SLAC Magnetic Measurements

Trajectory Analysis
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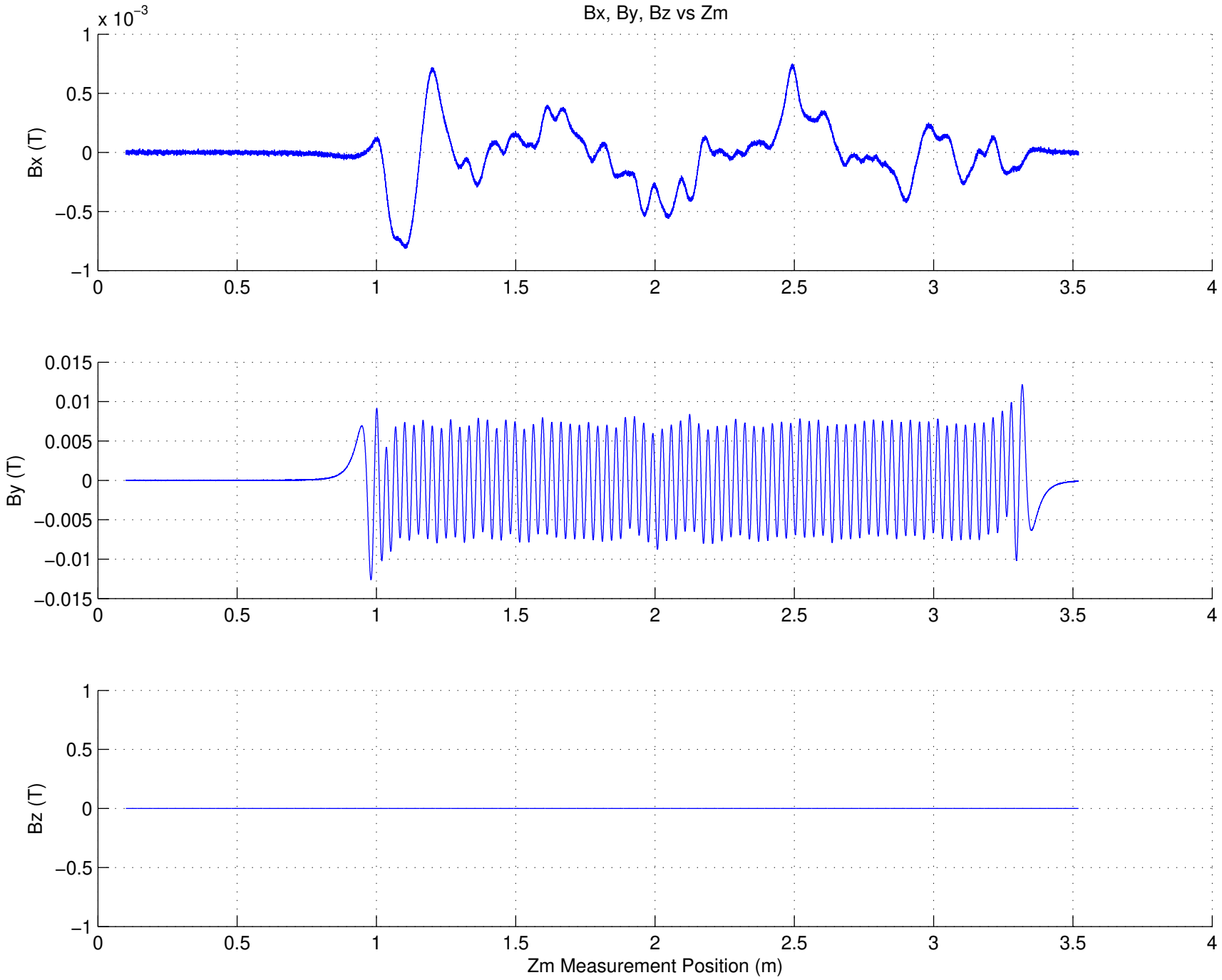
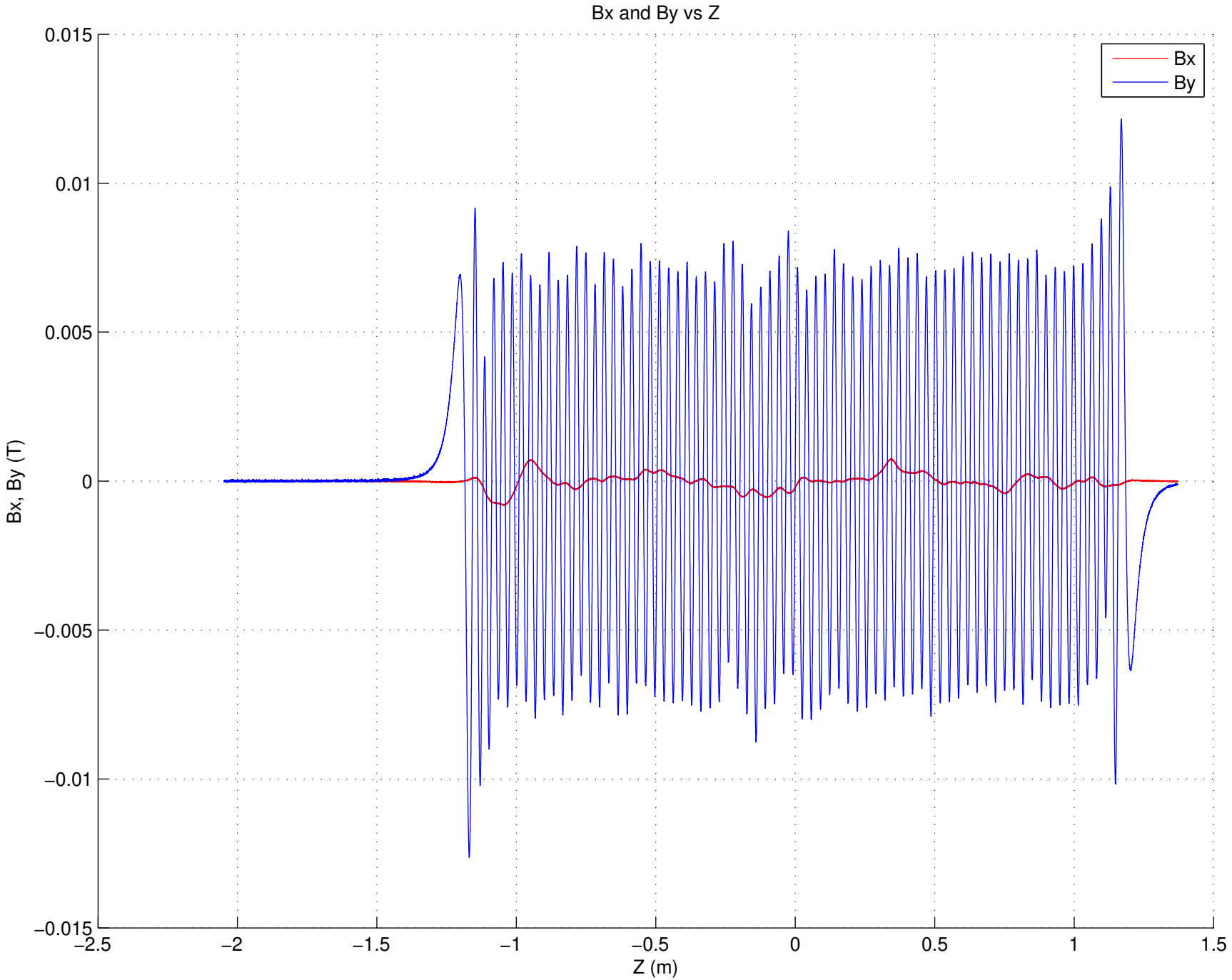
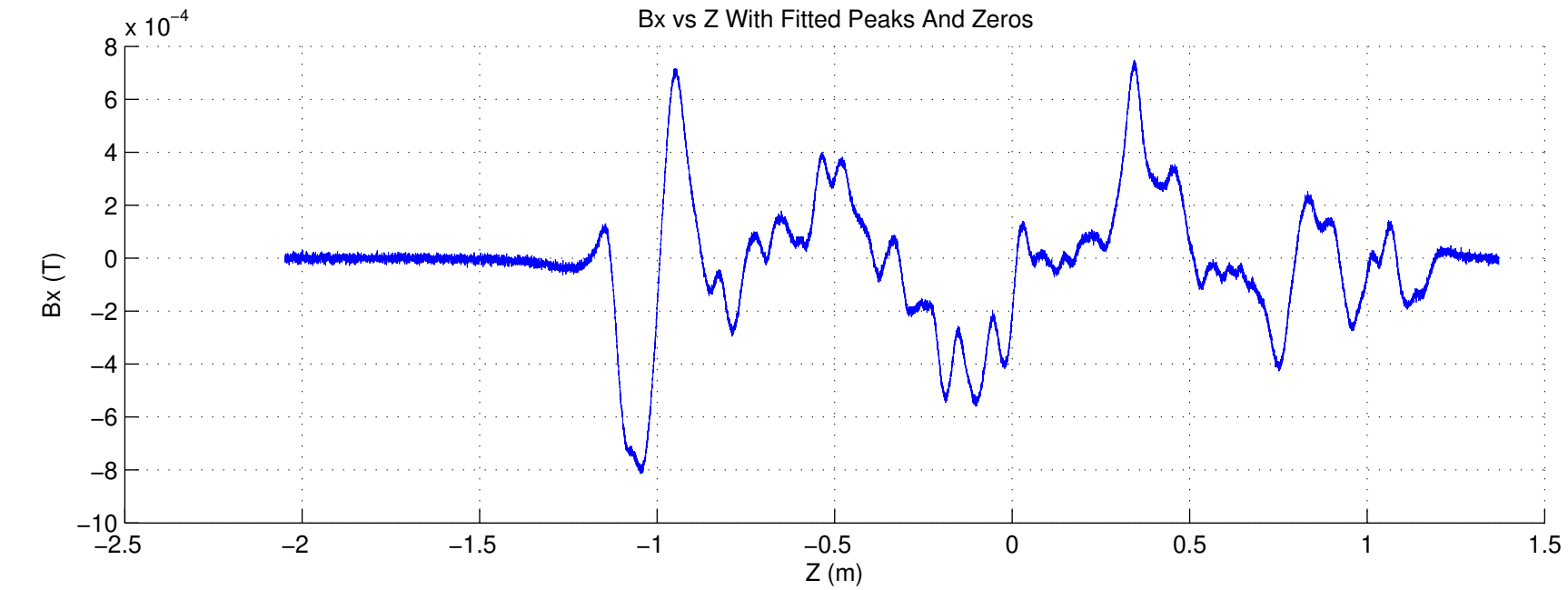
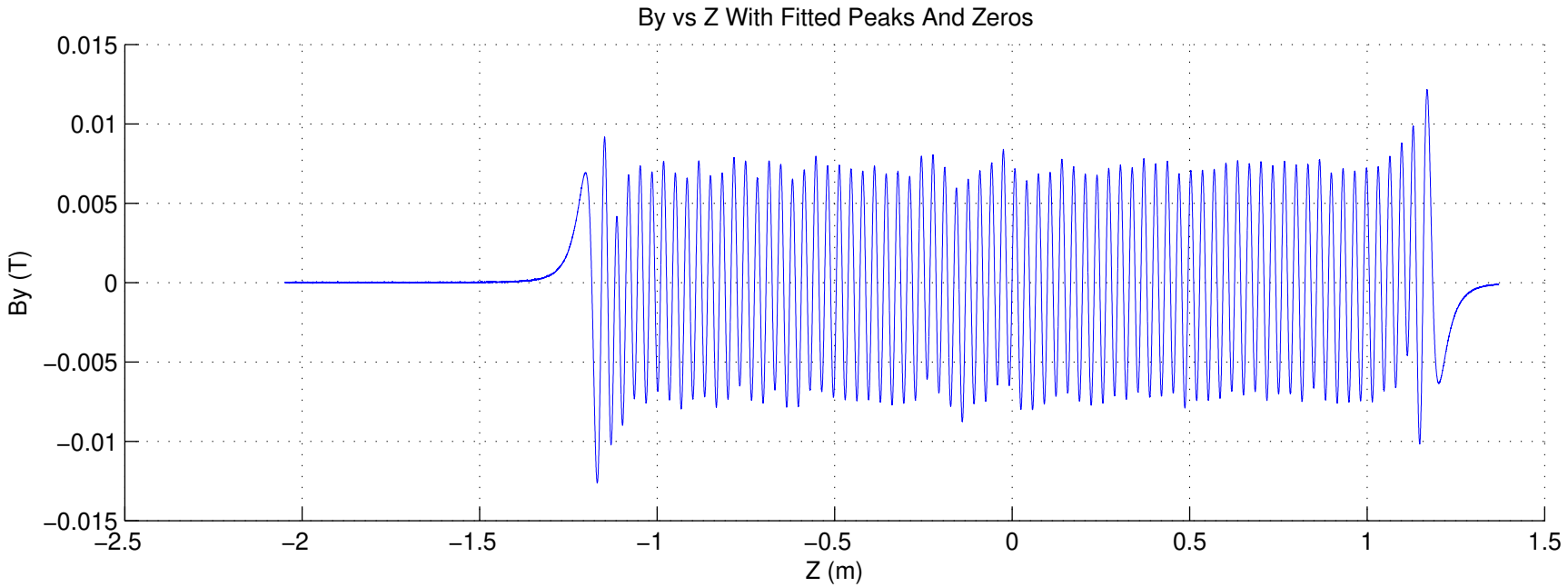
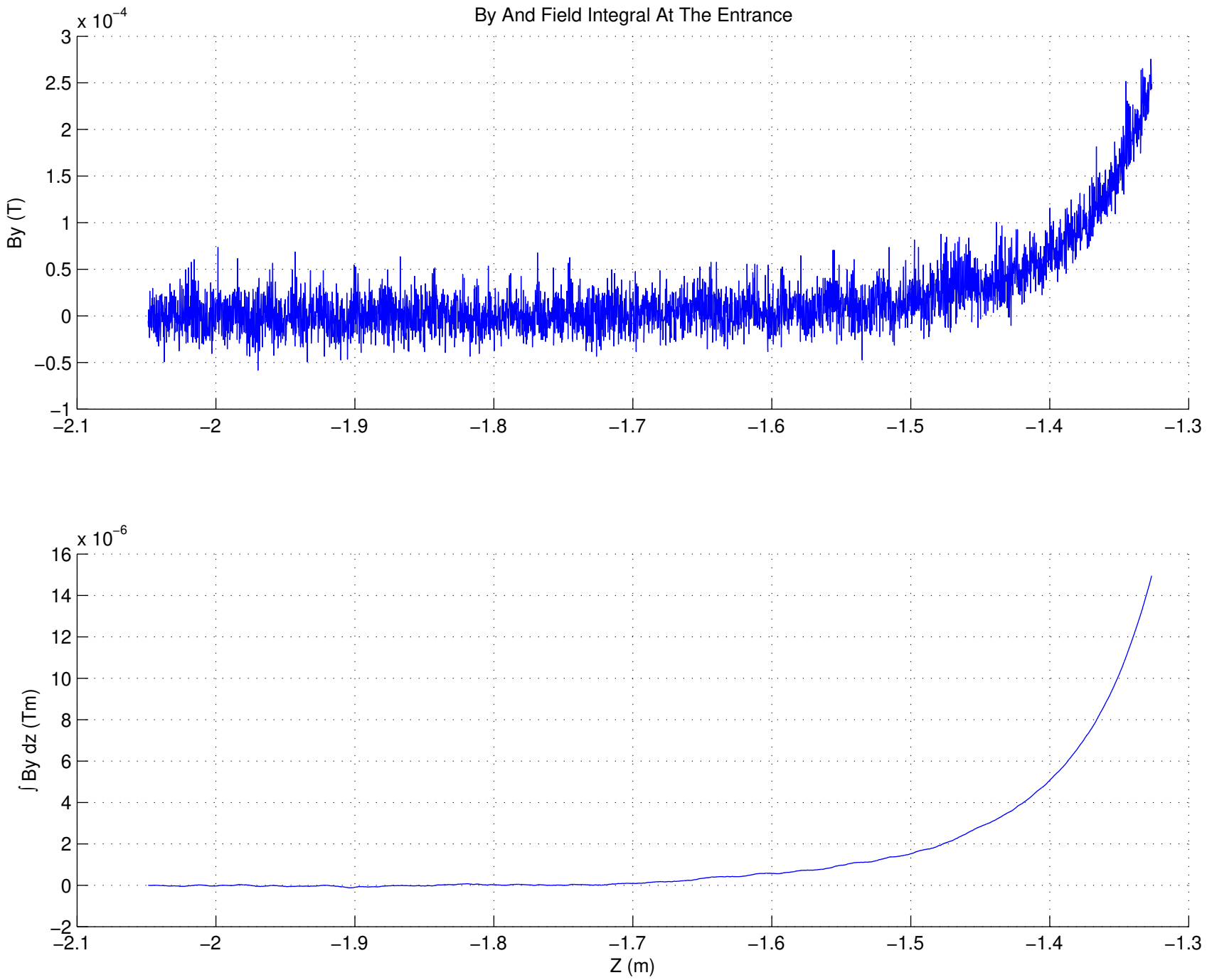
Parameters:
INPUT−FILE−DIR =S:\MagData\LCLS\Undulator\A1−ANL\DATASET0001\Rough Tuning\Z Scans\Run 045\
INPUT−FILE−NAME =x+00000−y+000−bscanz−fixed.dat
INPUT−FILE−TYPE =ZVXYBXYH
CORR−REQUIRED =0
GAMMA =26627.1
DEVICE CENTER POSITION ZM =2.1492 m
DEVICE ENTRANCE POSITION ZM =0.9685 m
DEVICE EXIT POSITION ZM =3.3299 m
NOM−LAMBDA−R =1.5e−010 m

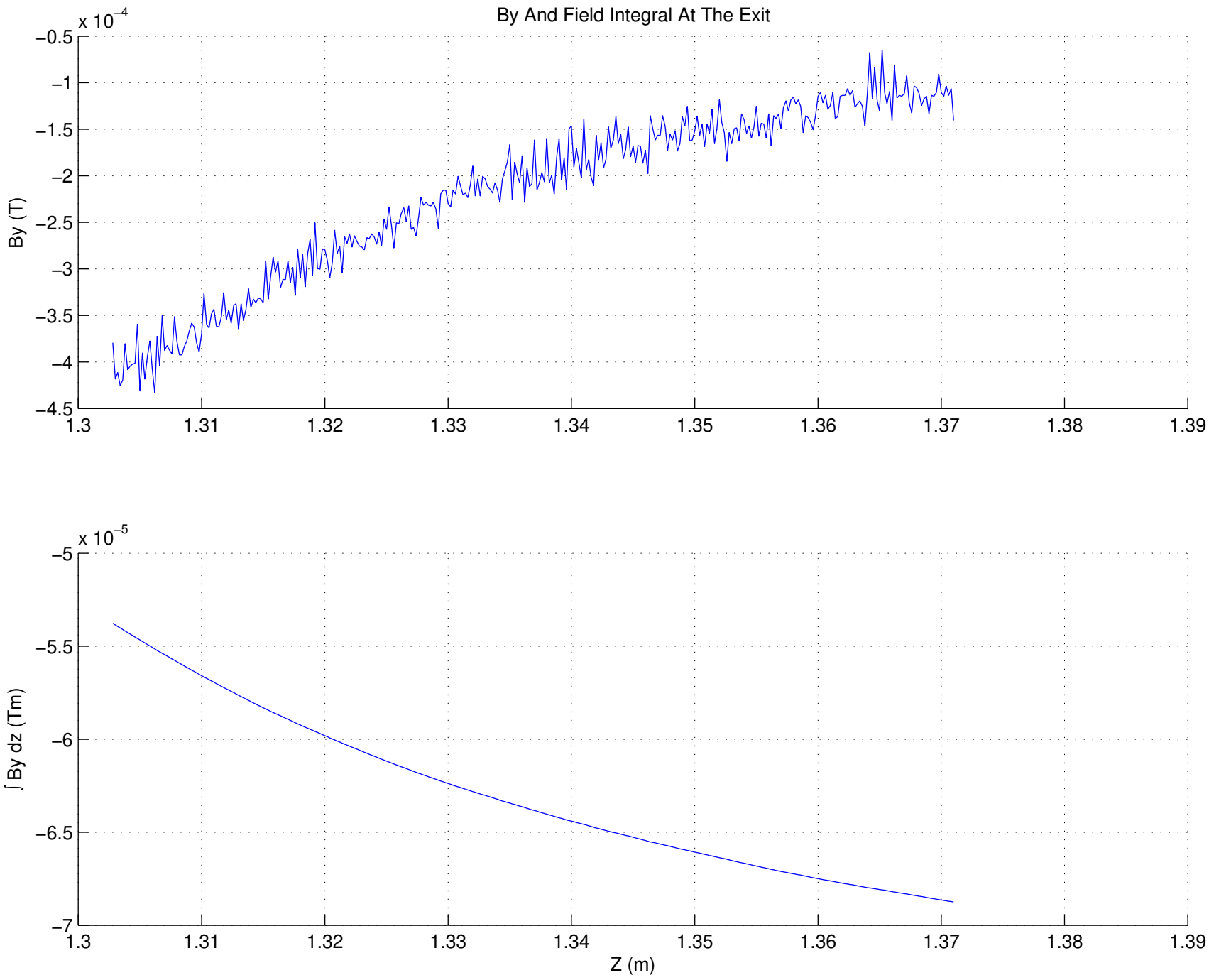

Bx, By, Bz vs Zm
x 10^-3
Bx (T)
By (T)
Bz (T)
Zm Measurement Position (m)
1
0.5
0
−0.5
−1
0.015
0.01
0.005
−0.005
−0.01
−0.015
0
0.5
1
1.5
2
2.5
3
3.5
4

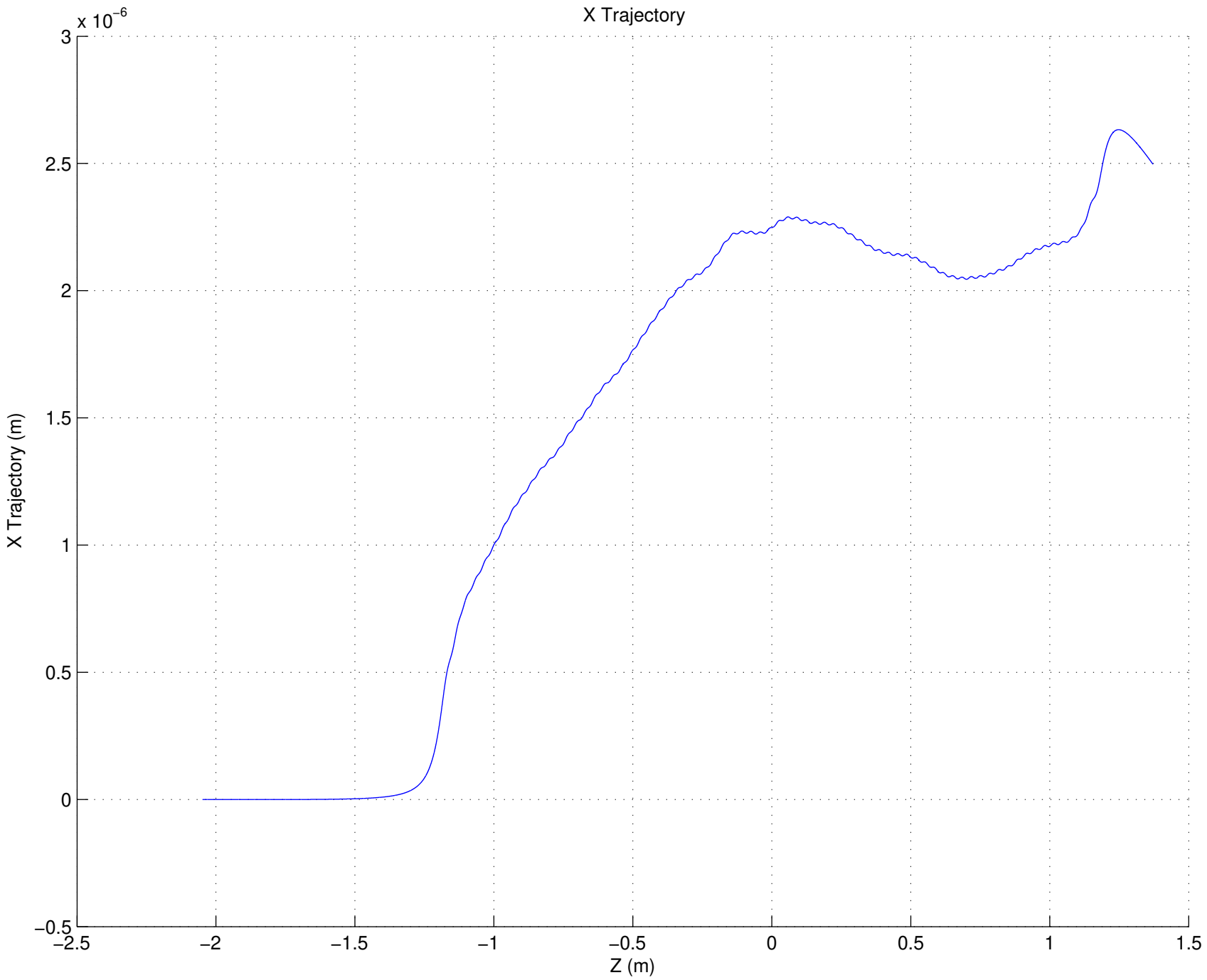

Bx and By vs Z
Bx
By
0.015
0.01
0.005
0
−0.005
−0.01
−0.015
Bx, By (T)
−2.5
−2
−1.5
−1
−0.5
0
0.5
1
1.5
Z (m)

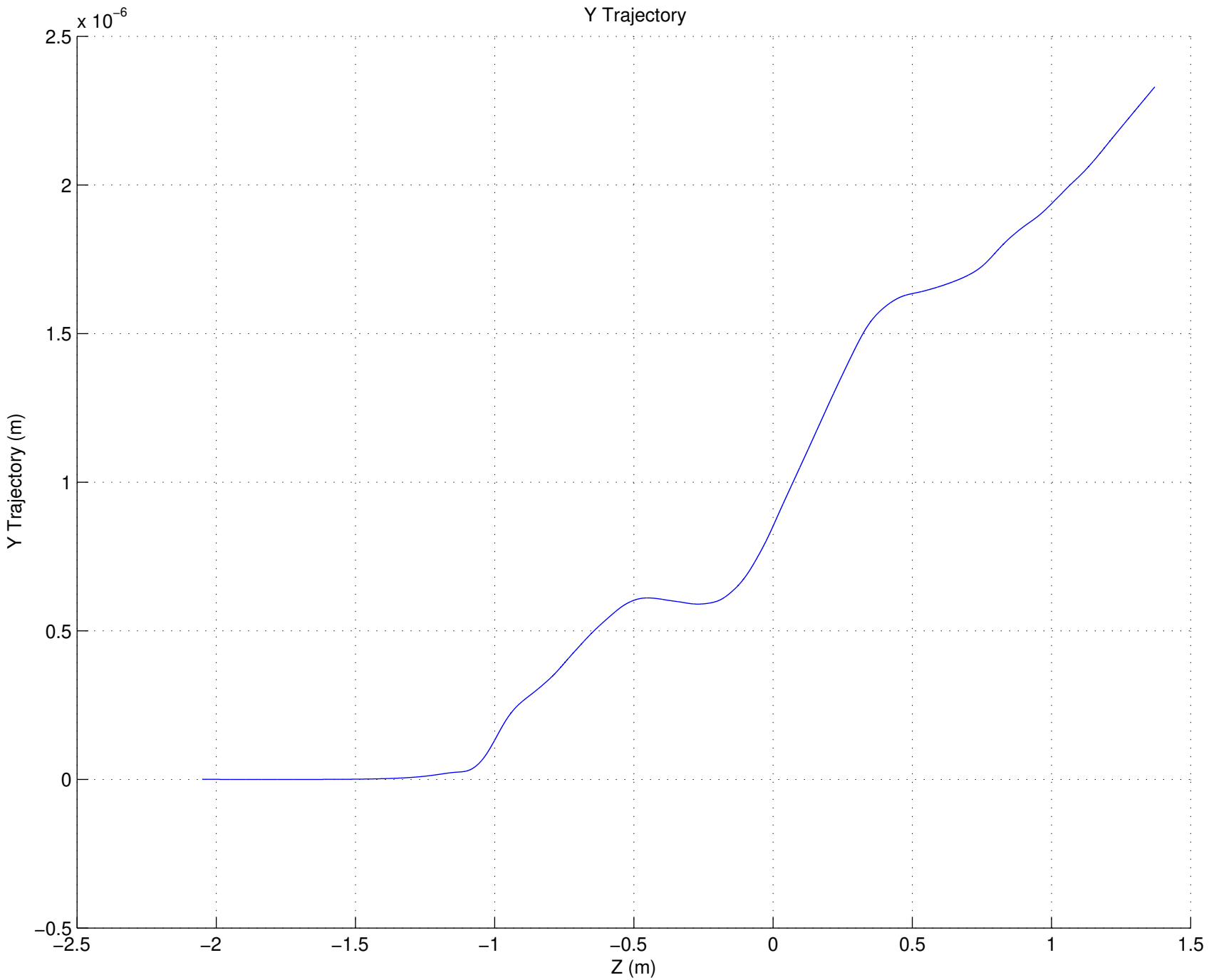

Bx vs Z With Fitted Peaks And Zeros
x 10^-4
8
6
4
2
0
−2
−4
−6
−8
−10
Bx (T)
−2.5
−2
−1.5
−1
−0.5
0
0.5
1
1.5
Z (m)

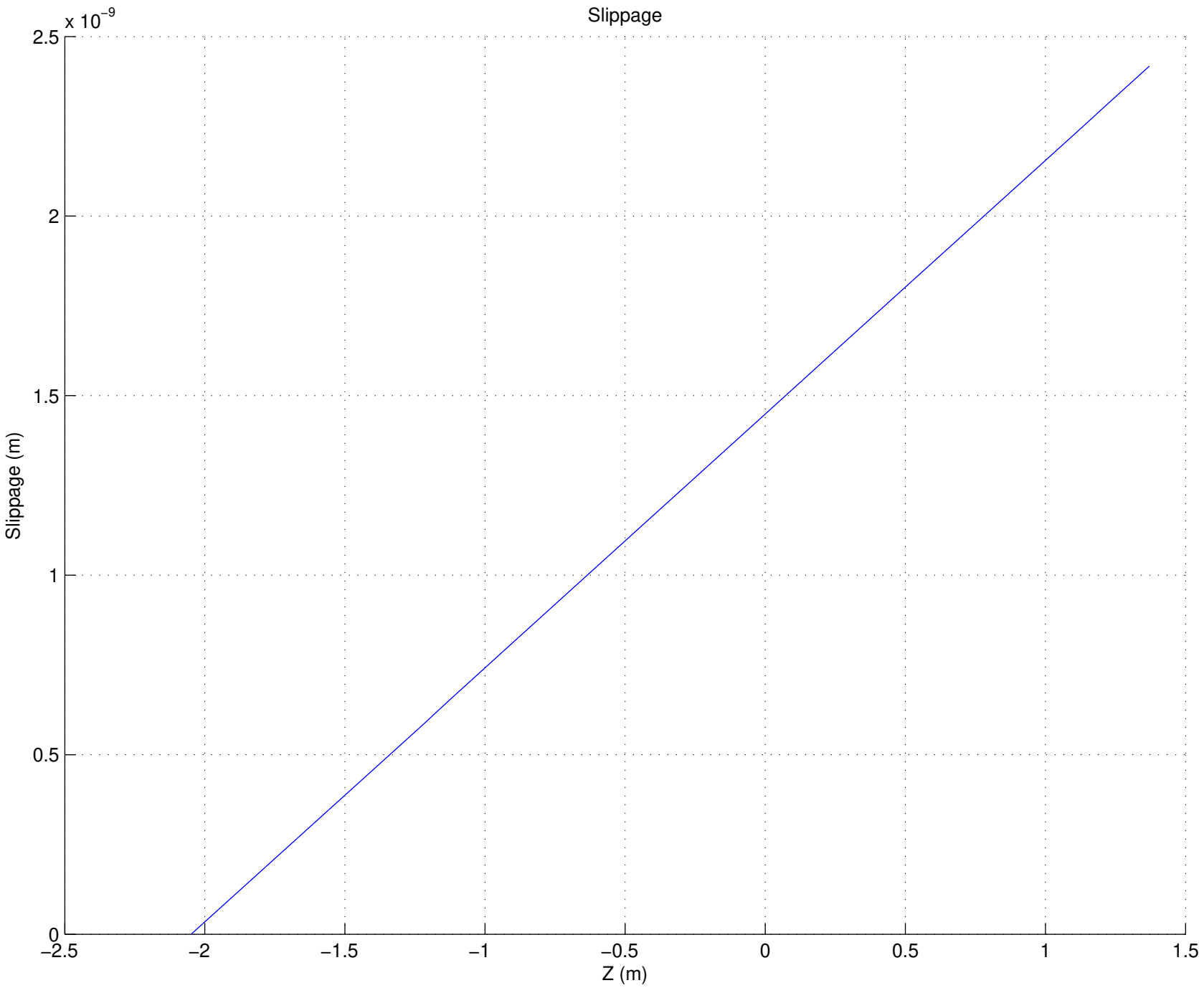

By vs Z With Fitted Peaks And Zeros
0.015
0.01
0.005
0
−0.005
−0.01
−0.015
By (T)
−2.5
−2
−1.5
−1
−0.5
0
0.5
1
1.5
Z (m)

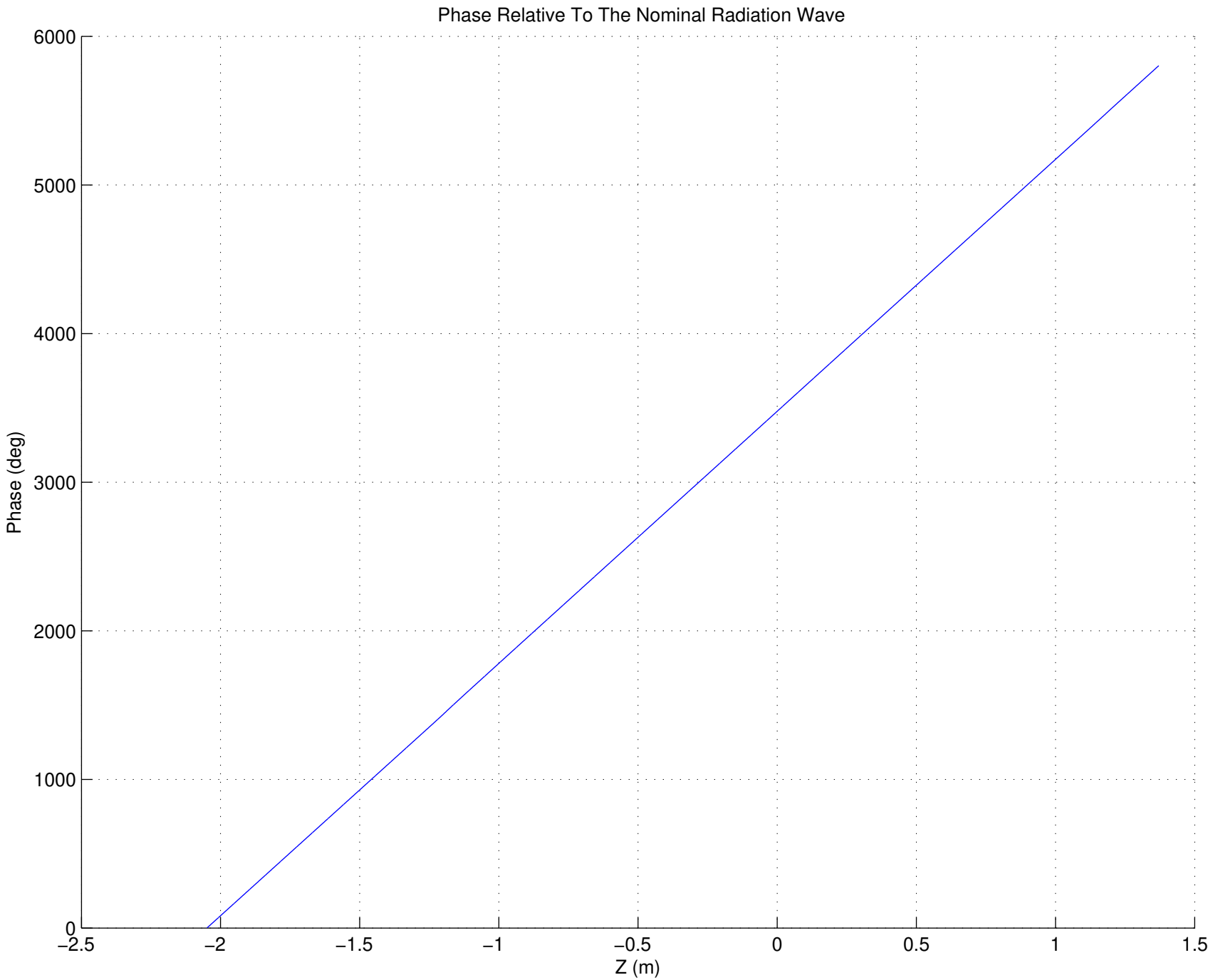

By And Field Integral At The Entrance
x 10^-4
By (T)
3
2.5
2
1.5
1
0.5
0
−0.5
−1
−2.1
−2
−1.9
−1.8
−1.7
−1.6
−1.5
−1.4
−1.3
x 10^-6
∫ By dz (Tm)
16
14
12
10
8
6
4
2
0
−2
Z (m)


By And Field Integral At The Exit
x 10^-4
−0.5
−1
−1.5
−2
−2.5
−3
−3.5
−4
−4.5
By (T)
1.3
1.31
1.32
1.33
1.34
1.35
1.36
1.37
1.38
1.39
x 10^-5
−5
−5.5
−6
−6.5
−7
∫ By dz (Tm)
Z (m)


X Trajectory
x 10^-6
3
2.5
2
1.5
1
0.5
0
−0.5
X Trajectory (m)
−2.5
−2
−1.5
−1
−0.5
0
0.5
1
1.5
Z (m)


Y Trajectory
x 10^-6
2.5
2
1.5
1
0.5
0
−0.5
Y Trajectory (m)
−2.5
−2
−1.5
−1
−0.5
0
0.5
1
1.5
Z (m)


Slippage
x 10^-9
2.5
2
1.5
1
0.5
0
Slippage (m)
−2.5
−2
−1.5
−1
−0.5
0
0.5
1
1.5
Z (m)


Phase Relative To The Nominal Radiation Wave
Phase (deg)
Z (m)
6000
5000
4000
3000
2000
1000
0
−2.5
−2
−1.5
−1
−0.5
0
0.5
1
1.5