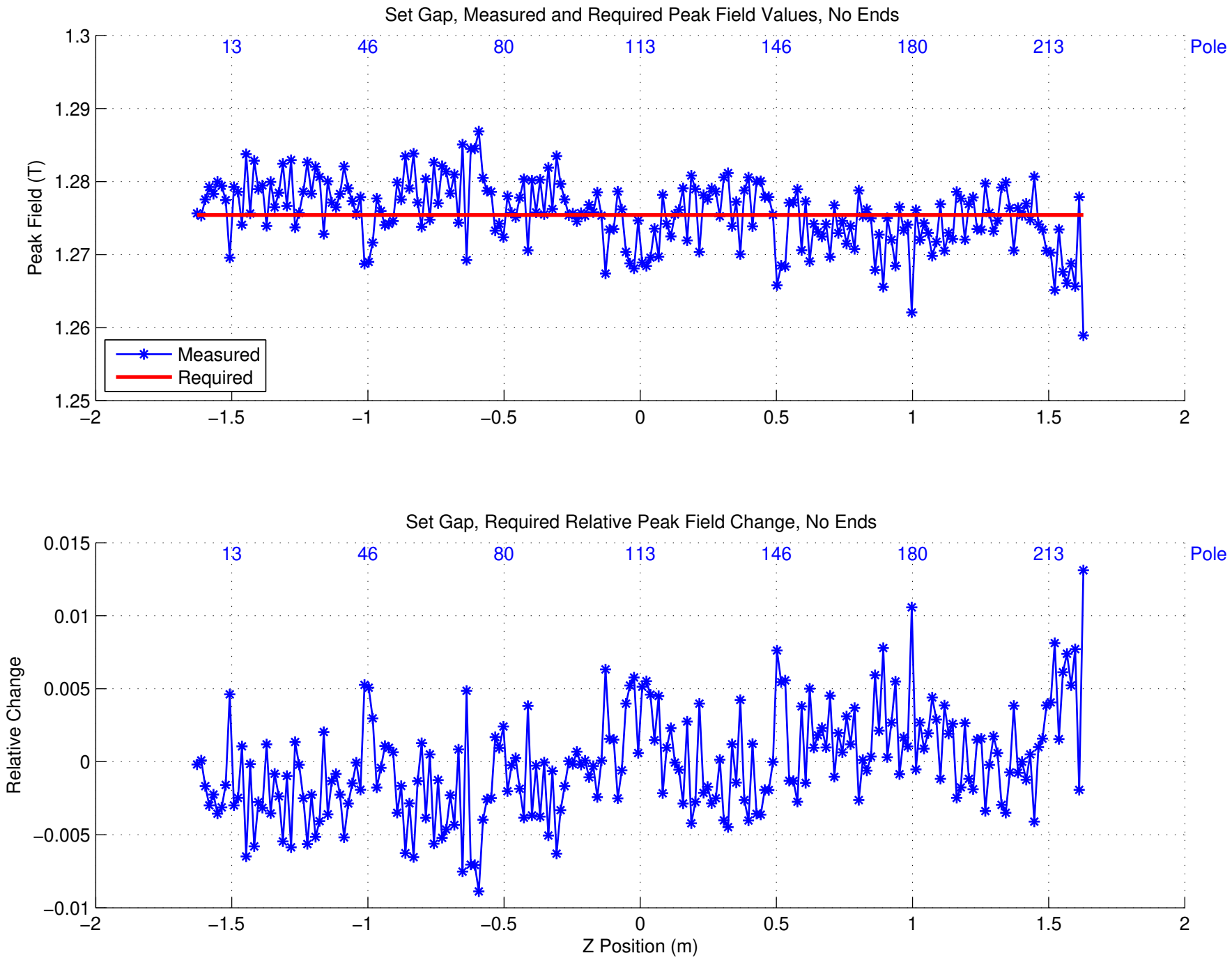
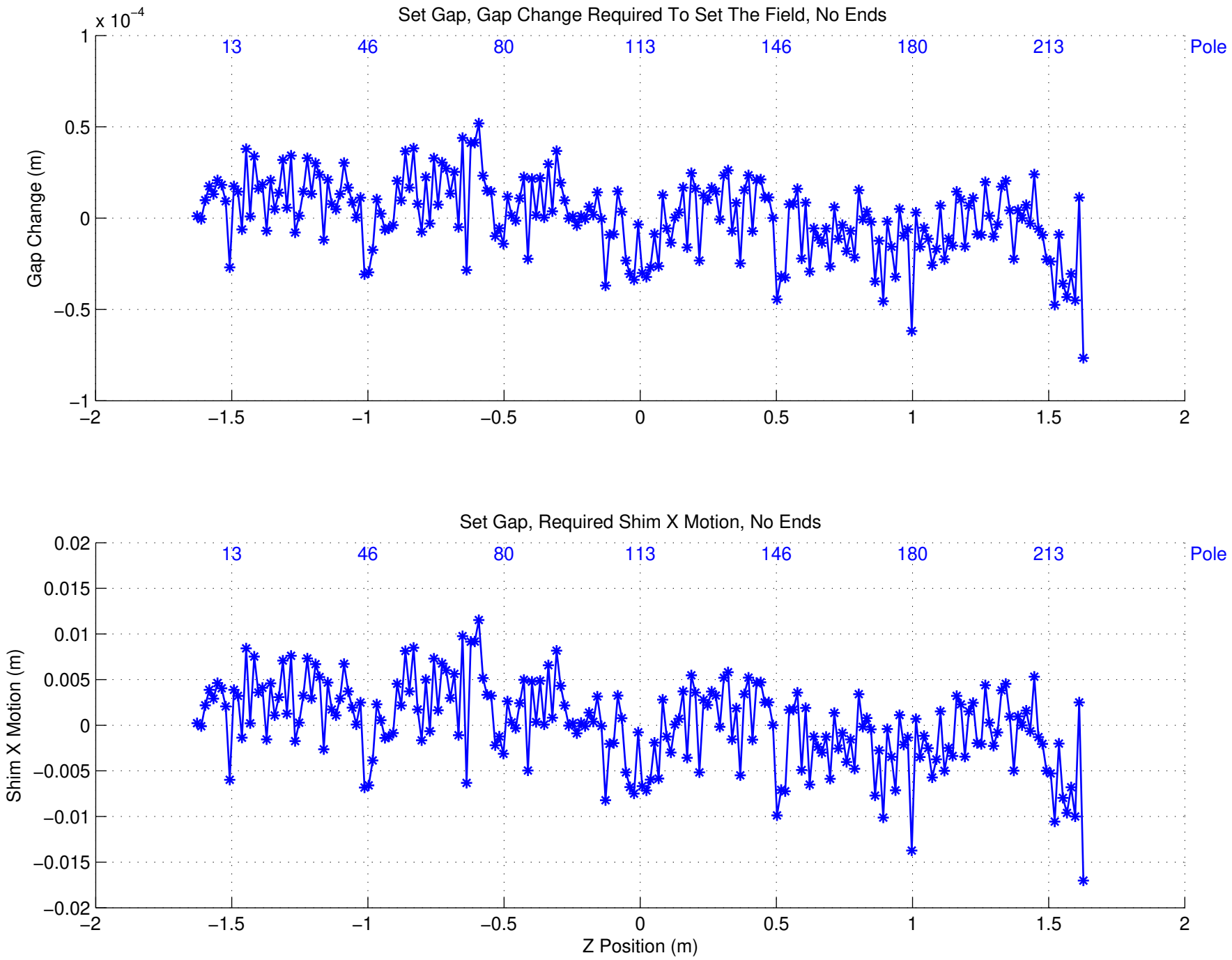
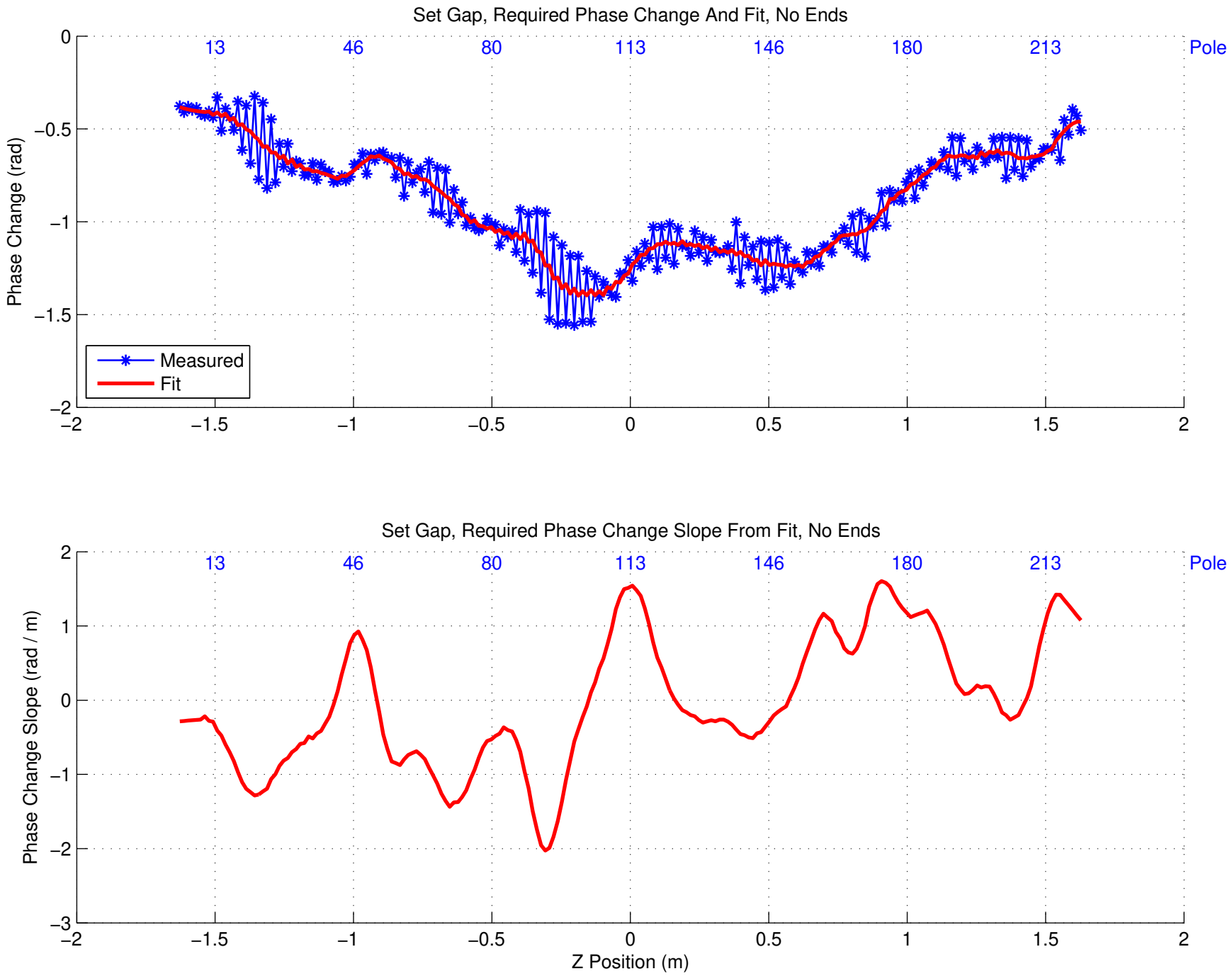
SLAC Magnetic Measurements

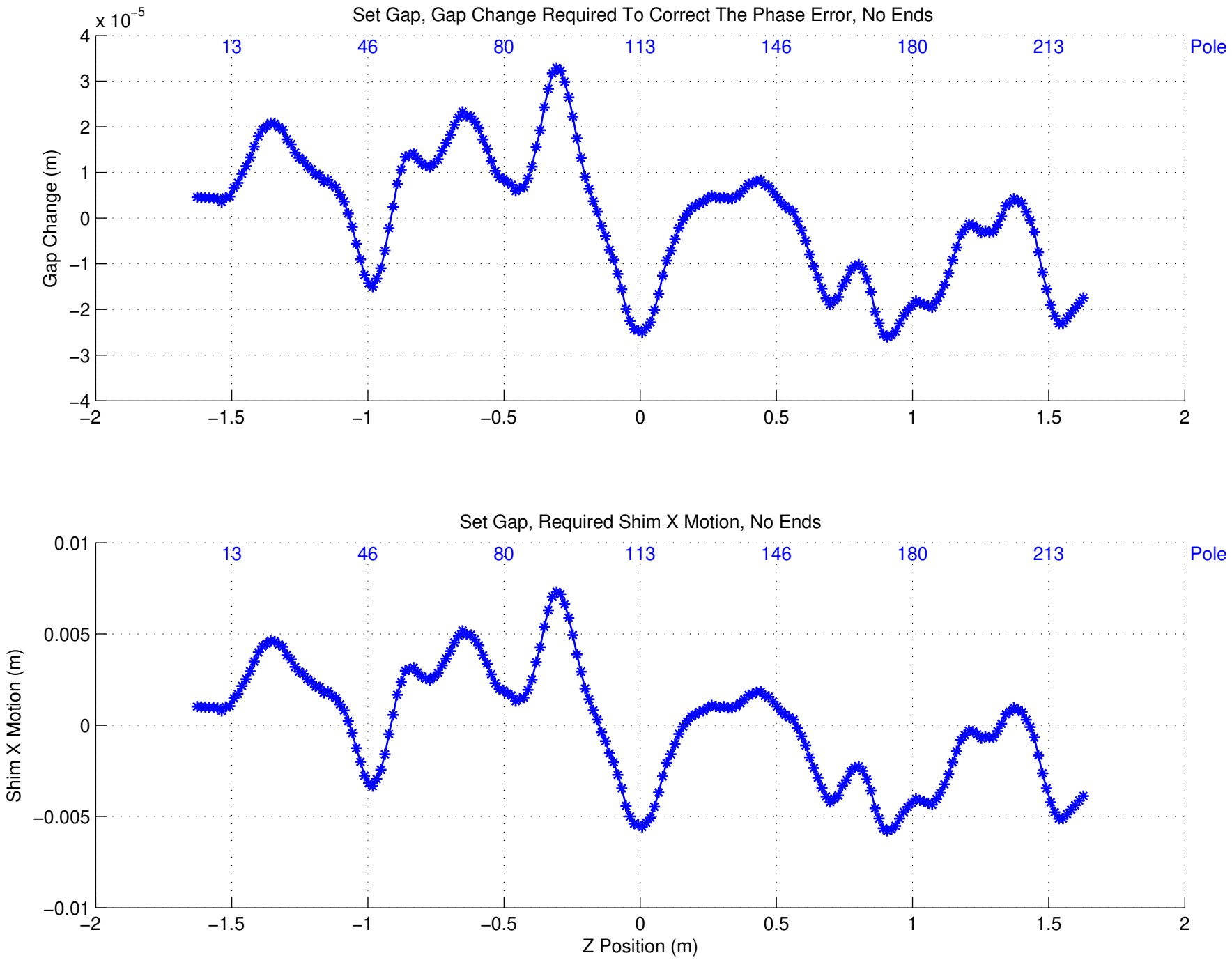
Planar Insertion Device Shim Analysis

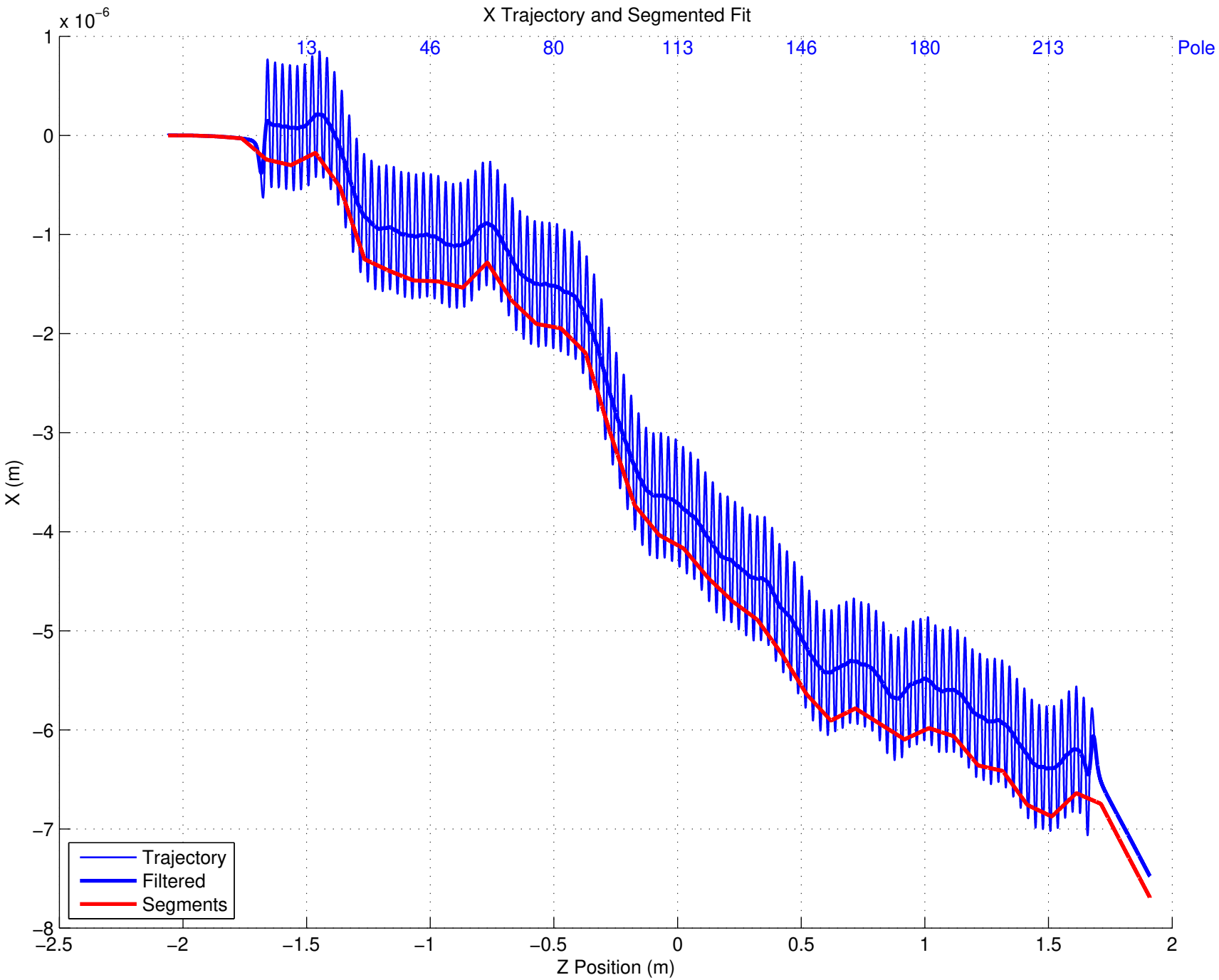
Parameters:
INPUT−FILE−DIR =S:\MagData\LCLS\Undulator\L143−112000−16\DATASET0001\Rough Tuning\Z Scans\Run 004\
INPUT−FILE−NAME =x+00000−y+000−bscanz.dat
INPUT−FILE−TYPE =ZVXYBXYH
CORR−REQUIRED =1
GAMMA =26682.25
NOM−LAMBDA−U =0.03
NOM−K−VALUE =3.4977
NOM−LAMBDA−R =1.4995e−010
NUM−POLES =226
NUM−END−POLES =4
CELL−LENGTH =3.656

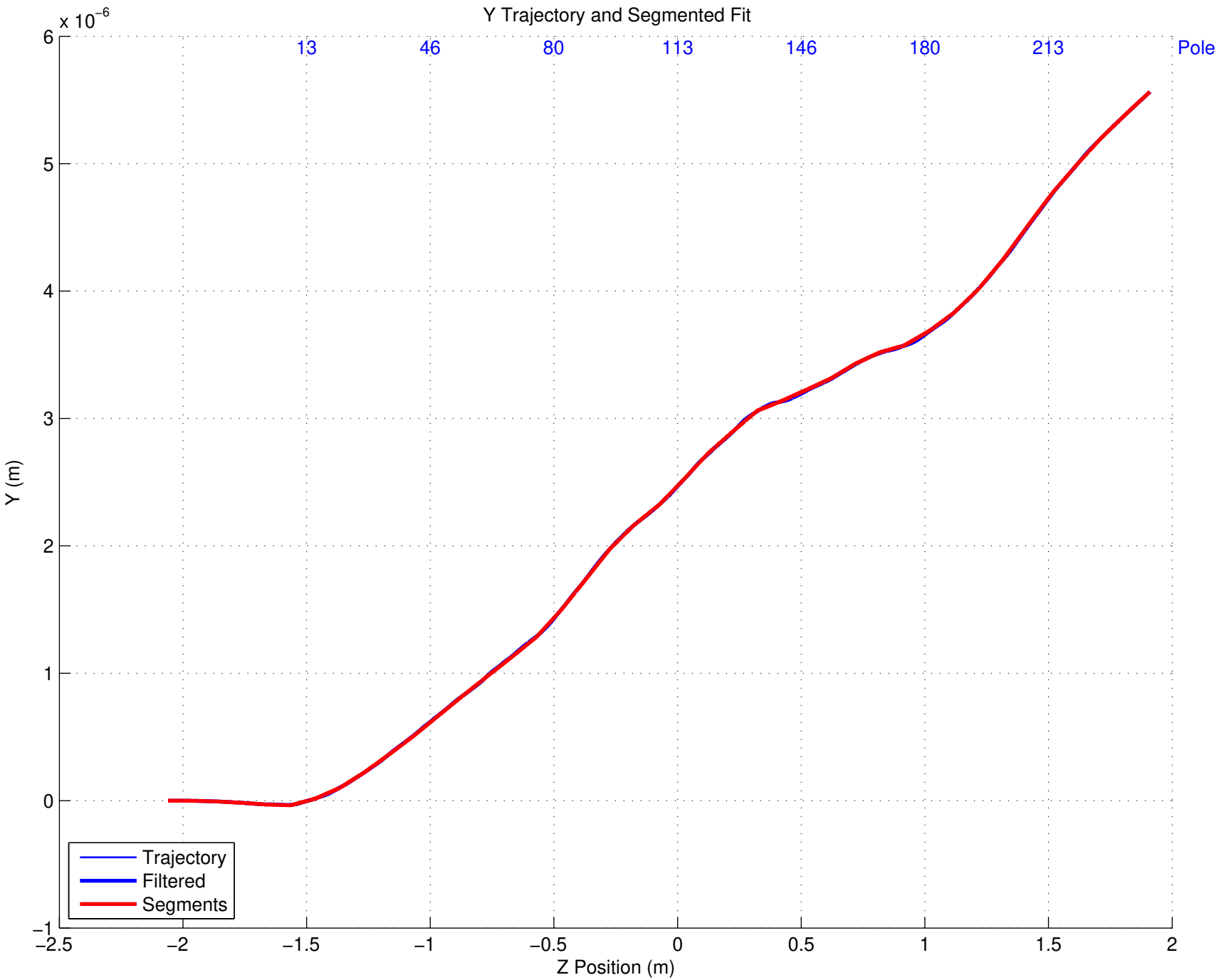

Set Gap, Measured and Required Peak Field Values, No Ends
13
46
80
113
146
180
213
Pole
Peak Field (T)
1.3
1.29
1.28
1.27
1.26
1.25
Measured
Required
−2
−1.5
−1
−0.5
0
0.5
1
1.5
2
Set Gap, Required Relative Peak Field Change, No Ends
Relative Change
0.015
0.01
0.005
0
−0.005
−0.01
Z Position (m)

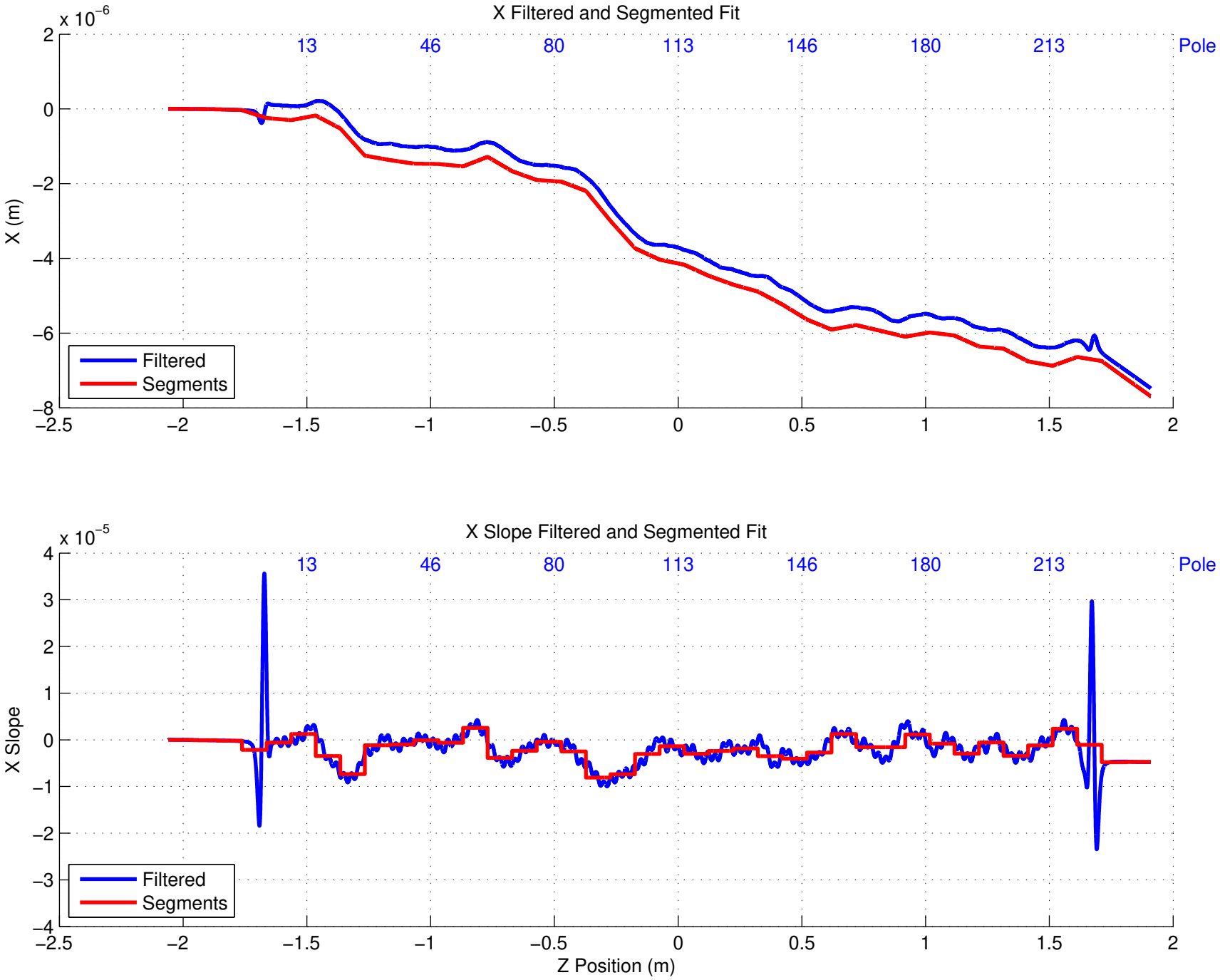

Set Gap, Gap Change Required To Set The Field, No Ends
x 10^-4
Gap Change (m)
13
46
80
113
146
180
213
Pole
Set Gap, Required Shim X Motion, No Ends
Shim X Motion (m)
Z Position (m)

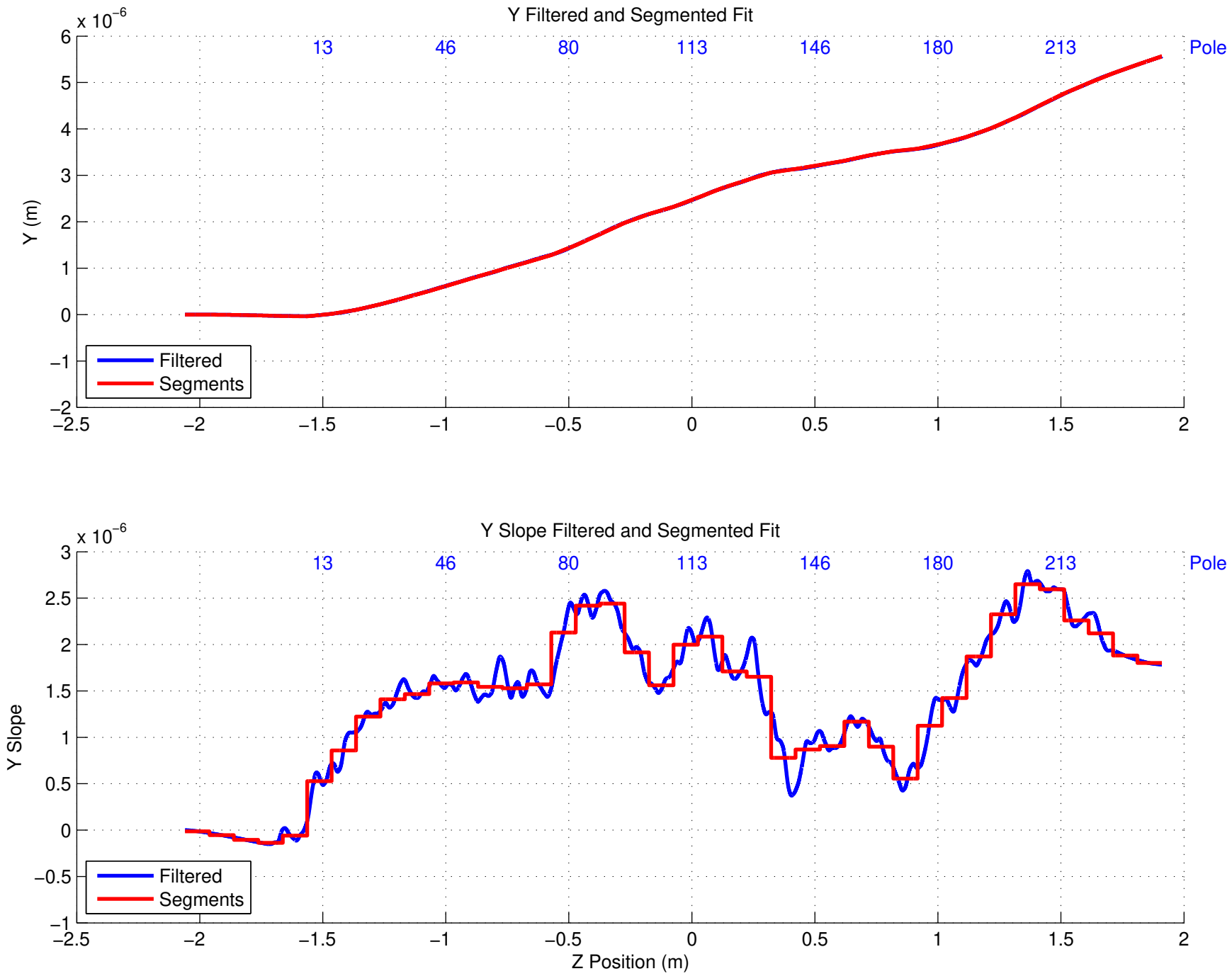

Set Gap, Required Phase Change And Fit, No Ends
13
46
80
113
146
180
213
Pole
Phase Change (rad)
0
−0.5
−1
−1.5
−2
Measured
Fit
−2
−1.5
−1
−0.5
0
0.5
1
1.5
2
Set Gap, Required Phase Change Slope From Fit, No Ends
Phase Change Slope (rad / m)
2
1
0
−1
−2
−3
Z Position (m)

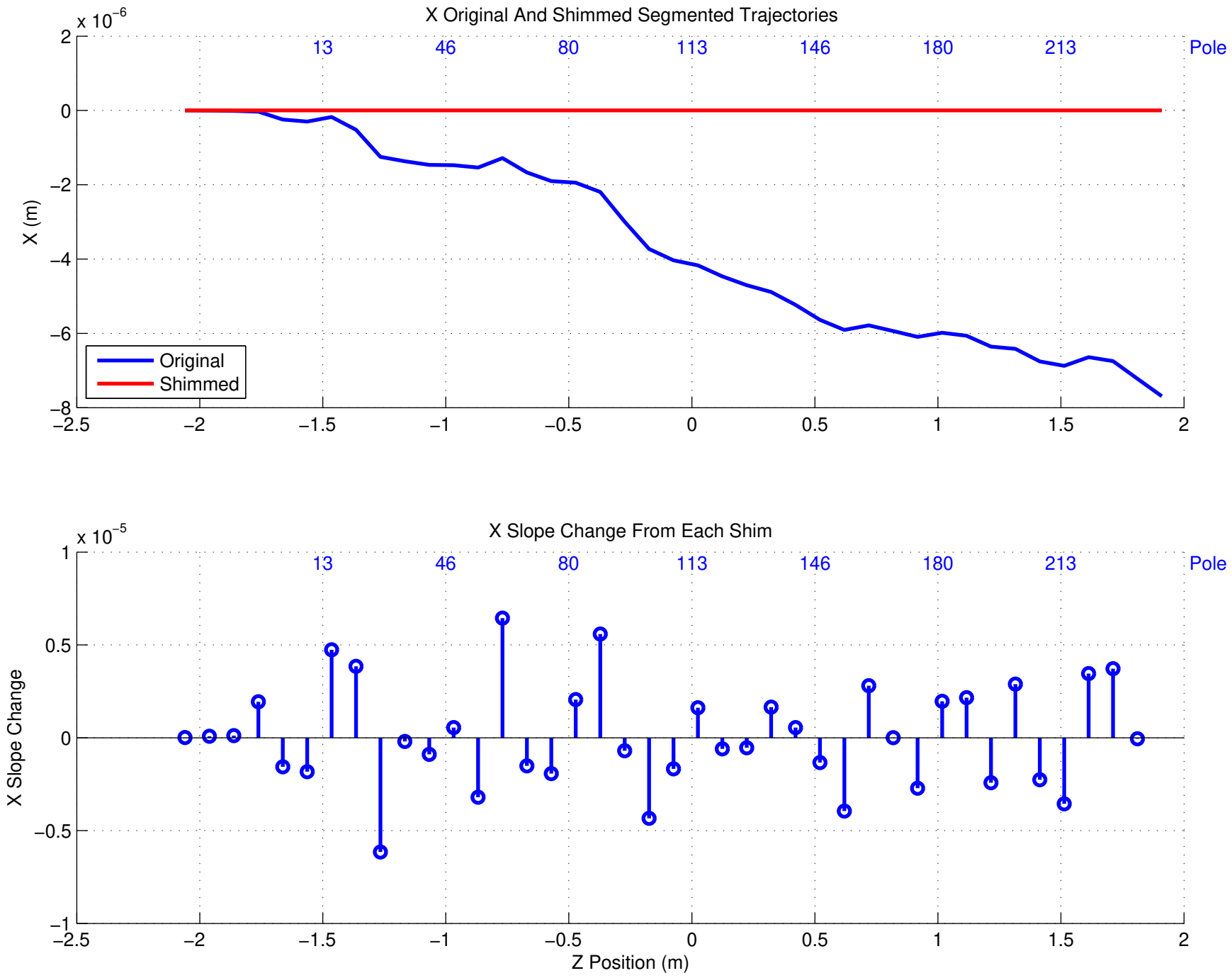

Set Gap, Gap Change Required To Correct The Phase Error, No Ends
x 10^-5
Gap Change (m)
13
46
80
113
146
180
213
Pole
Set Gap, Required Shim X Motion, No Ends
Shim X Motion (m)
Z Position (m)

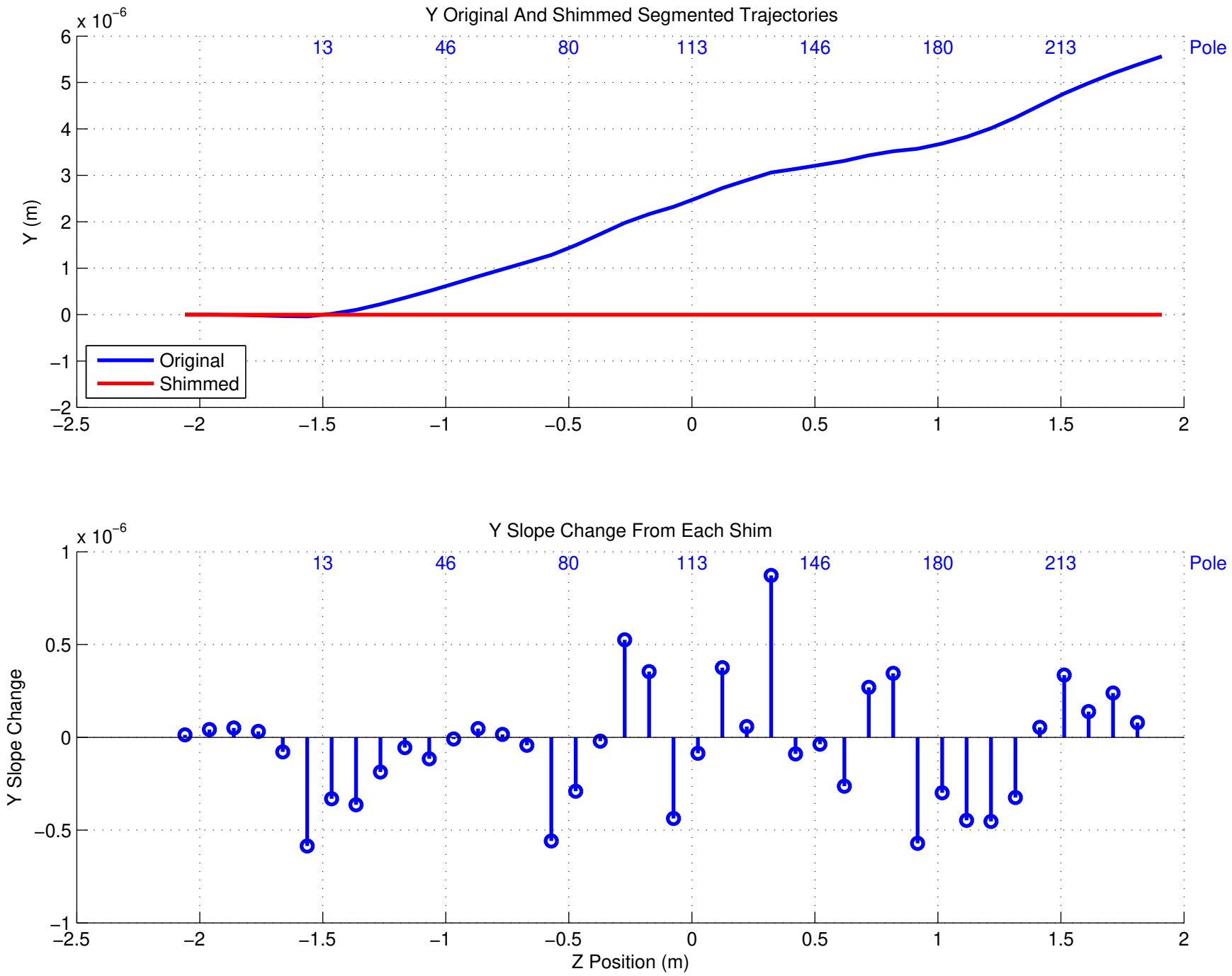

X Trajectory and Segmented Fit
x 10^-6
13
46
80
113
146
180
213
Pole
1
0
−1
−2
−3
−4
−5
−6
−7
−8
X (m)
−2.5
−2
−1.5
−1
−0.5
0
0.5
1
1.5
2
Z Position (m)
Trajectory
Filtered
Segments

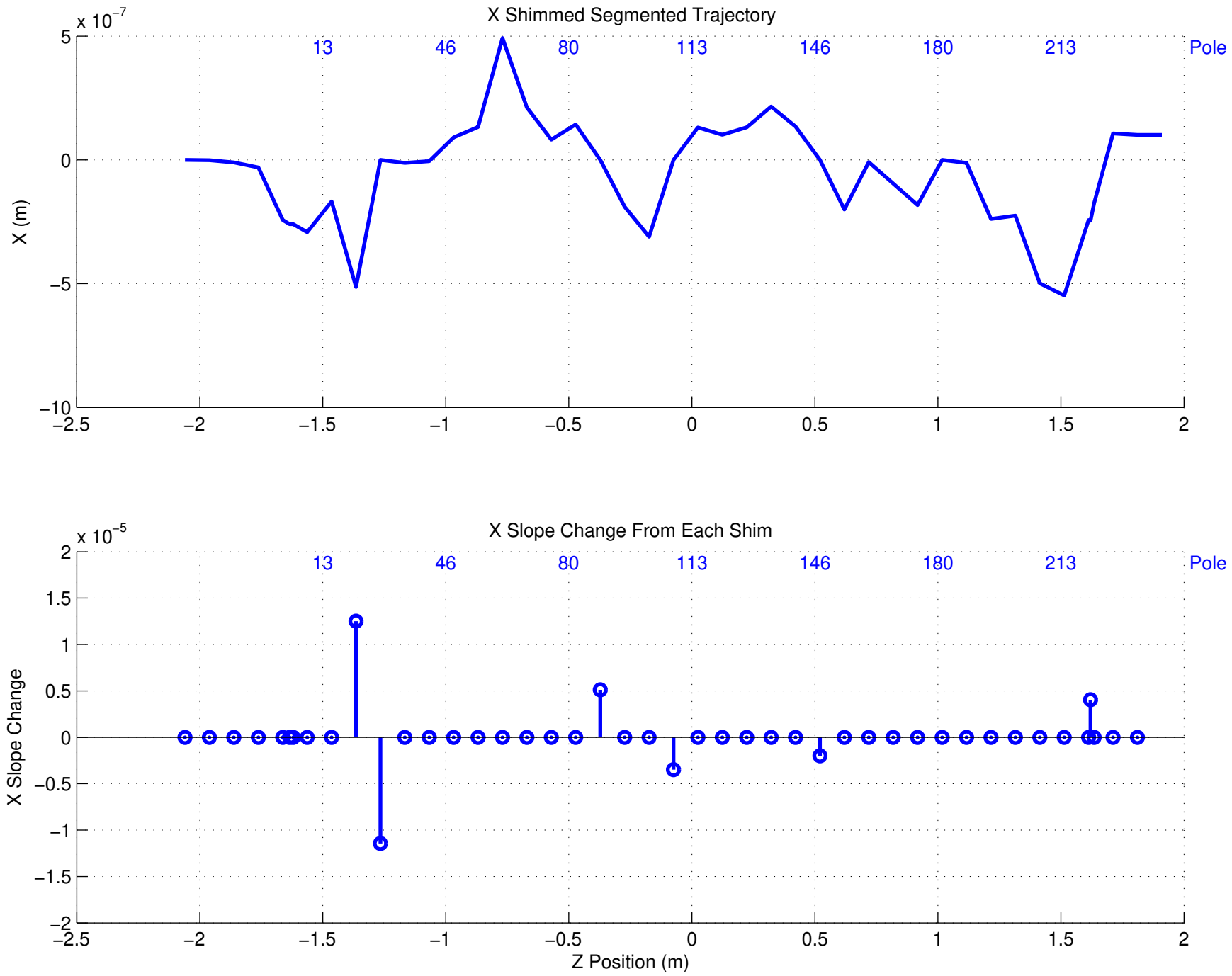

Y Trajectory and Segmented Fit
x 10^-6
6
5
4
3
2
1
0
−1
13
46
80
113
146
180
213
Pole
Y (m)
−2.5
−2
−1.5
−1
−0.5
0
0.5
1
1.5
2
Z Position (m)
Trajectory
Filtered
Segments

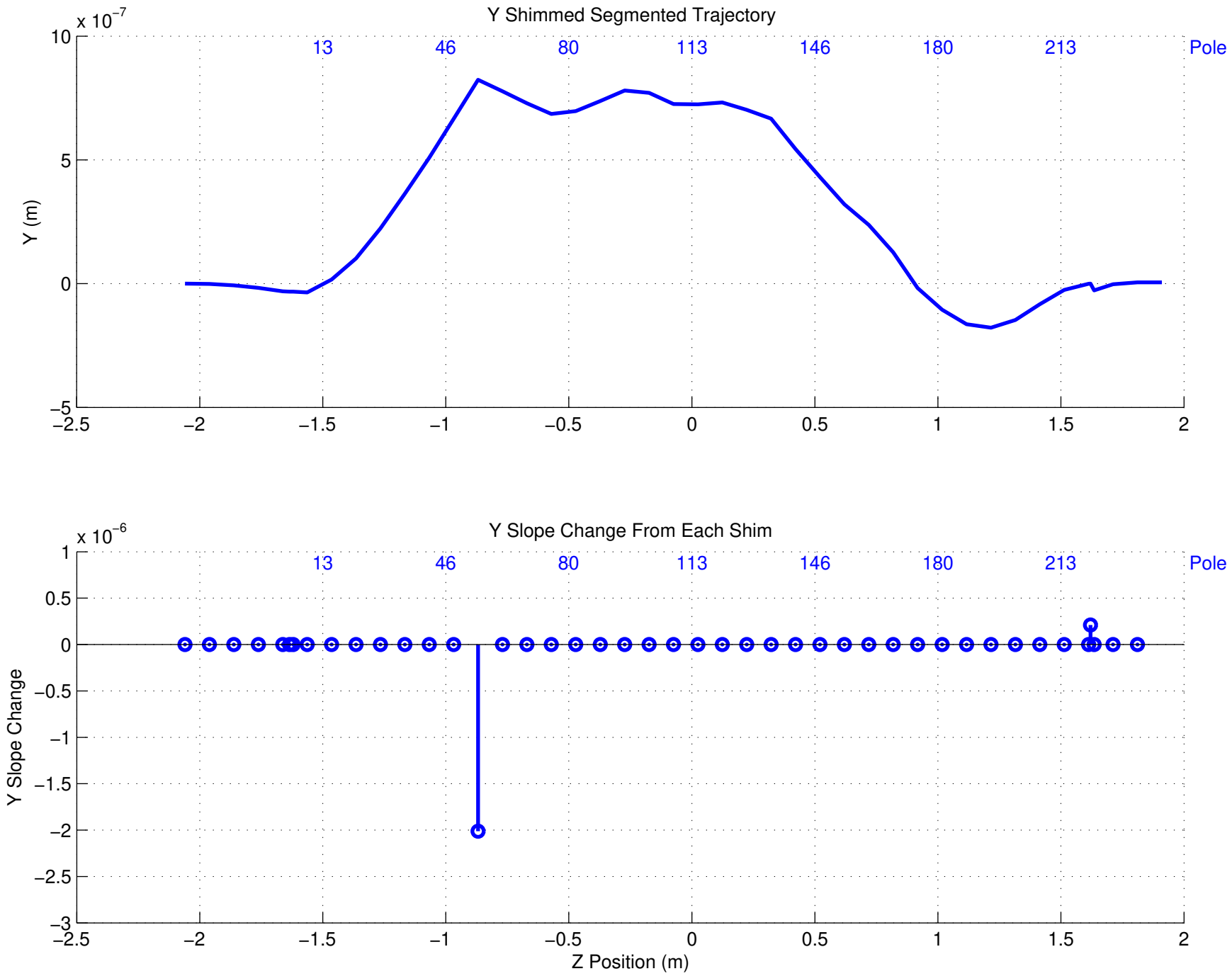

X Filtered and Segmented Fit
x 10^-6
X (m)
13
46
80
113
146
180
213
Pole
Filtered
Segments
X Slope Filtered and Segmented Fit
x 10^-5
X Slope
Z Position (m)

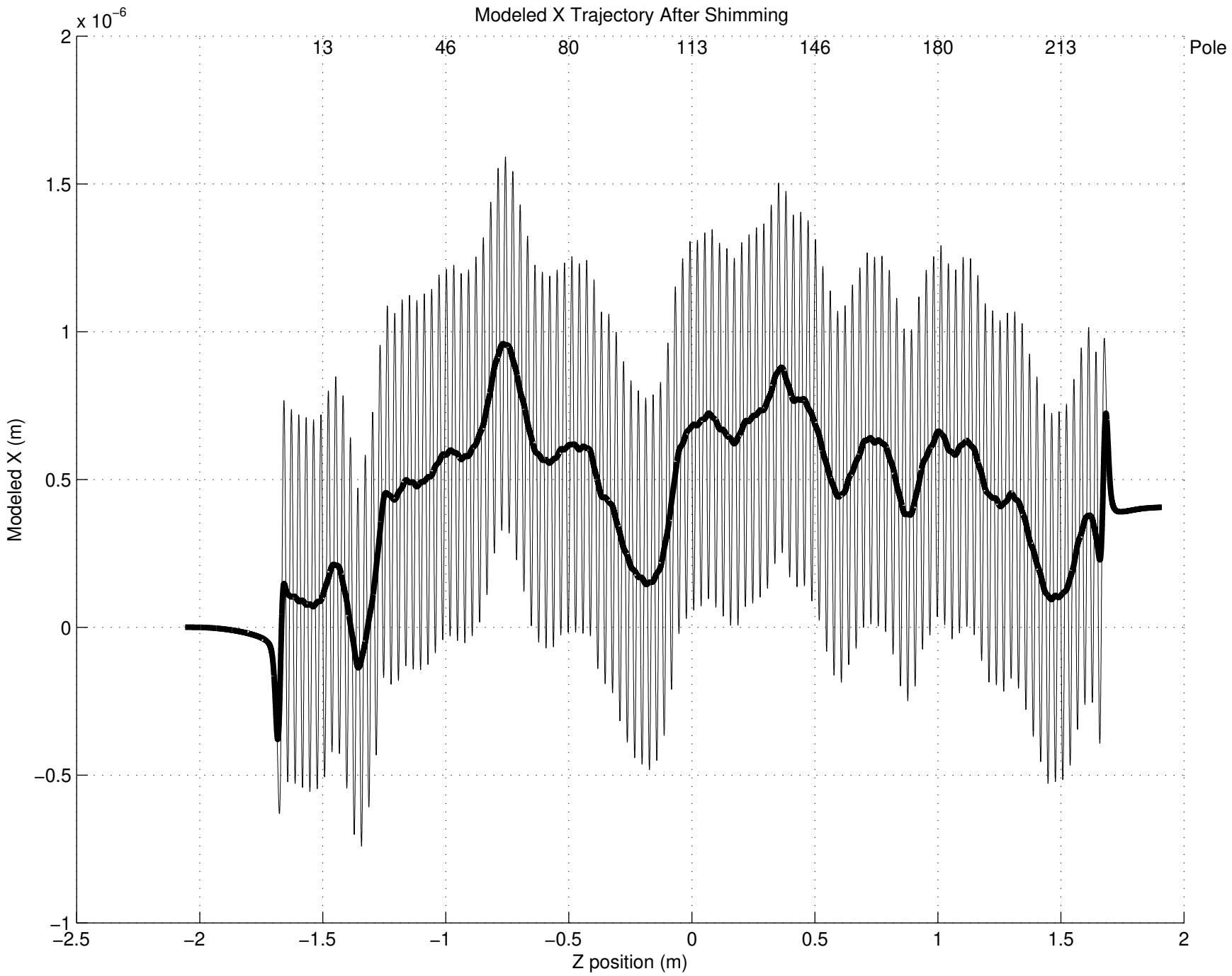

Y Filtered and Segmented Fit
x 10^-6
Y (m)
13
46
80
113
146
180
213
Pole
Filtered
Segments
Y Slope Filtered and Segmented Fit
x 10^-6
Y Slope
Z Position (m)

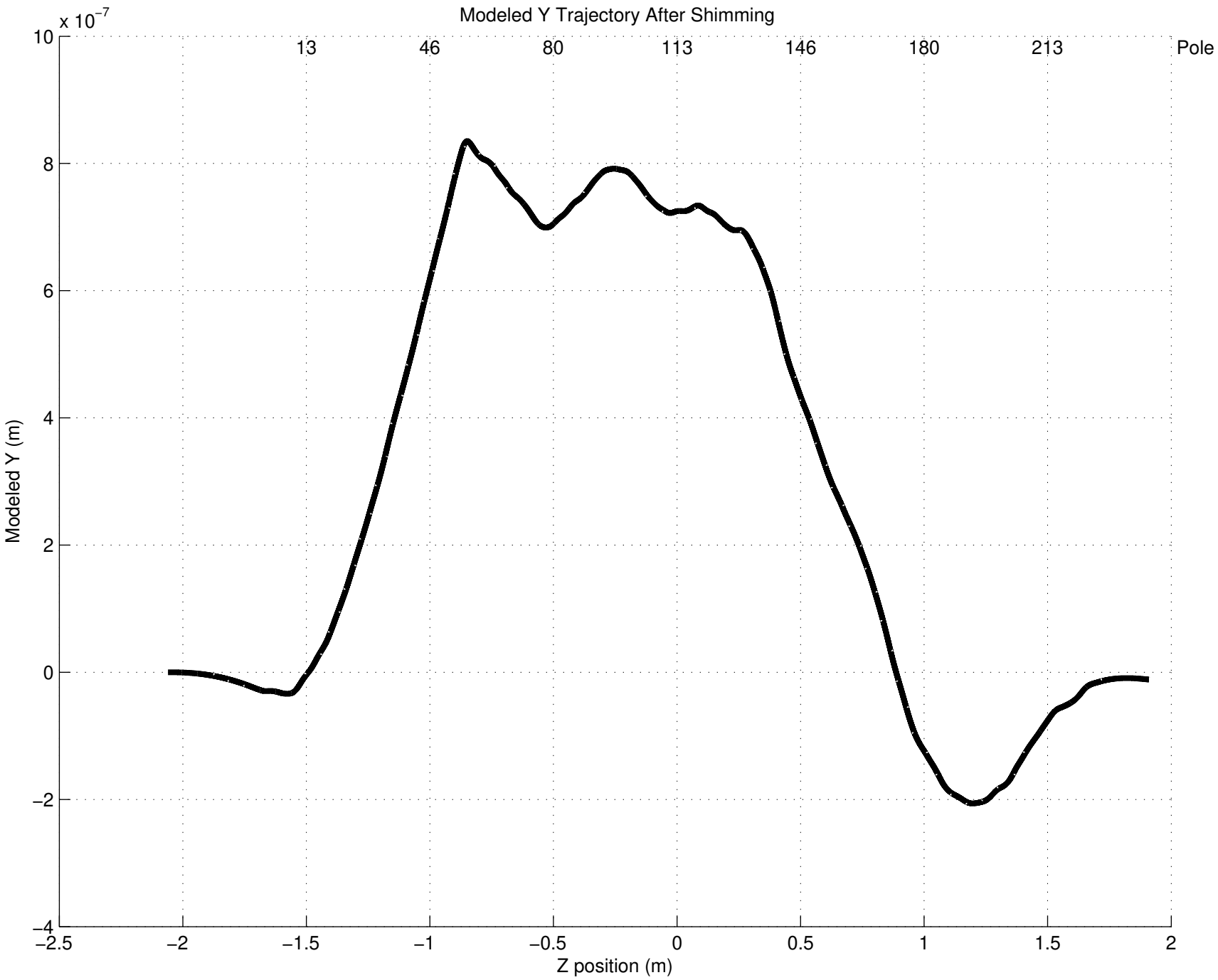

X Original And Shimmed Segmented Trajectories
x 10^-6
13
46
80
113
146
180
213
Pole
X (m)
Original
Shimmed
X Slope Change From Each Shim
x 10^-5
X Slope Change
Z Position (m)

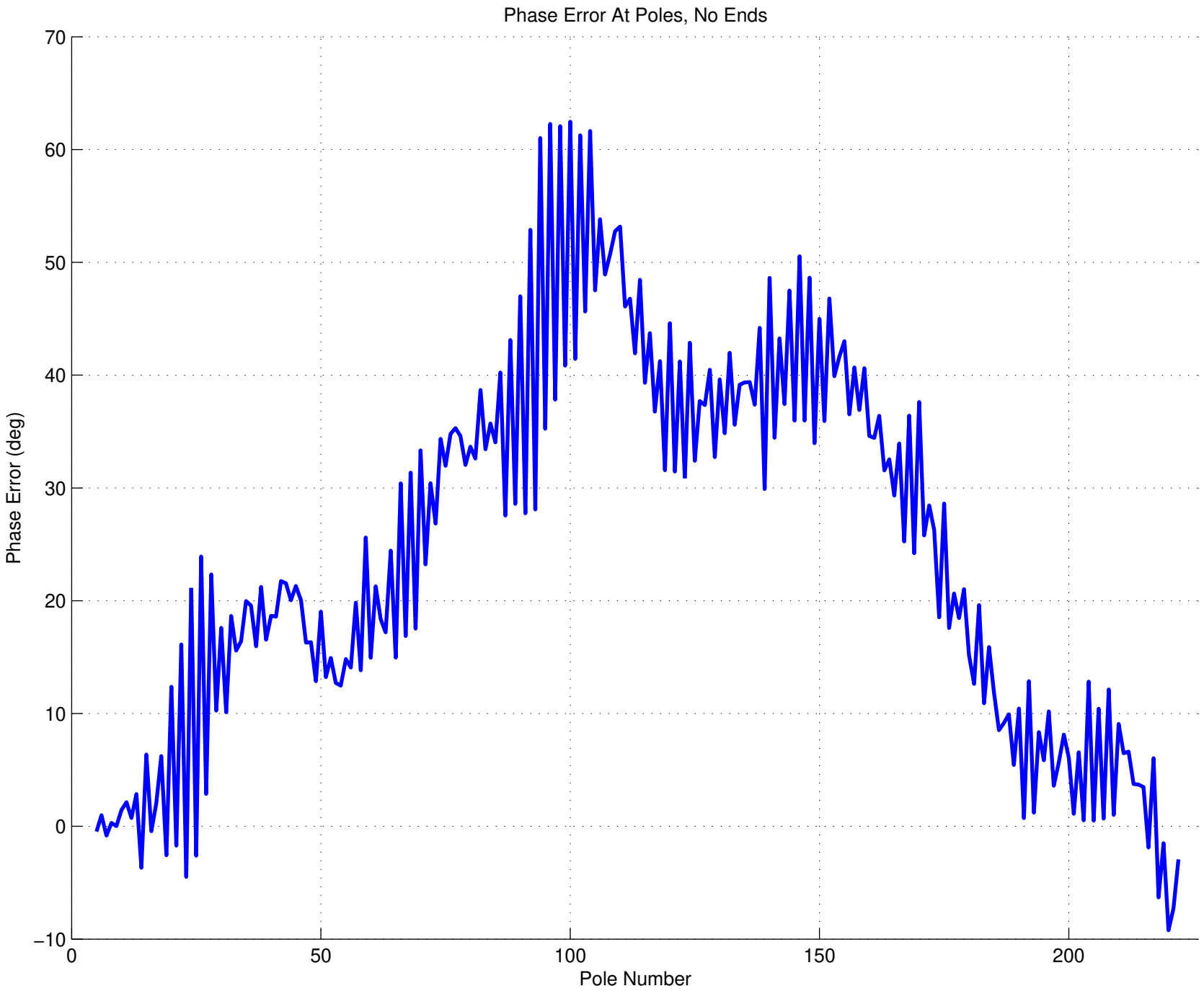

Y Original And Shimmed Segmented Trajectories
x 10^-6
13
46
80
113
146
180
213
Pole
Y (m)
Original
Shimmed
Y Slope Change From Each Shim
Y Slope Change
Z Position (m)

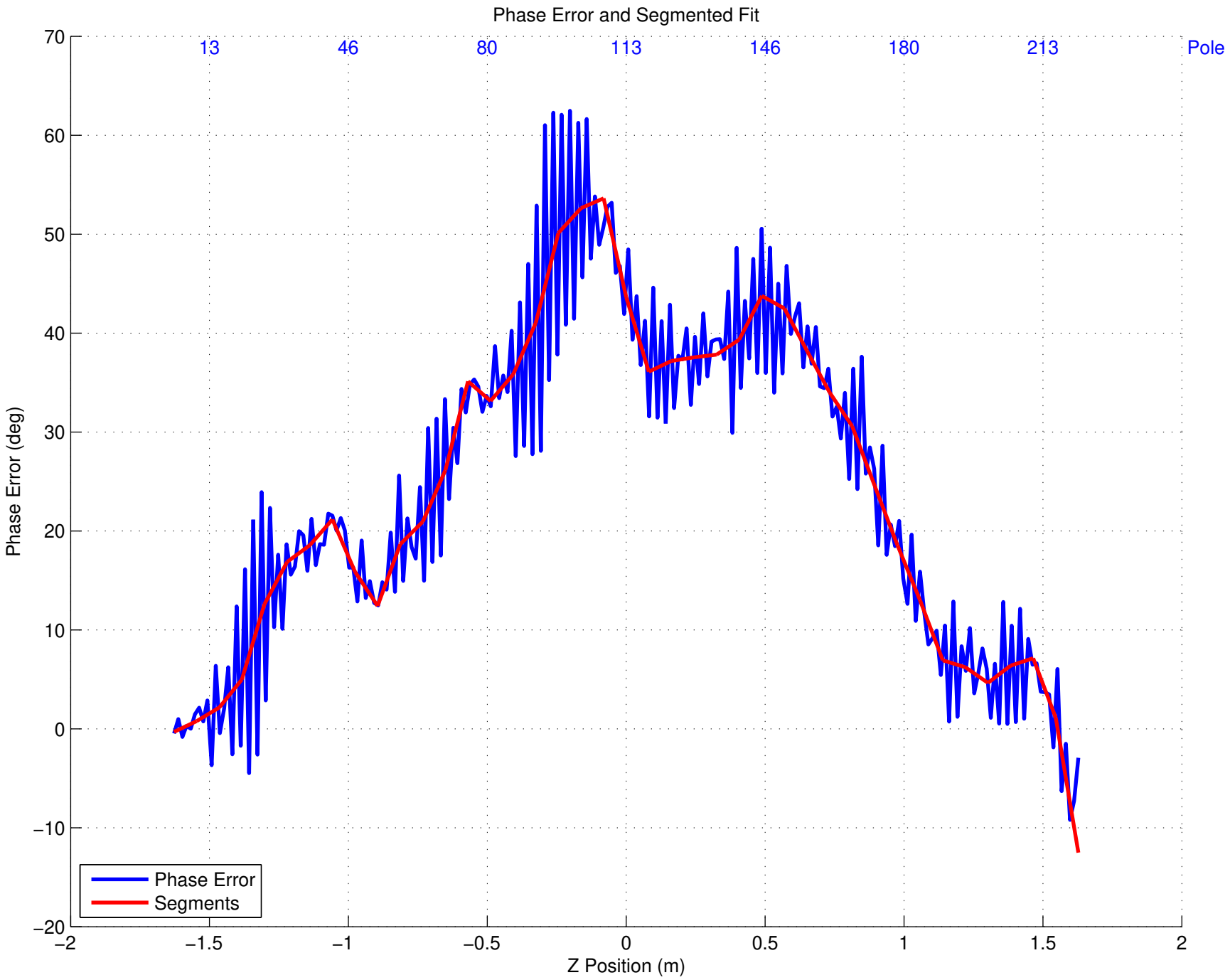

X Shimmed Segmented Trajectory
x 10^-7
X (m)
13
46
80
113
146
180
213
Pole
X Slope Change From Each Shim
x 10^-5
X Slope Change
Z Position (m)

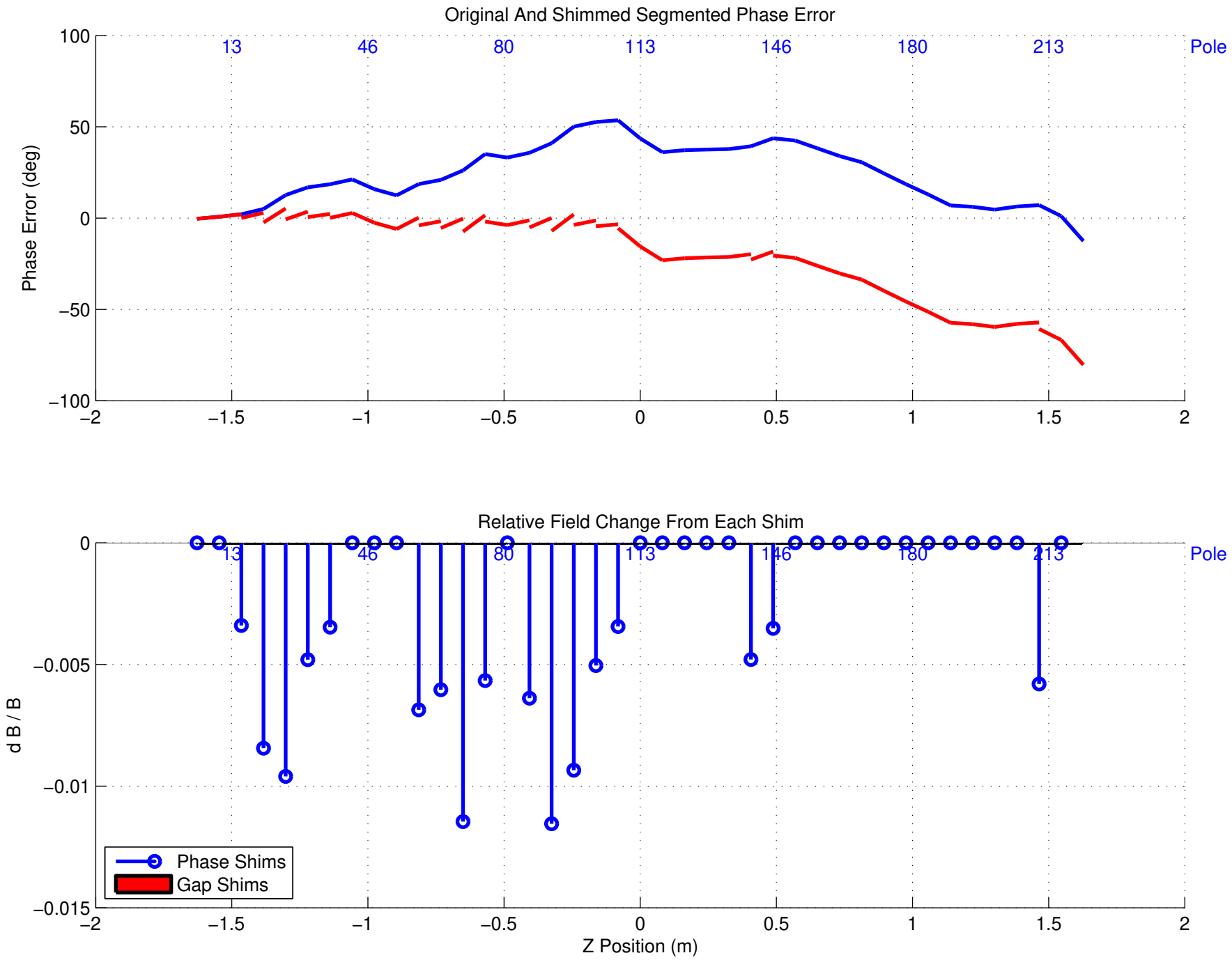

Y Shimmed Segmented Trajectory
x 10^-7
Y (m)
13
46
80
113
146
180
213
Pole
Y Slope Change From Each Shim
x 10^-6
Y Slope Change
Z Position (m)

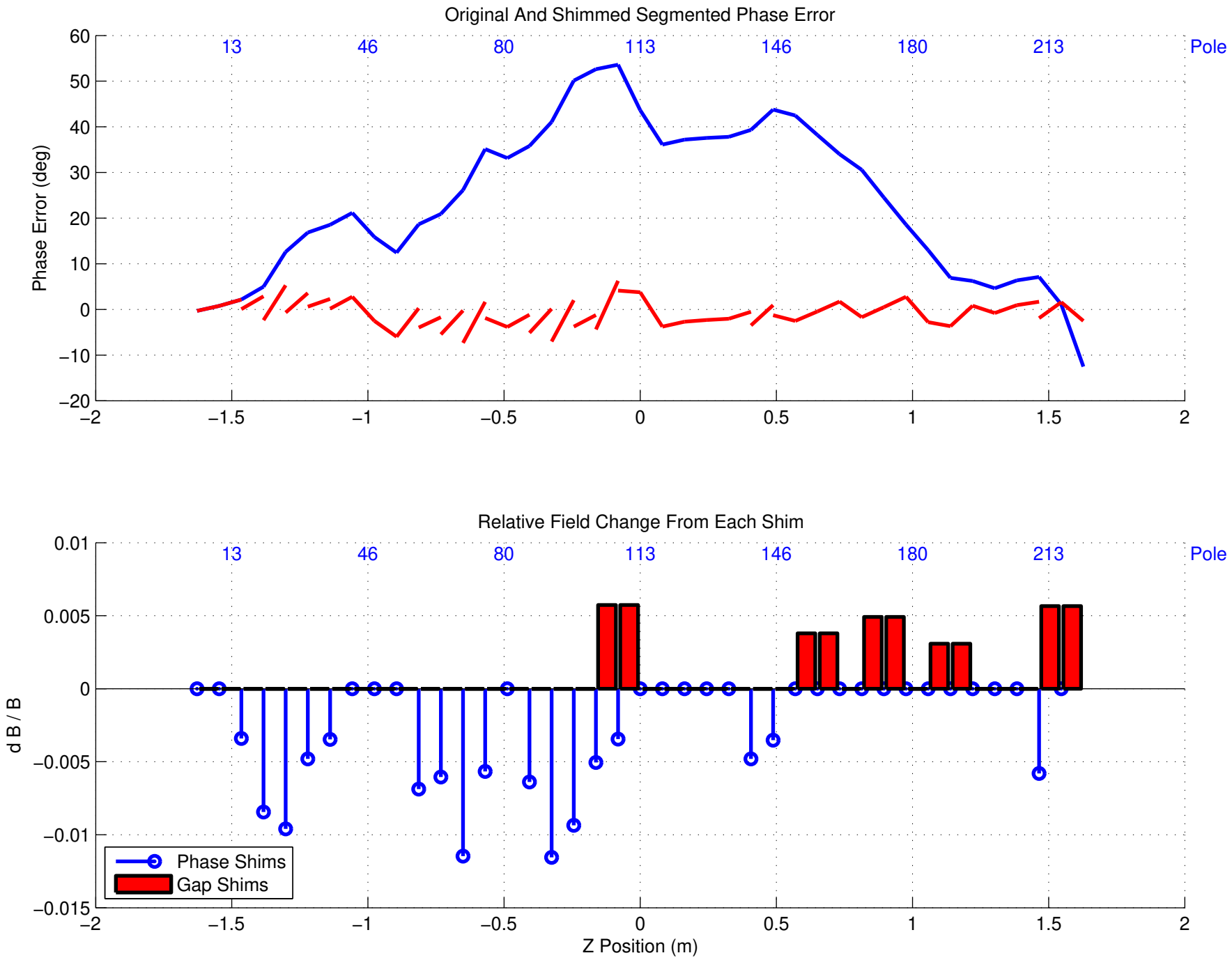

Modeled X Trajectory After Shimming
x 10^-6
2
1.5
1
0.5
0
−0.5
−1
13
46
80
113
146
180
213
Pole
Modeled X (m)
−2.5
−2
−1.5
−1
−0.5
0
0.5
1
1.5
2
Z position (m)

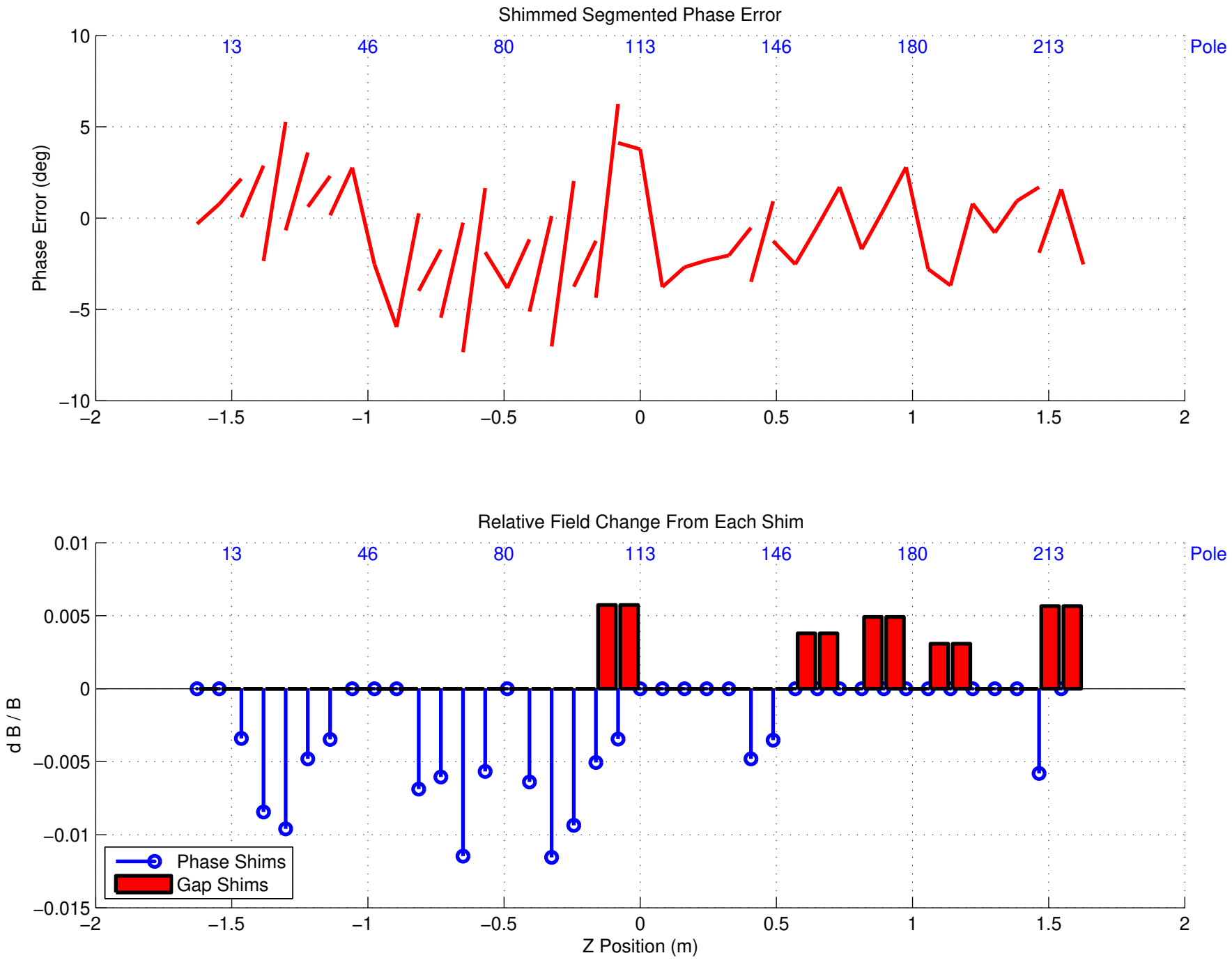

Modeled Y Trajectory After Shimming
x 10^-7
13
46
80
113
146
180
213
Pole
10
8
6
4
2
0
−2
−4
Modeled Y (m)
−2.5
−2
−1.5
−1
−0.5
0
0.5
1
1.5
2
Z position (m)

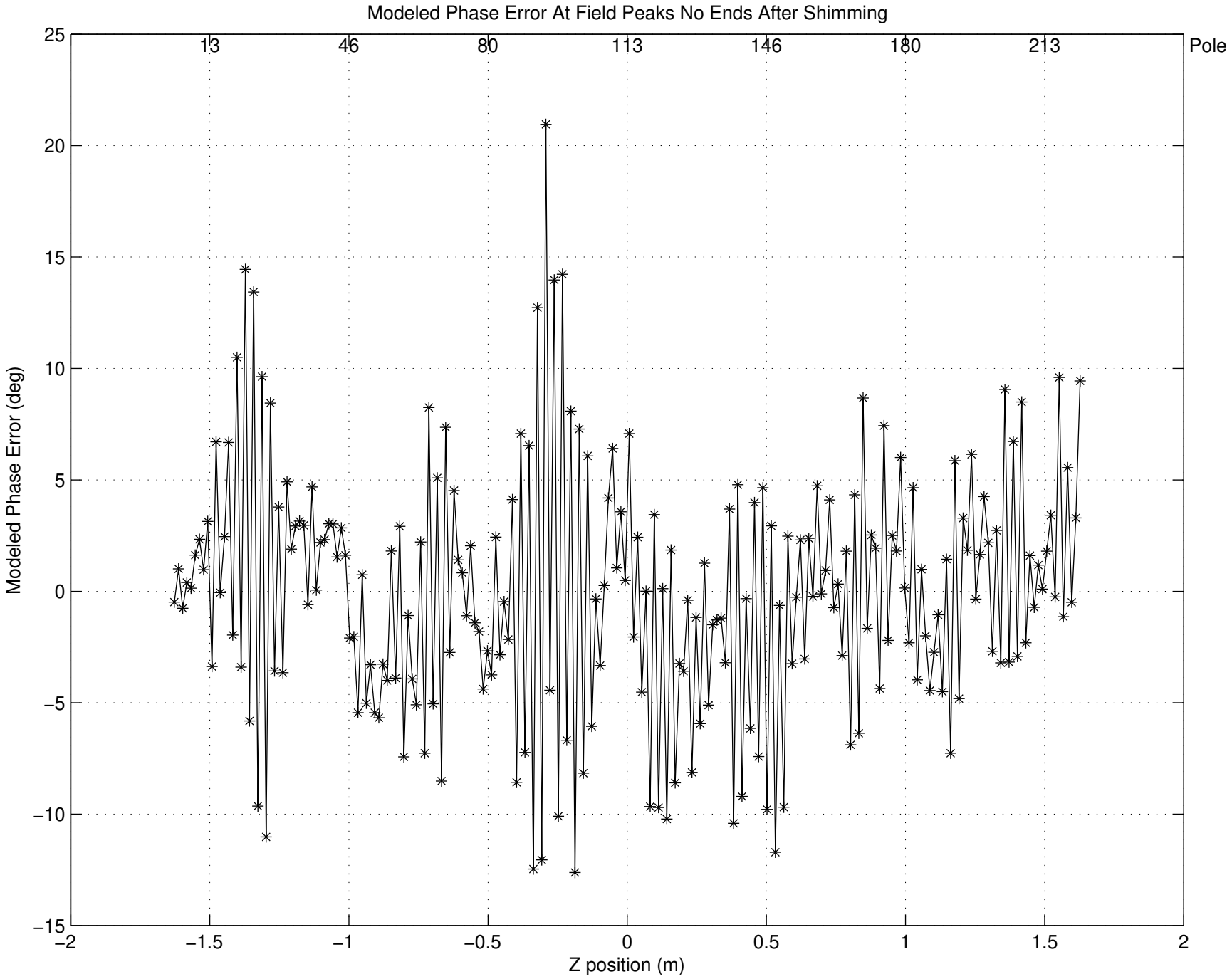

Phase Error At Poles, No Ends
Phase Error (deg)
Pole Number
70
60
50
40
30
20
10
0
−10
0
50
100
150
200


Phase Error and Segmented Fit
13
46
80
113
146
180
213
Pole
70
60
50
40
30
20
10
0
−10
−20
Phase Error (deg)
−2
−1.5
−1
−0.5
0
0.5
1
1.5
2
Z Position (m)
Phase Error
Segments


Original And Shimmed Segmented Phase Error
Phase Error (deg)
100
50
0
−50
−100
13
46
80
113
146
180
213
Pole
−2
−1.5
−1
−0.5
0
0.5
1
1.5
2
Relative Field Change From Each Shim
d B / B
0
−0.005
−0.01
−0.015
Phase Shims
Gap Shims
Z Position (m)


Original And Shimmed Segmented Phase Error
Phase Error (deg)
13
46
80
113
146
180
213
Pole
60
50
40
30
20
10
0
−10
−20
−2
−1.5
−1
−0.5
0
0.5
1
1.5
2
Relative Field Change From Each Shim
d B / B
0.01
0.005
0
−0.005
−0.01
−0.015
Phase Shims
Gap Shims
Z Position (m)


Shimmed Segmented Phase Error
Phase Error (deg)
10
5
0
−5
−10
13
46
80
113
146
180
213
Pole
−2
−1.5
−1
−0.5
0
0.5
1
1.5
2
Relative Field Change From Each Shim
d B / B
0.01
0.005
0
−0.005
−0.01
−0.015
Phase Shims
Gap Shims
Z Position (m)



Phase Error: Ave = 0.000000 deg, RMS = 5.524446 deg