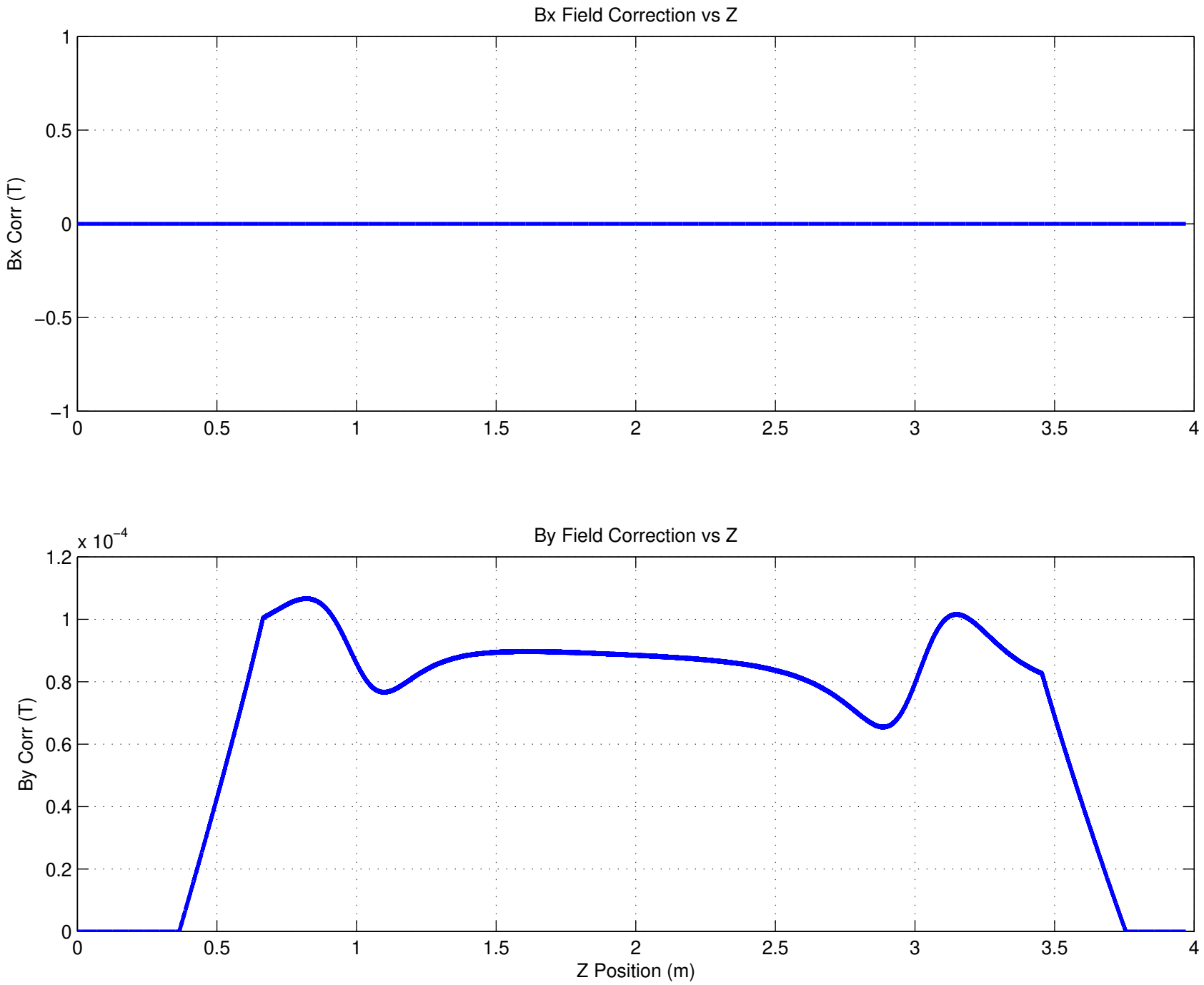
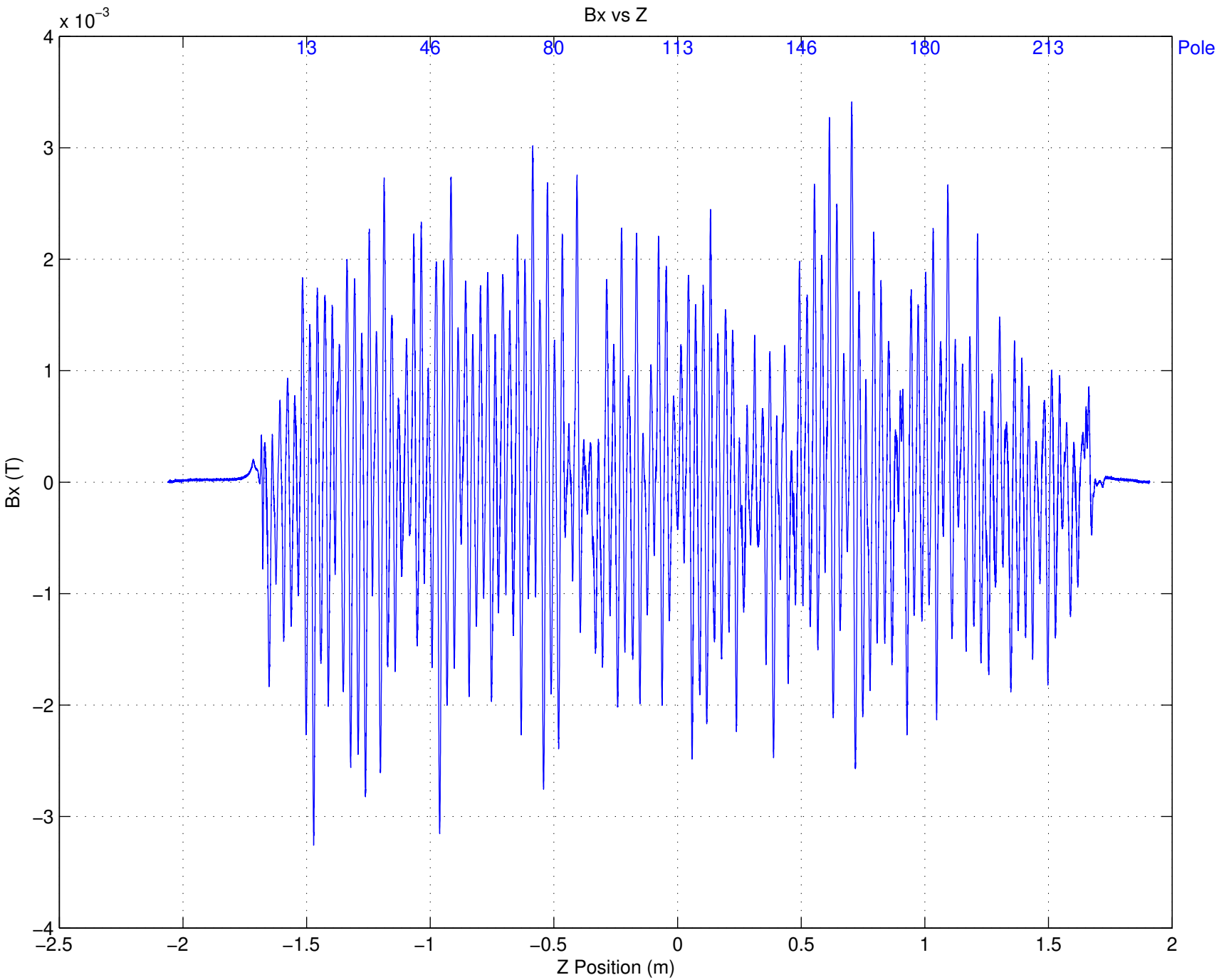
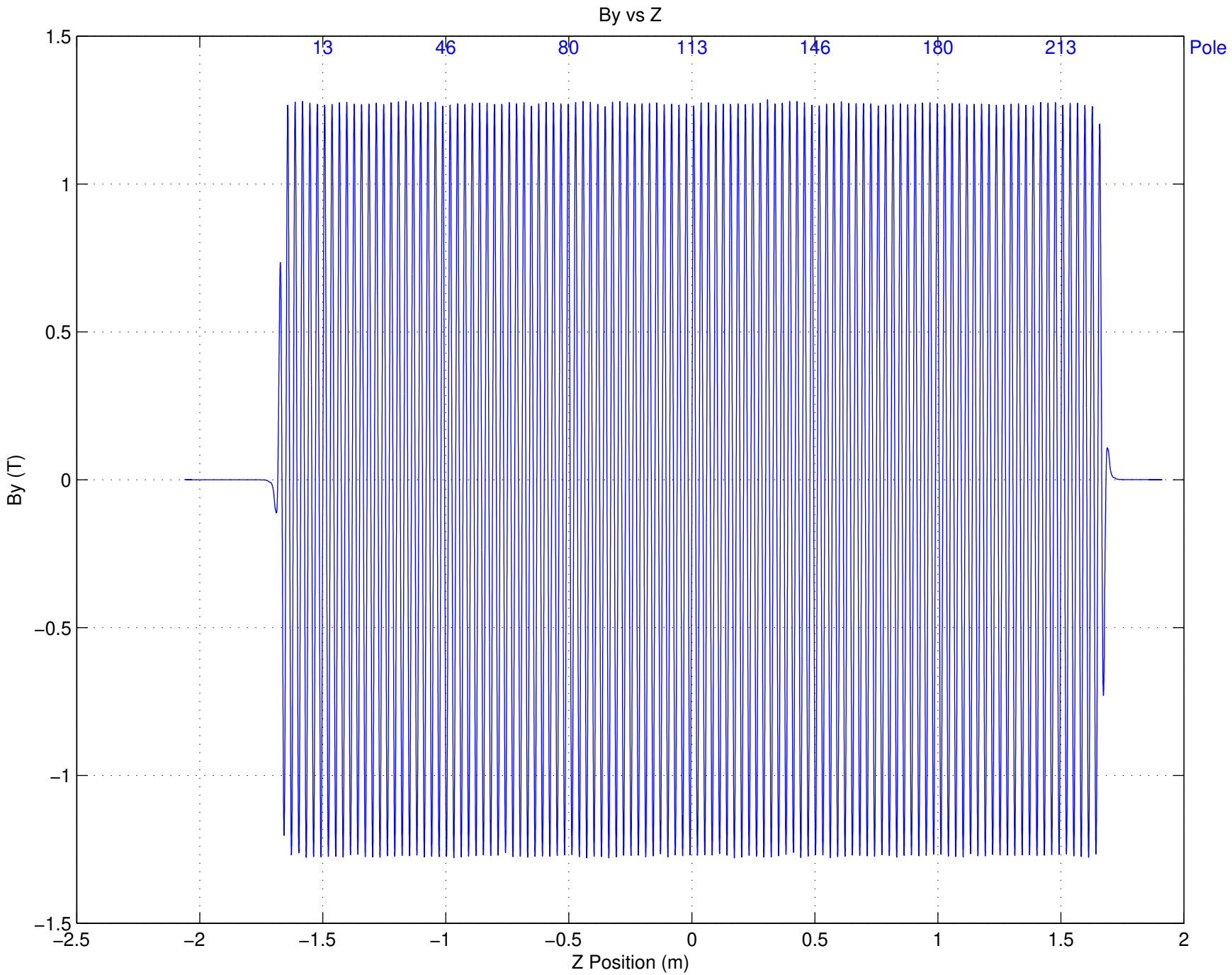
SLAC Magnetic Measurements

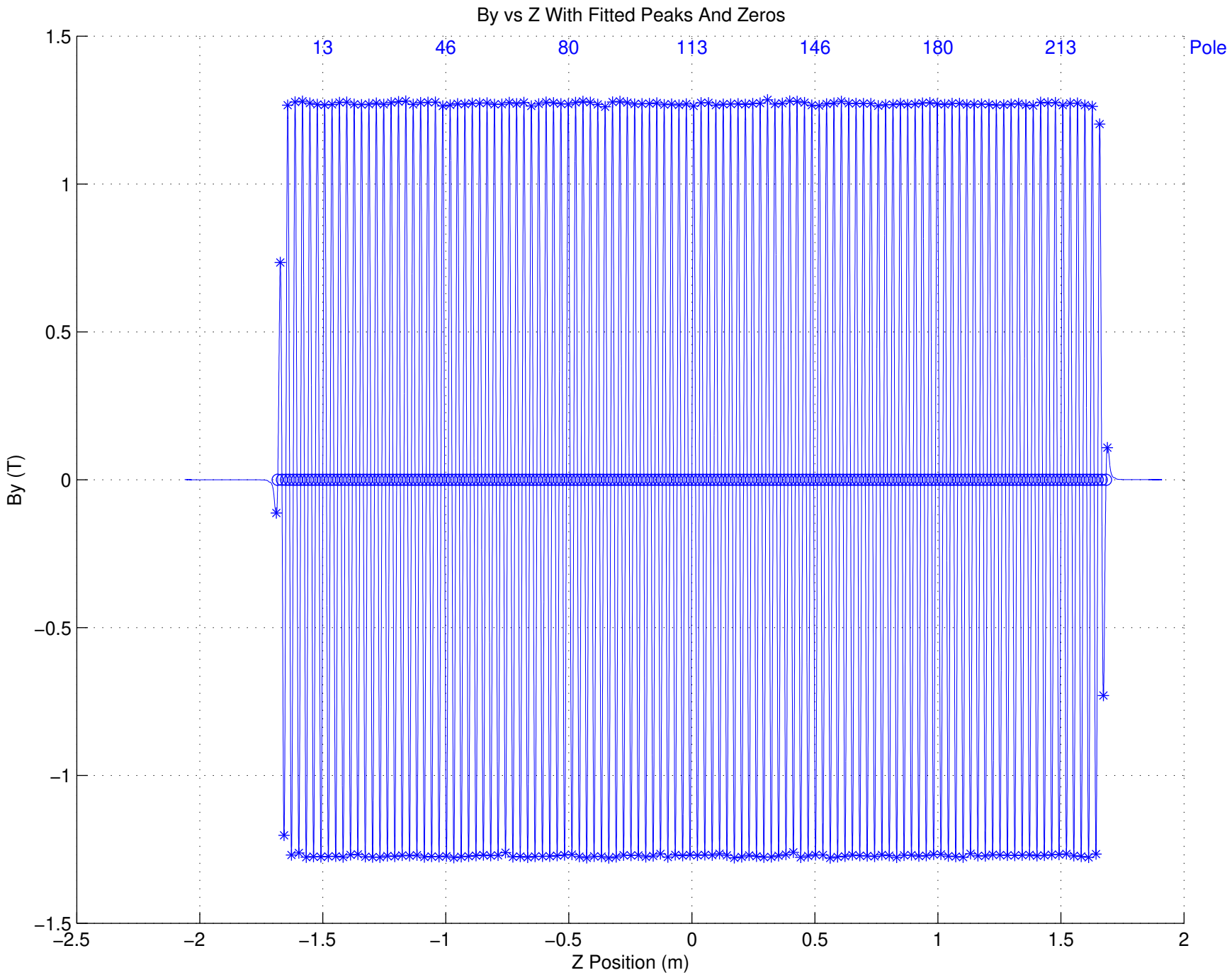
Planar Insertion Device Analysis

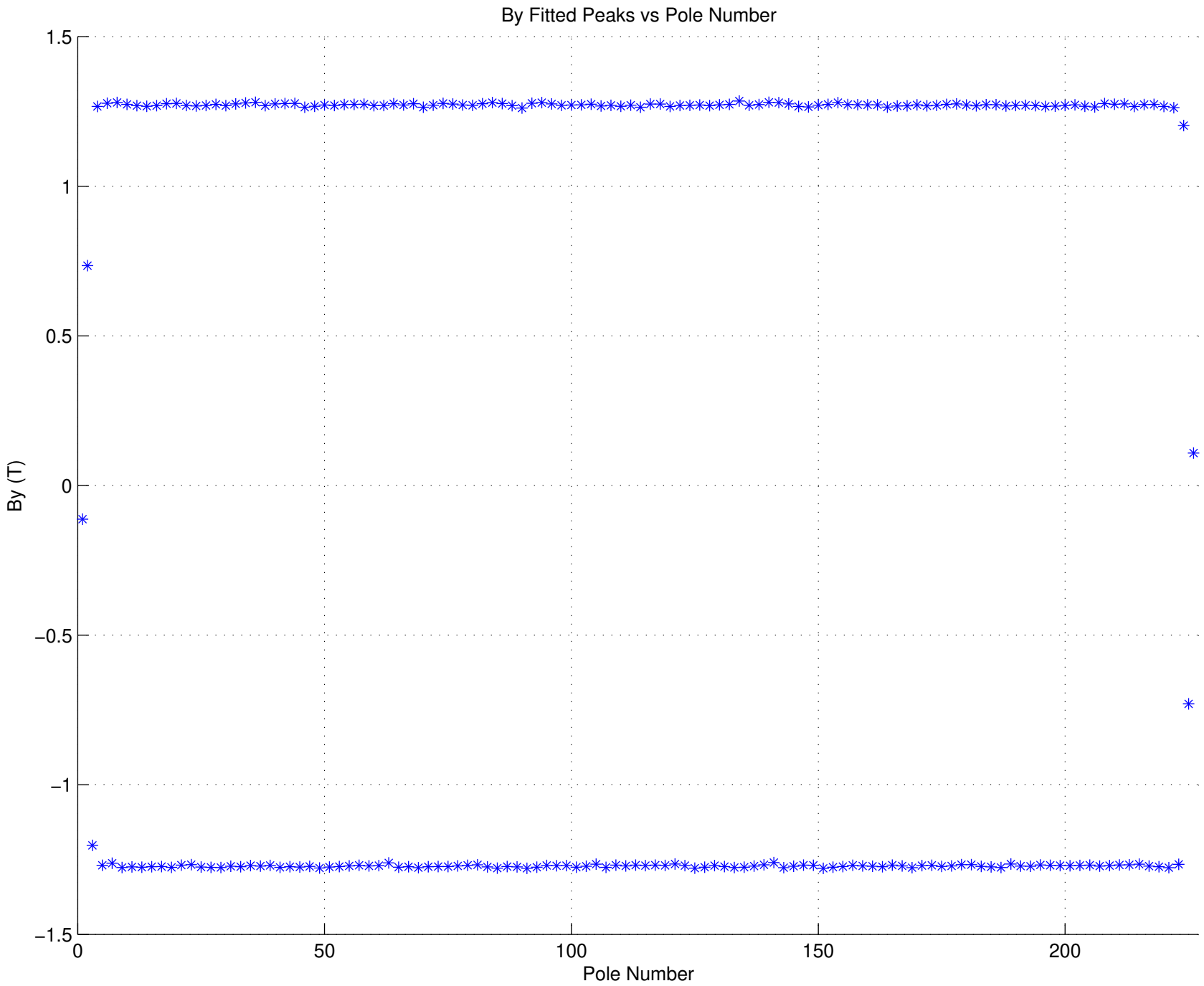
Parameters:
INPUT−FILE−DIR =S:\Magdata\Lcls\Undulator\L143−112000−15\DATASET0001\Rough Tuning\Z Scans\Run 034\
INPUT−FILE−NAME =x+00000−y+000−bscanz.dat
INPUT−FILE−TYPE =ZVXYBXYH
CORR−REQUIRED =1
GAMMA =26654.56
NOM−LAMBDA−U =0.03
NOM−K−VALUE =3.4917
NOM−LAMBDA−R =1.4982e−010
NUM−POLES =226
NUM−END−POLES =4
CELL−LENGTH =3.656

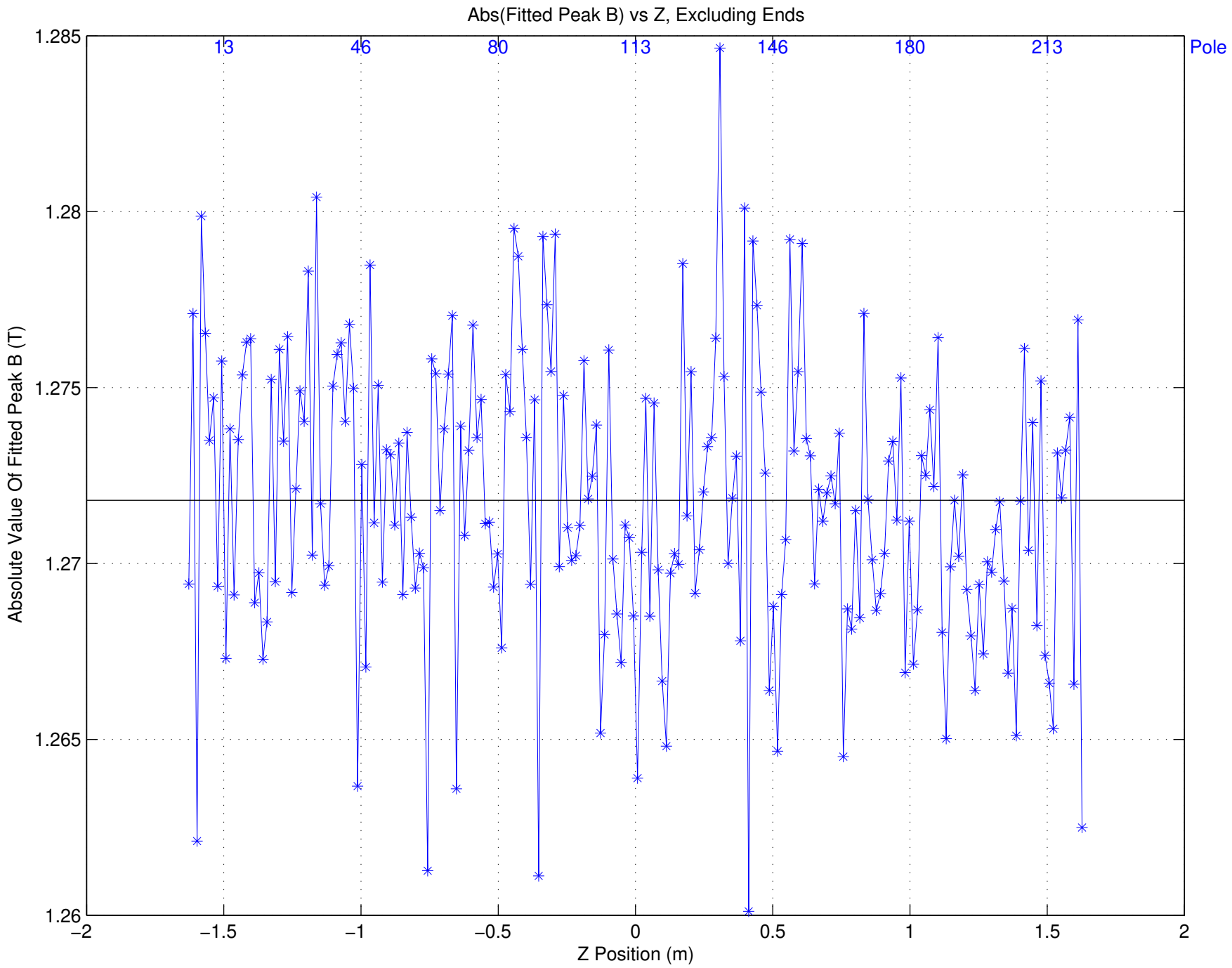

Bx Field Correction vs Z
Bx Corr (T)
1
0.5
0
−0.5
−1
0
0.5
1
1.5
2
2.5
3
3.5
4
By Field Correction vs Z
x 10^−4
By Corr (T)
1.2
1
0.8
0.6
0.4
0.2
0
Z Position (m)


Bx vs Z
x 10^-3
13
46
80
113
146
180
213
Pole
4
3
2
1
0
−1
−2
−3
−4
Bx (T)
−2.5
−2
−1.5
−1
−0.5
0
0.5
1
1.5
2
Z Position (m)

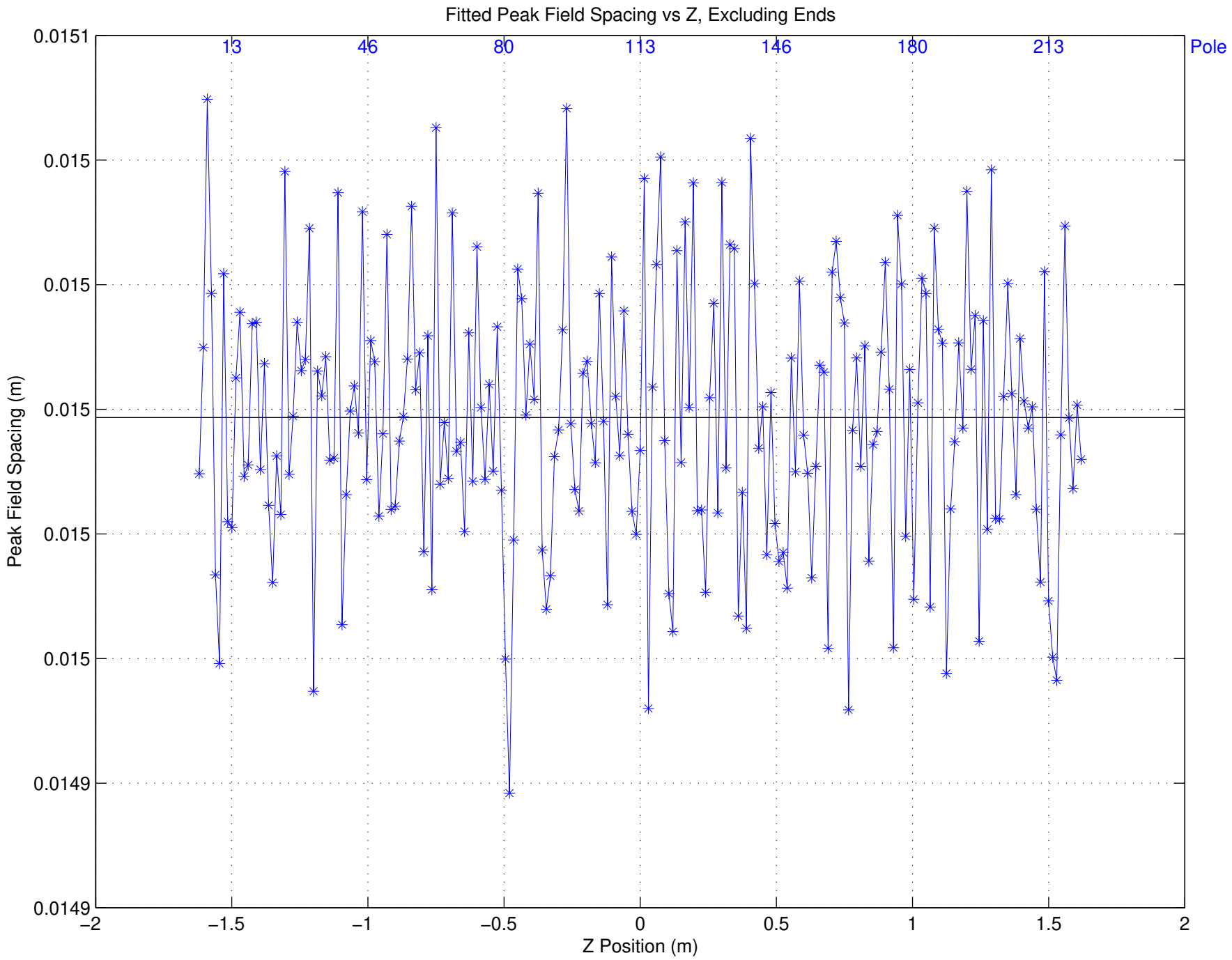

By vs Z
13
46
80
113
146
180
213
Pole
1.5
1
0.5
0
−0.5
−1
−1.5
By (T)
−2.5
−2
−1.5
−1
−0.5
0
0.5
1
1.5
2
Z Position (m)


By vs Z With Fitted Peaks And Zeros
13
46
80
113
146
180
213
Pole
1.5
1
0.5
0
−0.5
−1
−1.5
By (T)
−2.5
−2
−1.5
−1
−0.5
0
0.5
1
1.5
2
Z Position (m)

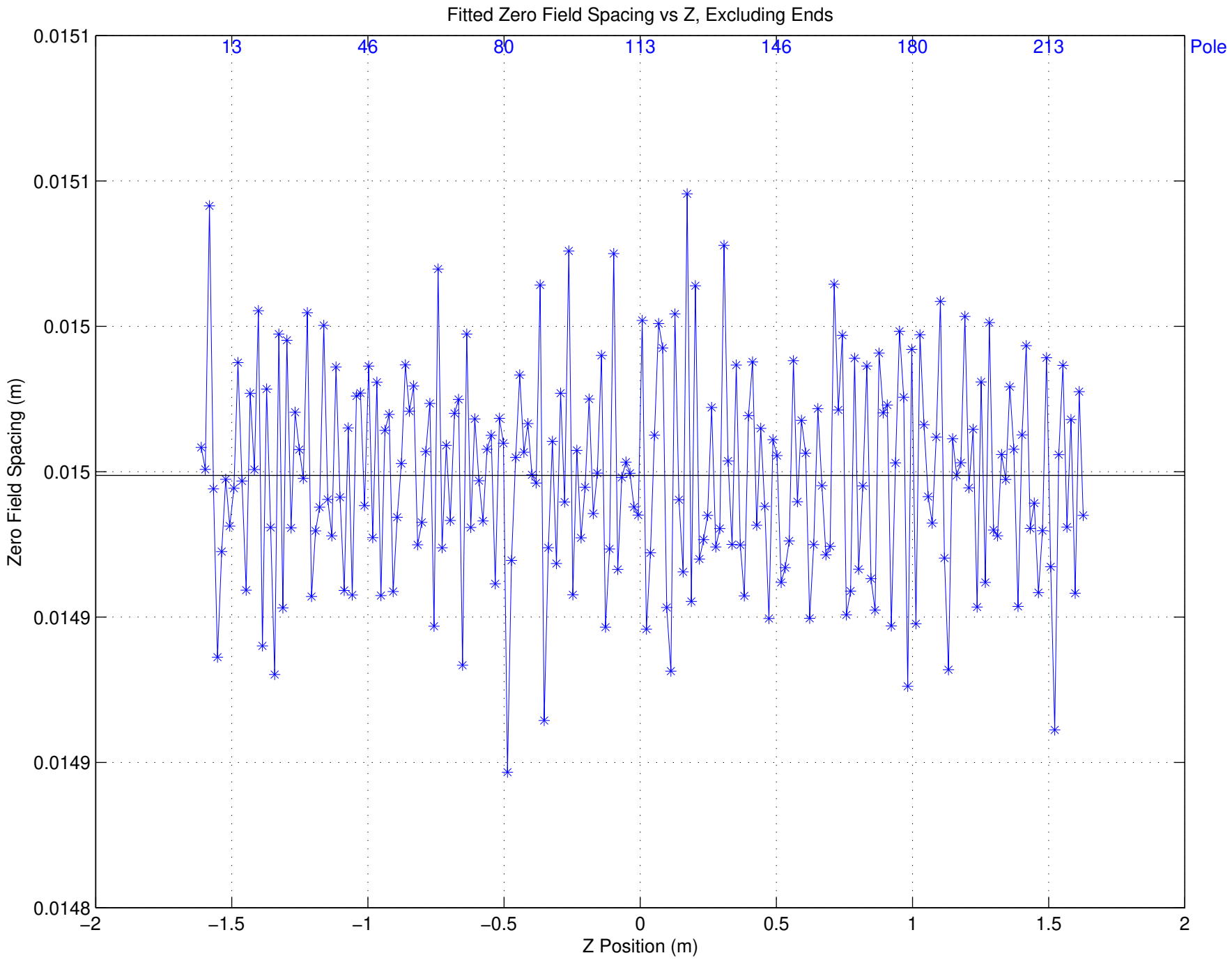

By Fitted Peaks vs Pole Number
By (T)
Pole Number
1.5
1
0.5
0
−0.5
−1
−1.5
0
50
100
150
200



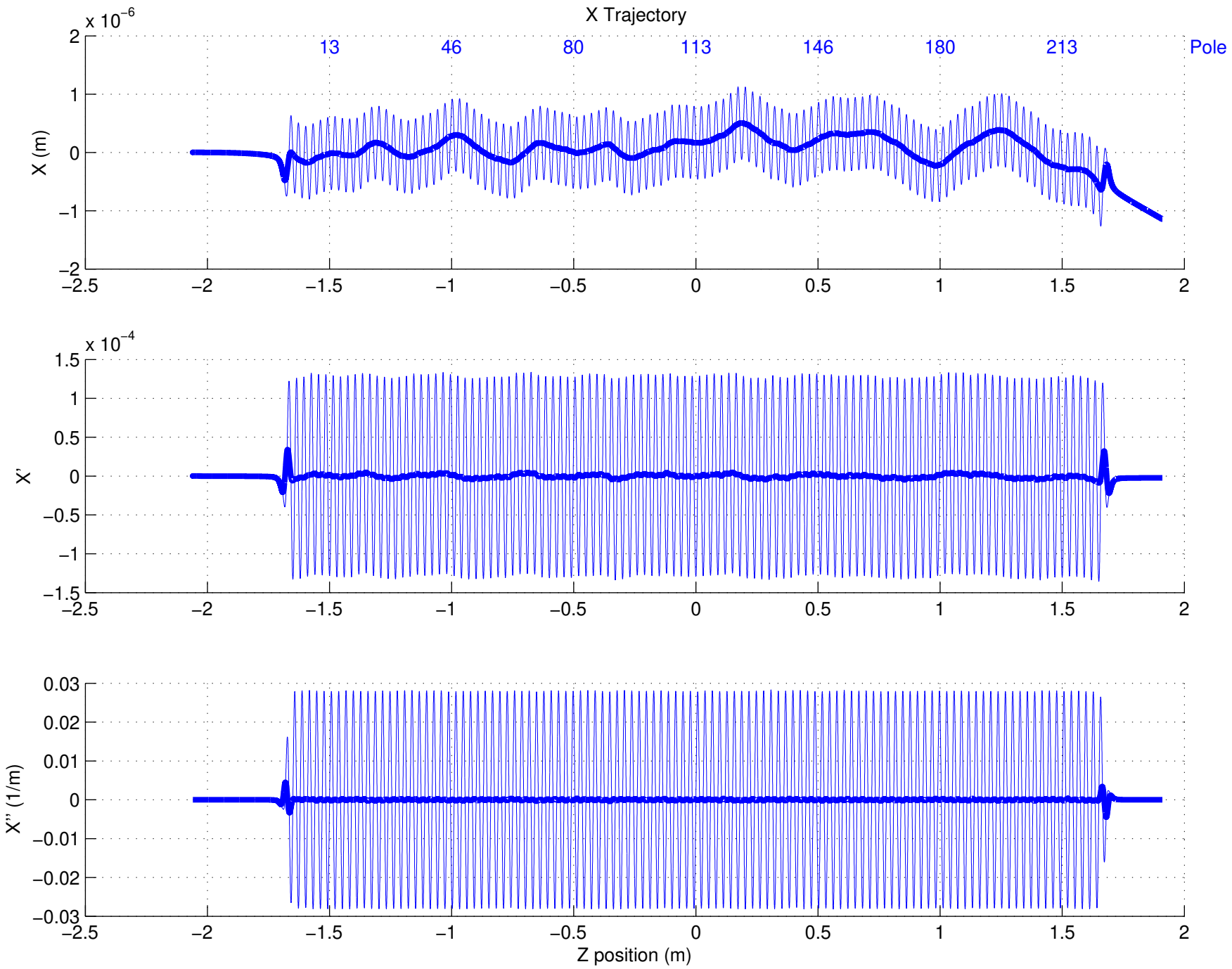
Peak Fields: Ave = 1.271797 T, RMS = 0.004046 T

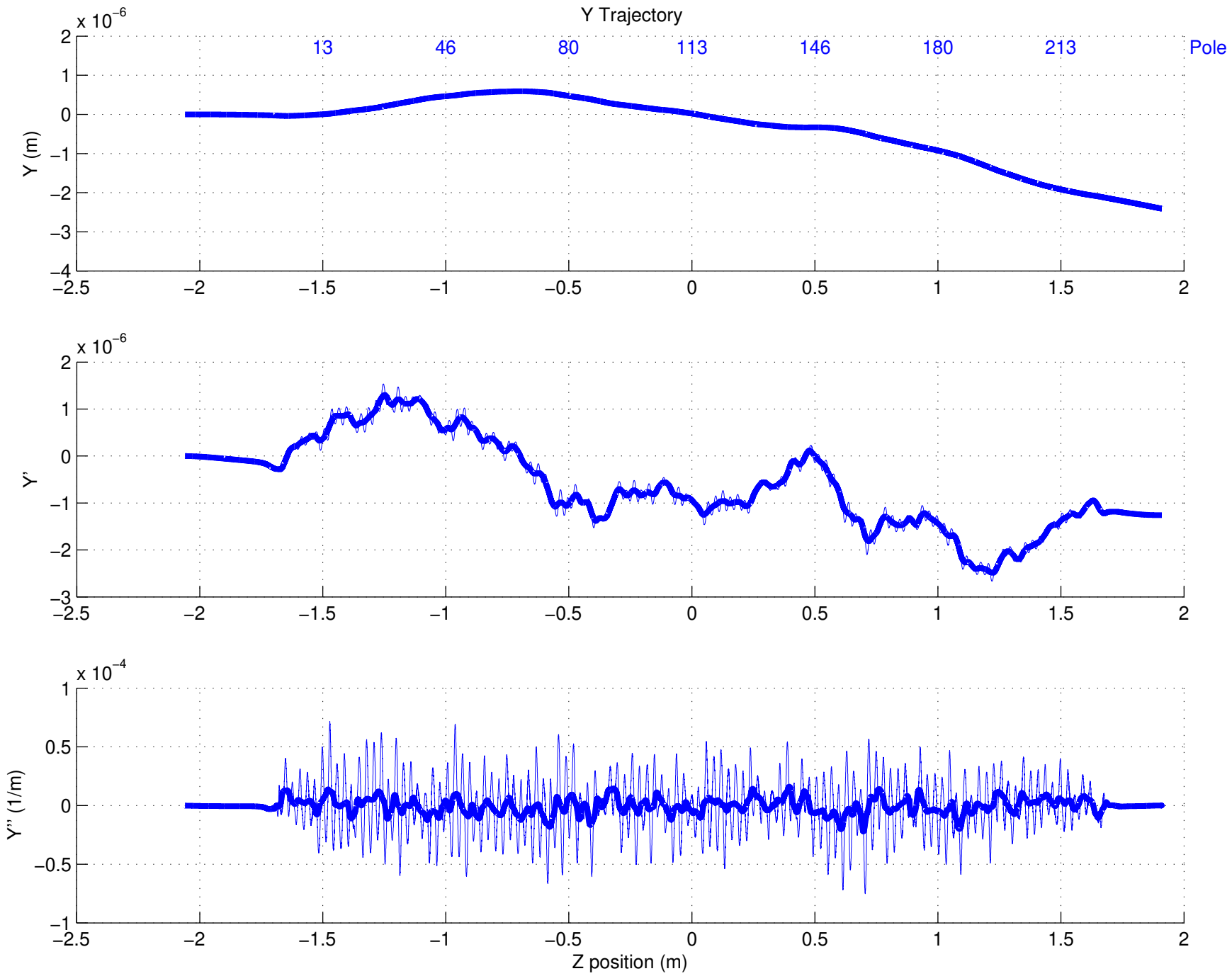


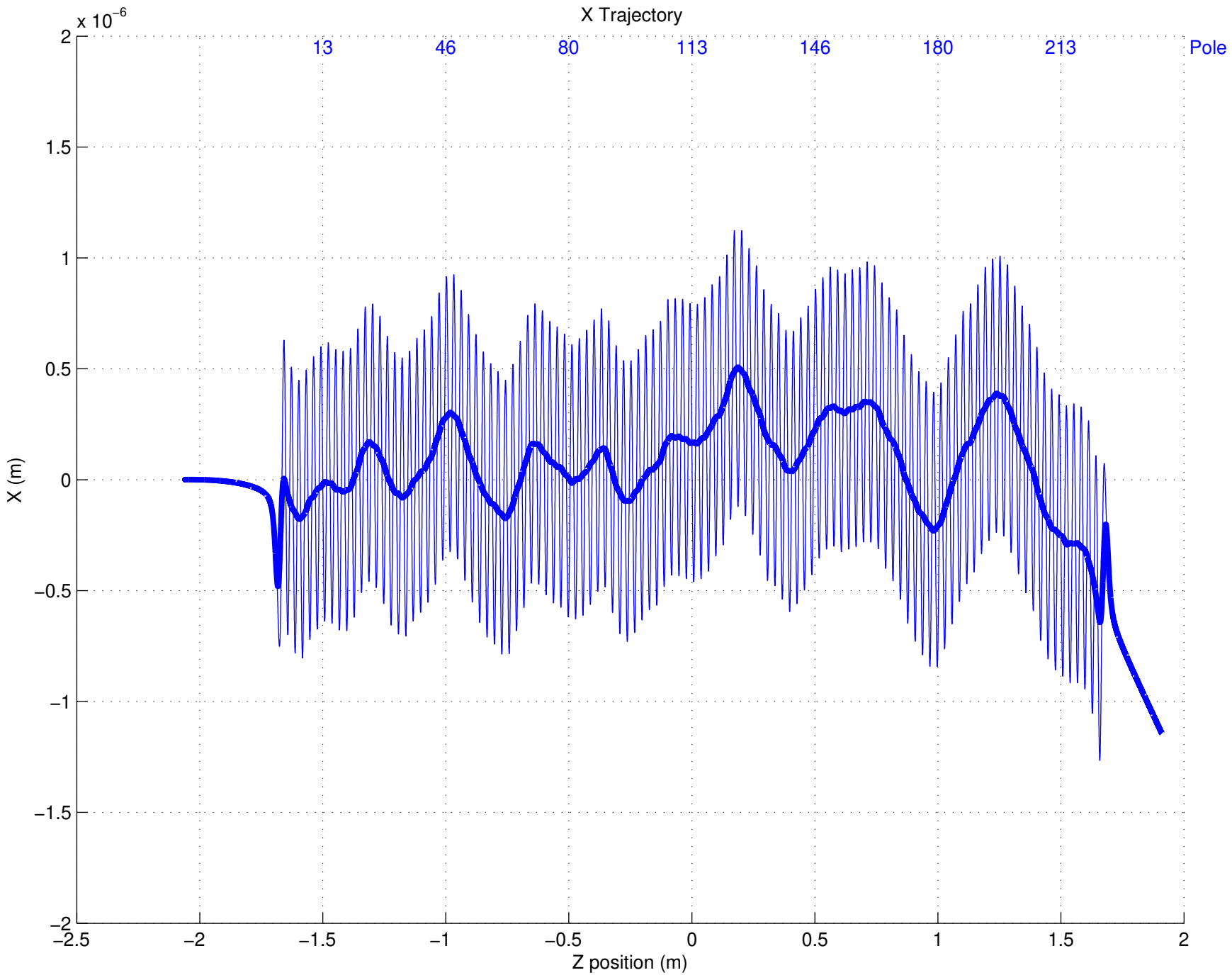
Peak Field Spacing: Ave = 0.014999 m, RMS = 0.000021 m

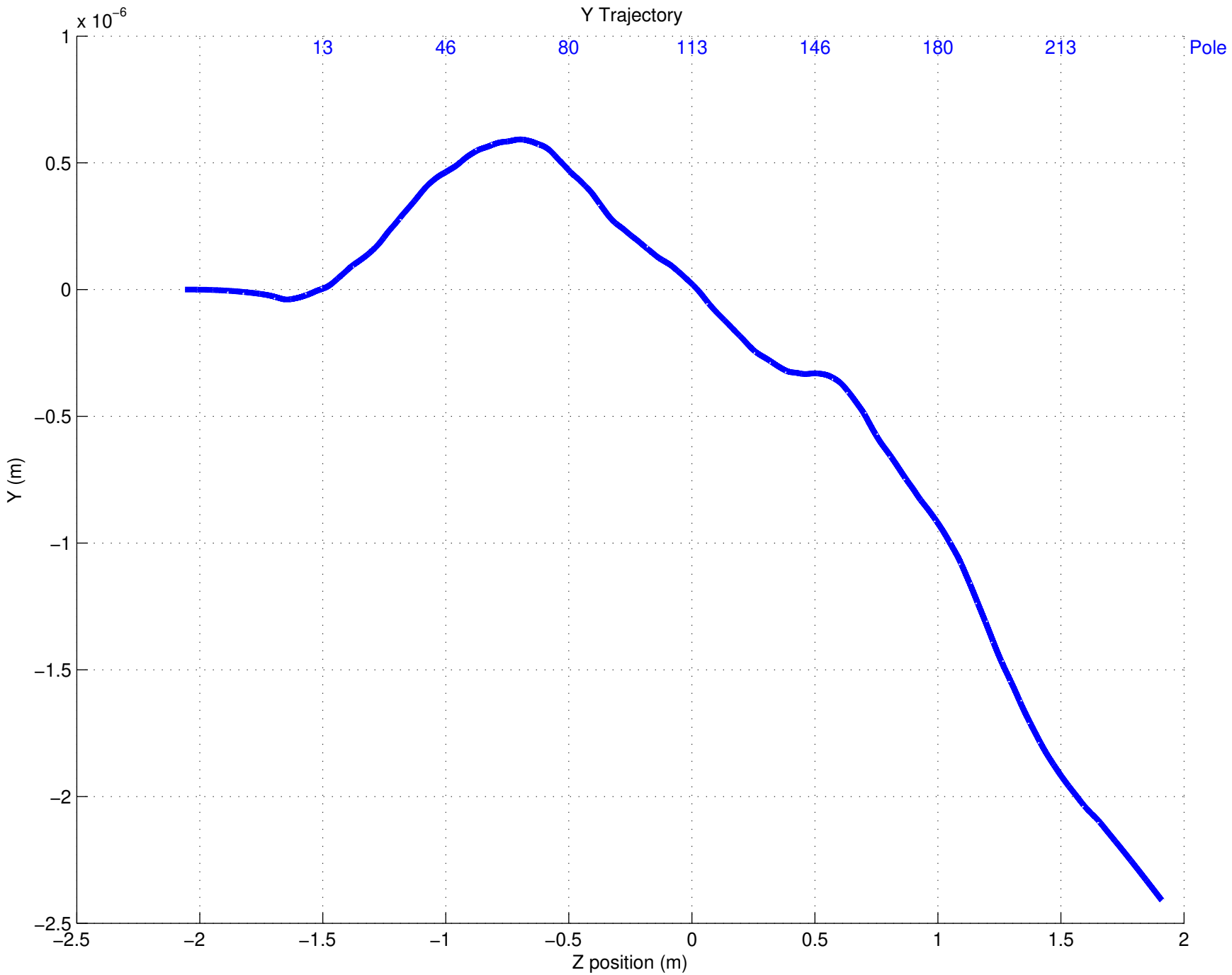


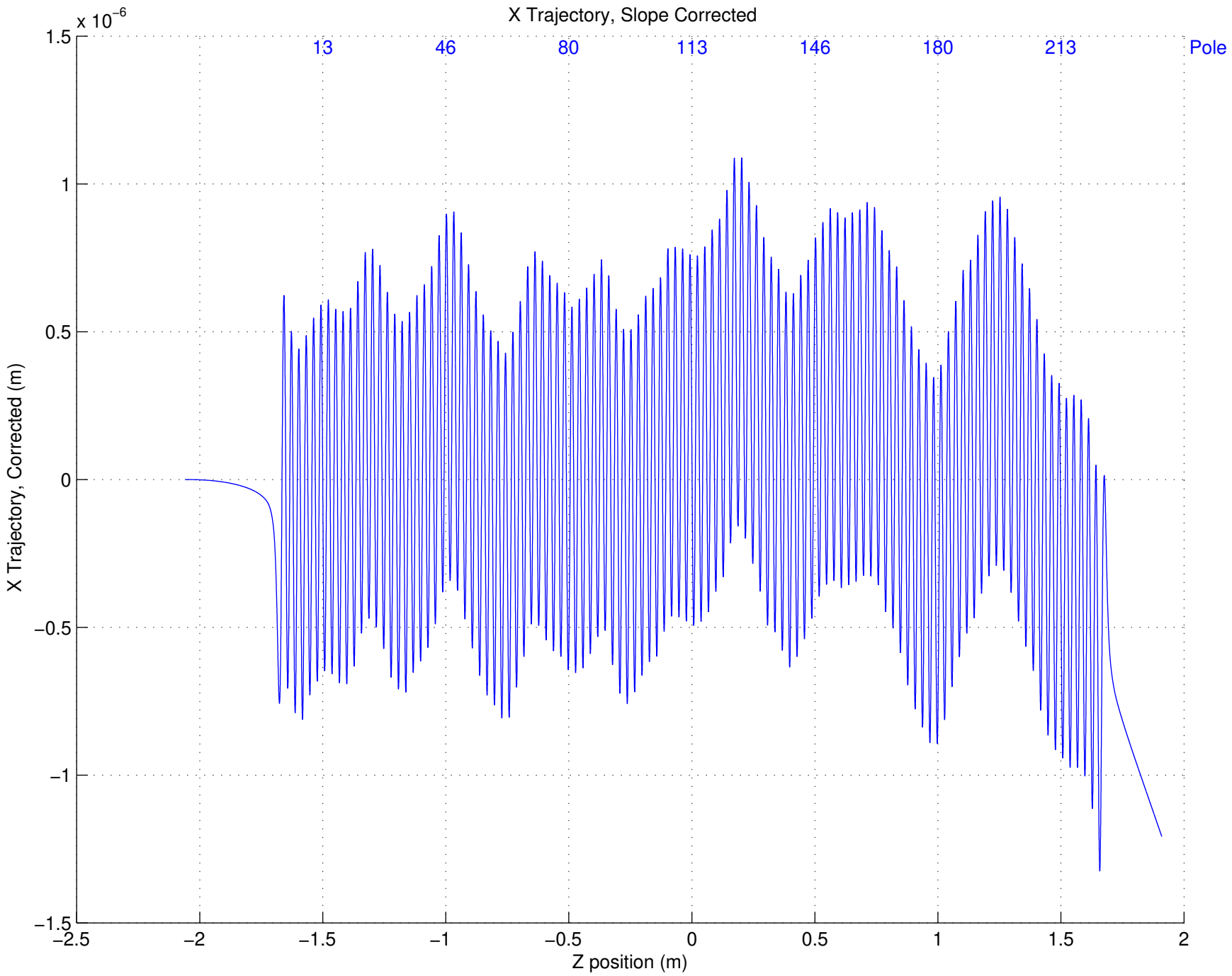
Zero Field Spacing: Ave = 0.014999 m, RMS = 0.000036 m

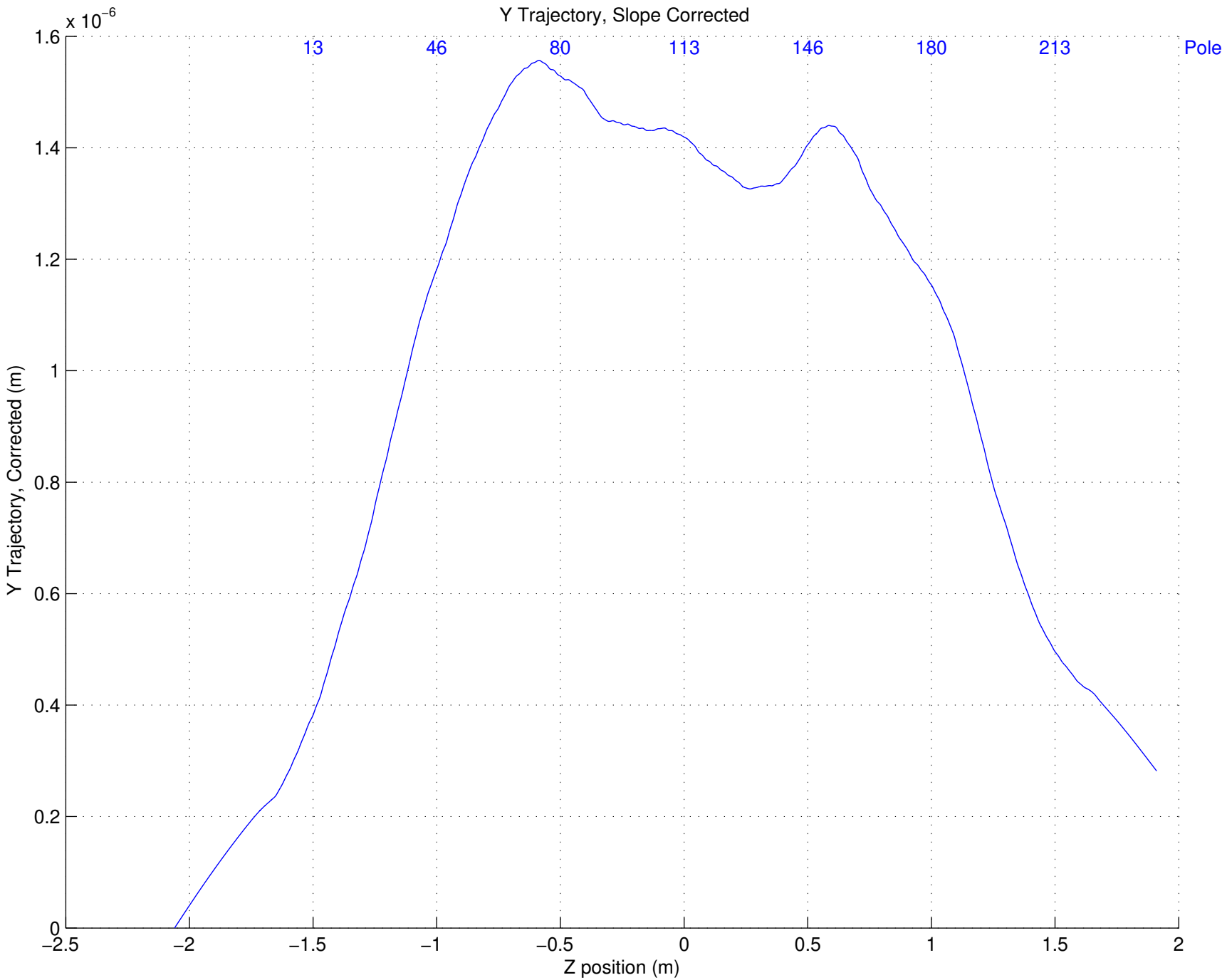

X Trajectory
x 10^-6
13
46
80
113
146
180
213
Pole
X (m)
x 10^-4
X'
X'' (1/m)
Z position (m)

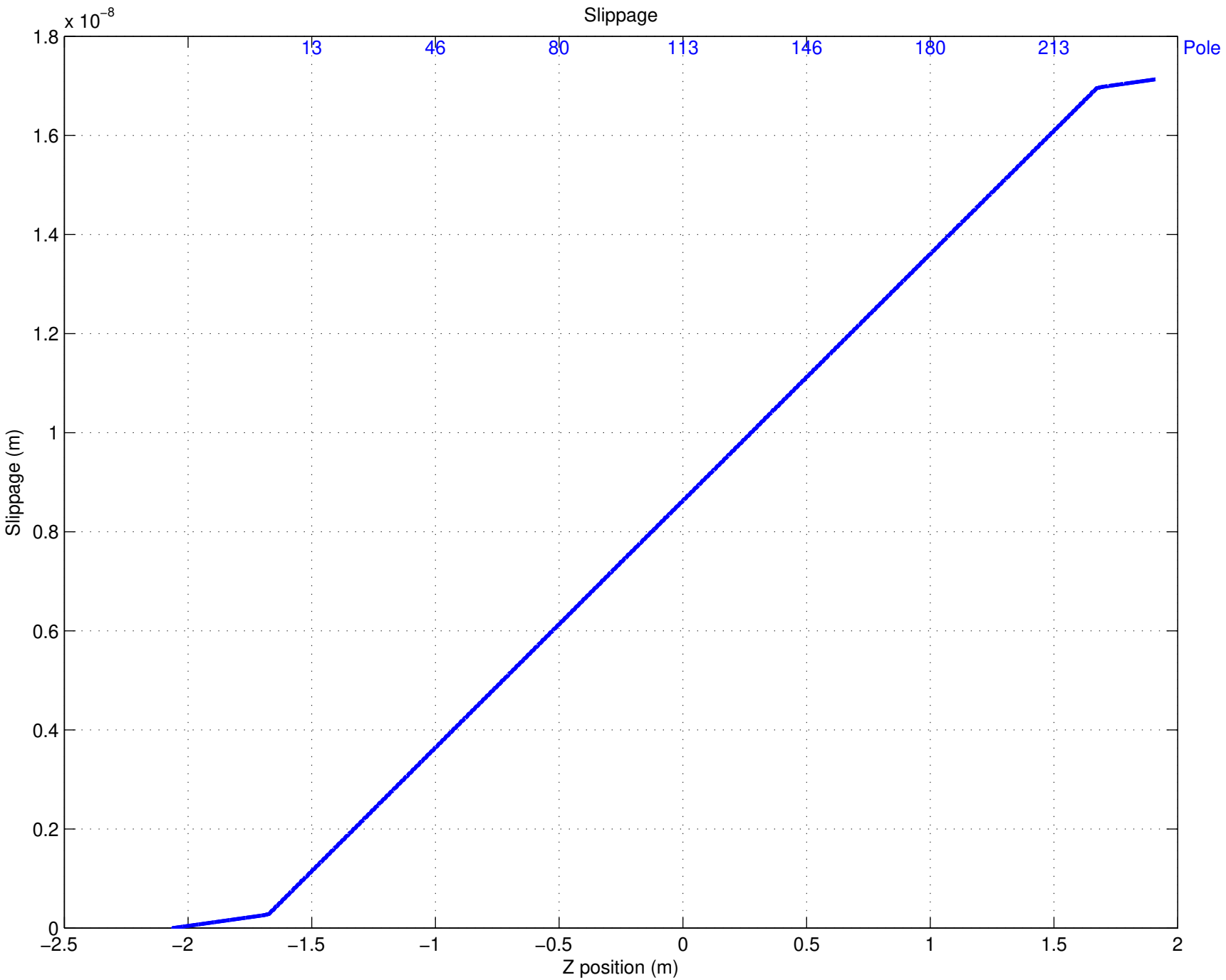

Y Trajectory
x 10^-6
13
46
80
113
146
180
213
Pole
Y (m)
x 10^-6
Y'
x 10^-4
Y'' (1/m)
Z position (m)


X Trajectory
x 10^-6
13
46
80
113
146
180
213
Pole
2
1.5
1
0.5
0
−0.5
−1
−1.5
−2
X (m)
−2.5
−2
−1.5
−1
−0.5
0
0.5
1
1.5
2
Z position (m)


Y Trajectory
x 10^-6
13
46
80
113
146
180
213
Pole
1
0.5
0
−0.5
−1
−1.5
−2
−2.5
Y (m)
−2.5
−2
−1.5
−1
−0.5
0
0.5
1
1.5
2
Z position (m)


X Trajectory, Slope Corrected
x 10^-6
1.5
1
0.5
0
−0.5
−1
−1.5
X Trajectory, Corrected (m)
13
46
80
113
146
180
213
Pole
−2.5
−2
−1.5
−1
−0.5
0
0.5
1
1.5
2
Z position (m)


Y Trajectory, Slope Corrected
x 10^-6
13
46
80
113
146
180
213
Pole
1.6
1.4
1.2
1
0.8
0.6
0.4
0.2
0
Y Trajectory, Corrected (m)
−2.5
−2
−1.5
−1
−0.5
0
0.5
1
1.5
2
Z position (m)


Slippage
x 10^-8
13
46
80
113
146
180
213
Pole
1.8
1.6
1.4
1.2
1
0.8
0.6
0.4
0.2
0
Slippage (m)
−2.5
−2
−1.5
−1
−0.5
0
0.5
1
1.5
2
Z position (m)