

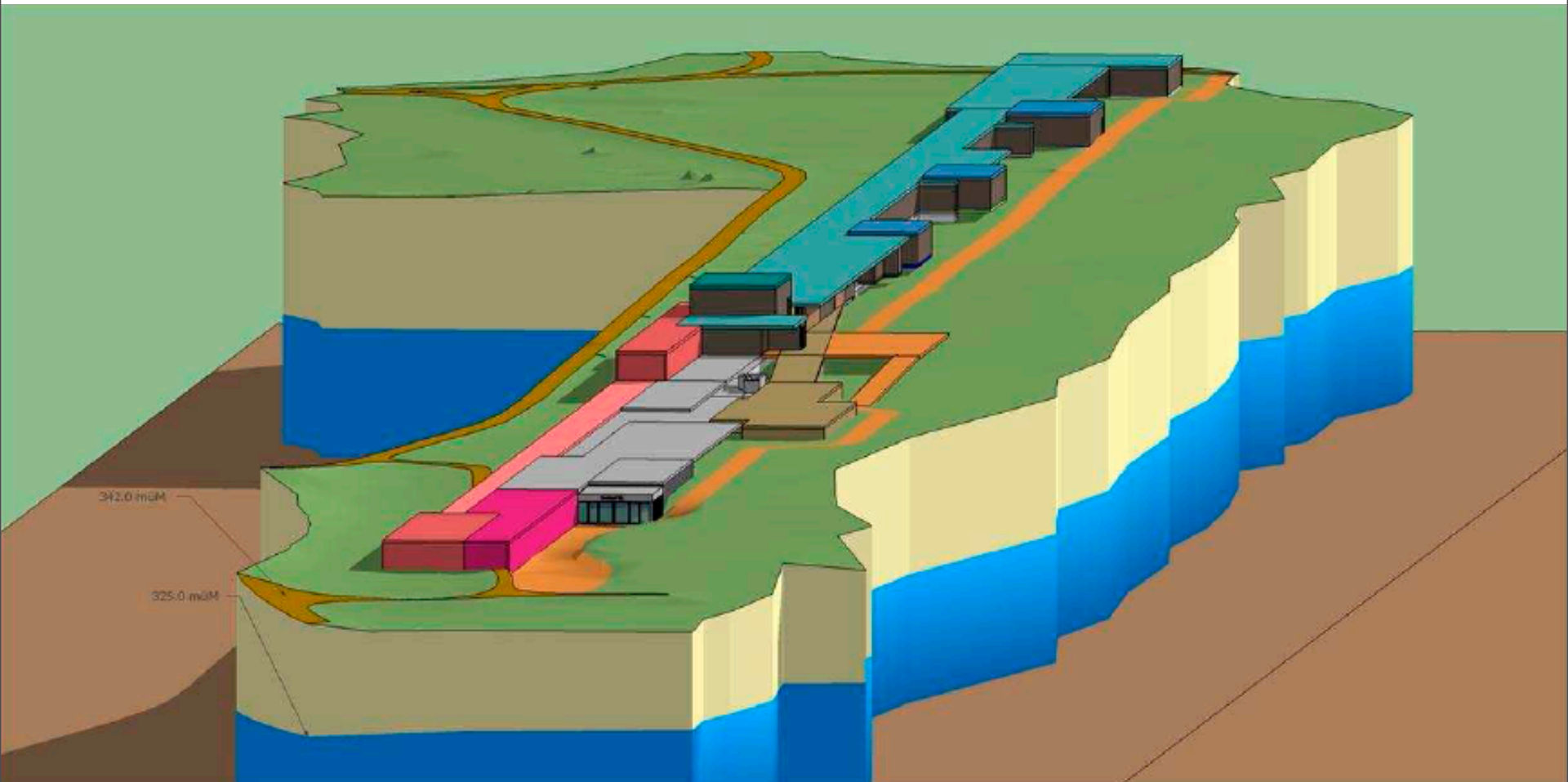


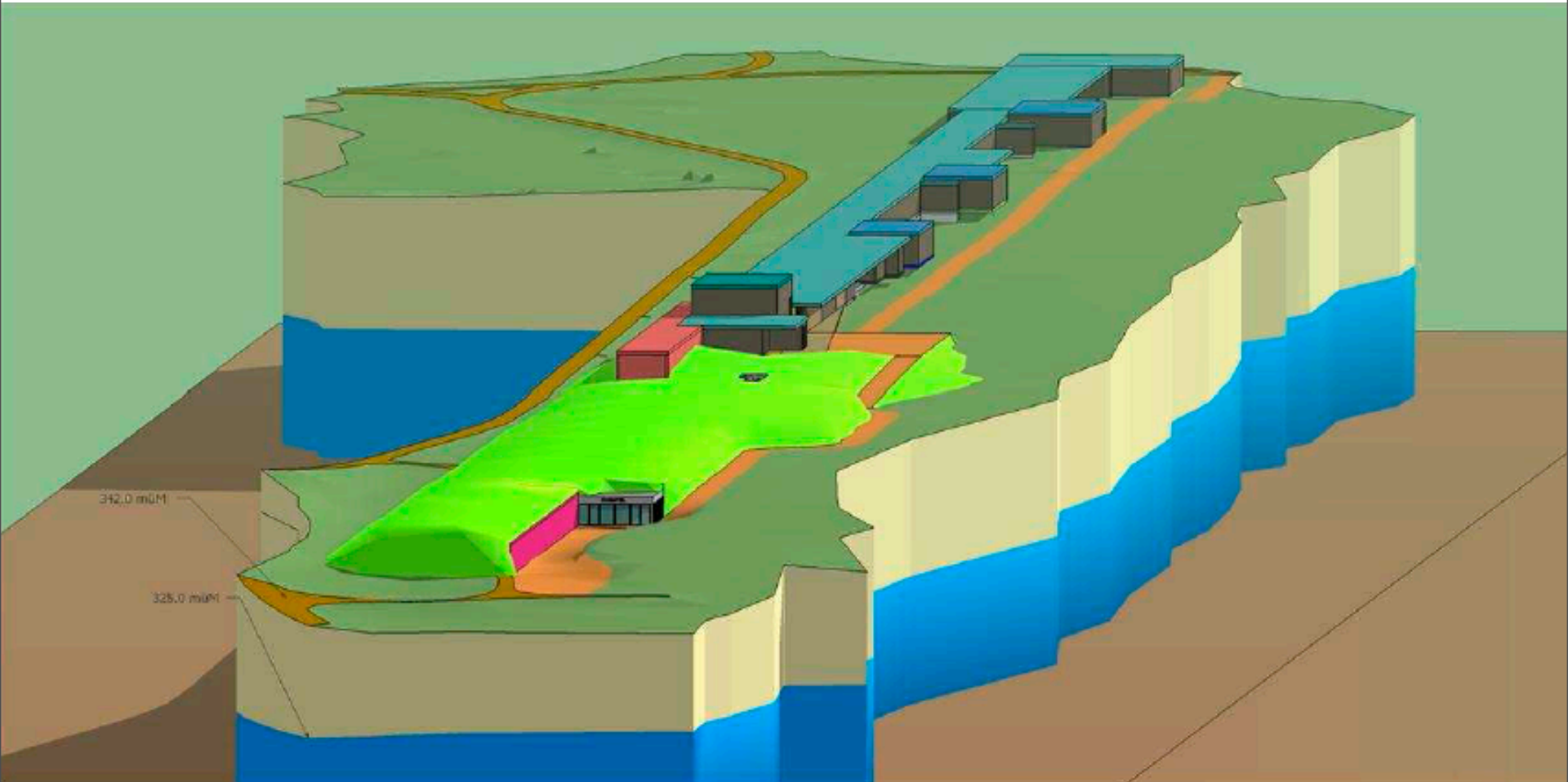
SwissFEL Undulators

Thomas Schmidt
PSI

on behalf of SwissFEL ID Project Team

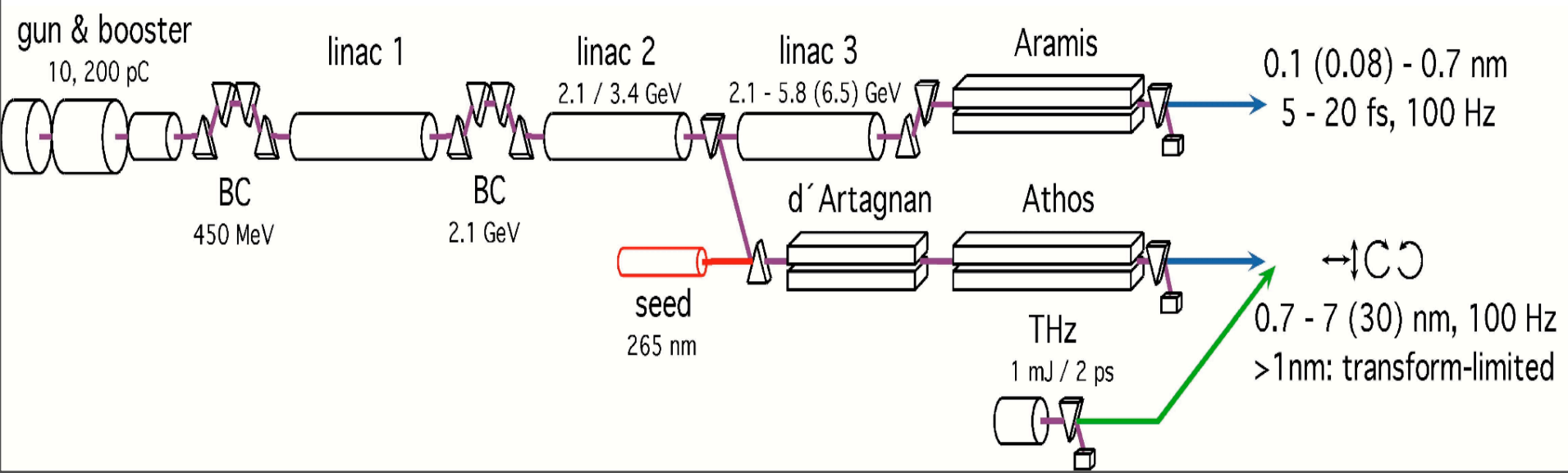
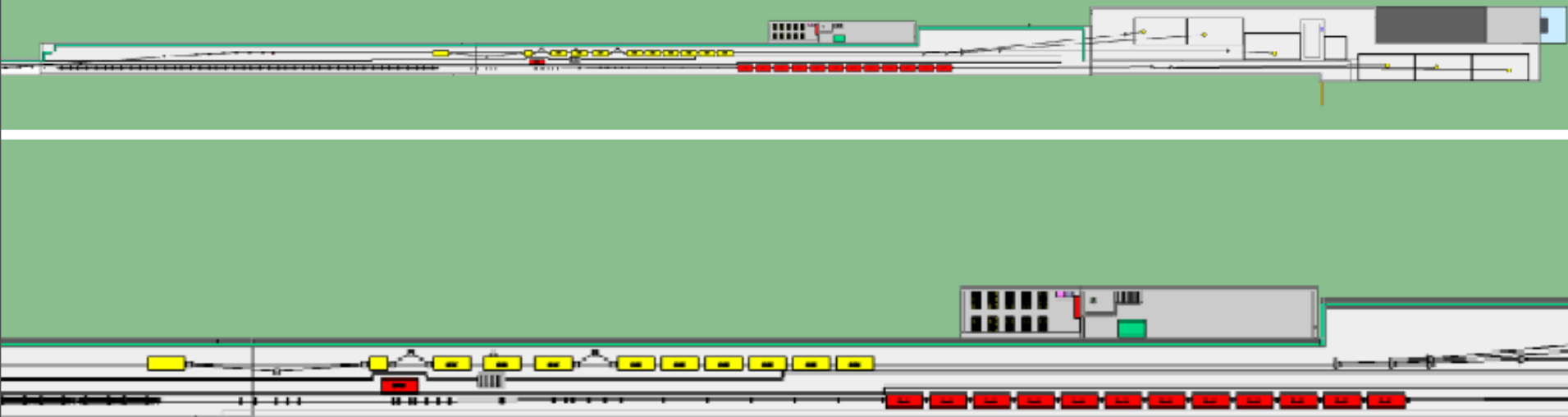
LCLS II meeting





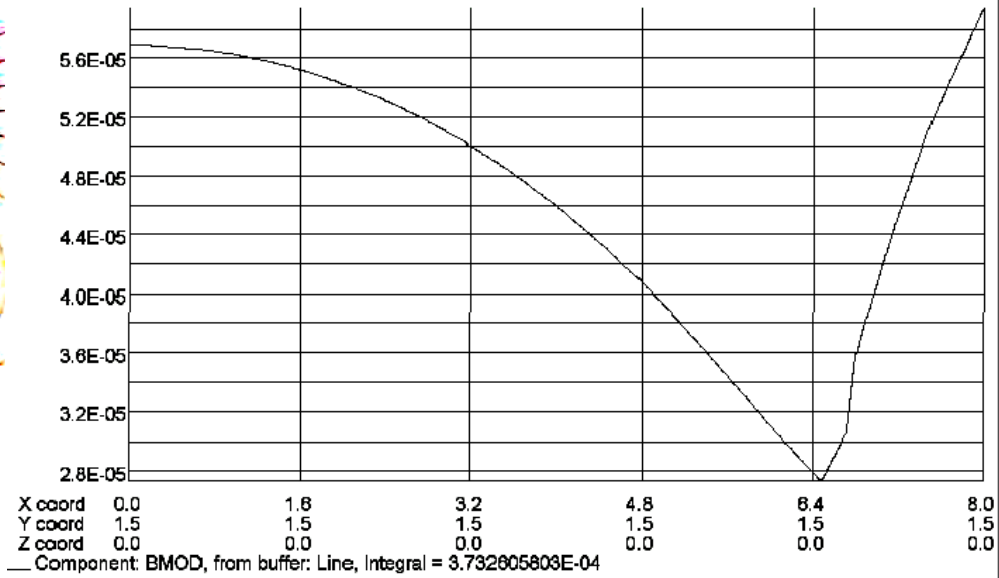
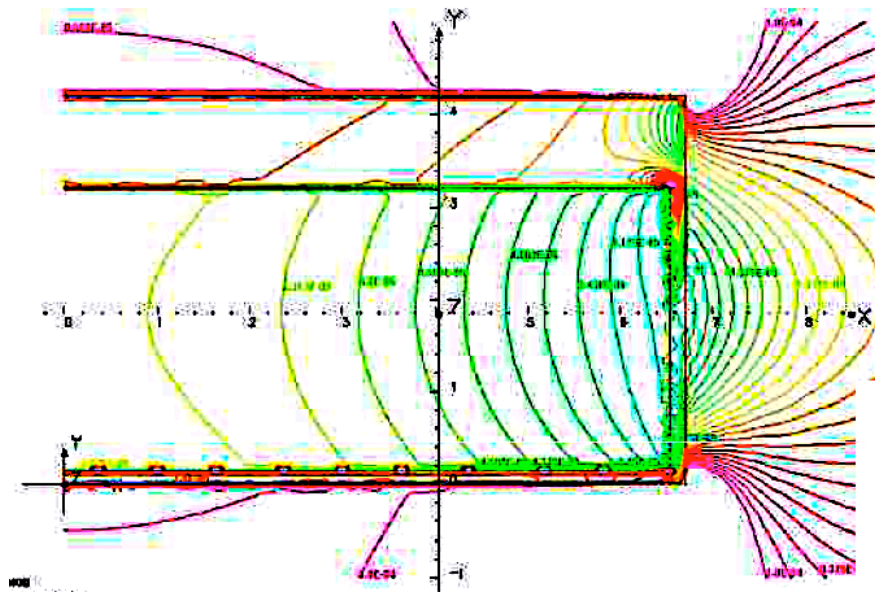
T. Schmidt April 28, 2010

Freitag, 30. April 2010



Shielding earth field in undulator tunnel

Opera 3D
by Marco Negrazus



attenuation factor
 in undulator tunnel: 1.7 - 3
 in linac tunnel: 5 - 8

Undulator Strategy for SLS

hard x-ray: (5 - 20 keV)

SPRING-8

small period
small gap
in-vacuum undulators
high harmonics (13th)

Hitachi
Danfysik
PSI



ID	gap
U24	6 - 12 mm
U19	4.5 - 7 mm
U14	4 - 6 mm
	length: 2m

soft x-ray: (10 eV - 2 (8) keV)

variable polarization
circular and inclined
electromagnetic
APPLE II
standard, fixed gap

BESSY

PSI



ID	gap
UE56	16 - 70 mm
UE54	16 - 70 mm (up to 28 th harm)
UE44	11.4 mm
	length: 2 - 3.4m

Undulator Strategy for SLS

hard x-ray: (5 - 20 keV)

soft x-ray: (10 eV - 2 (8) keV)

SPring-8

BESSY

small period
small gap
in-vacuum undulators
high harmonics (13th)

variable polarization
circular and inclined
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APPLE II
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PSI

Hitachi
Danfysik
PSI



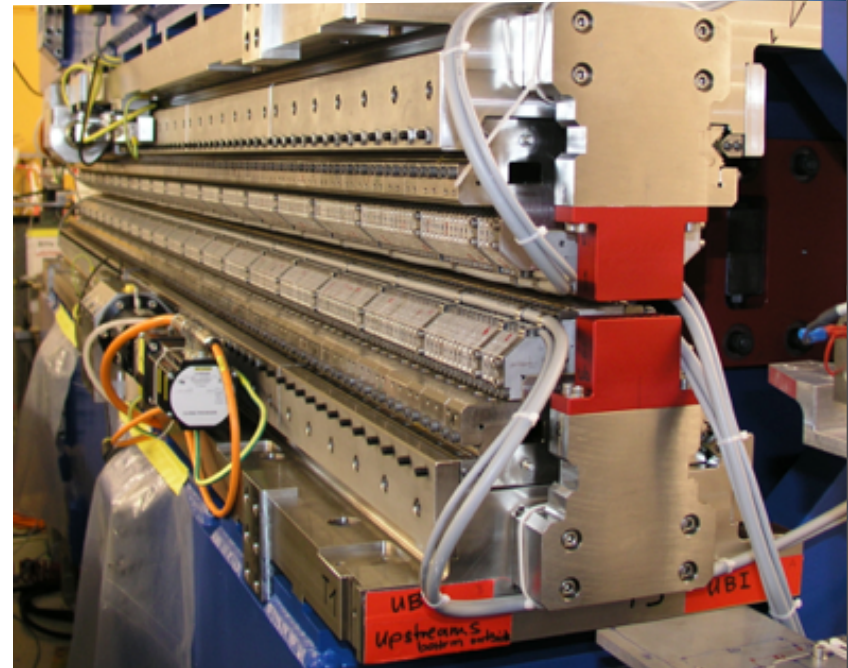
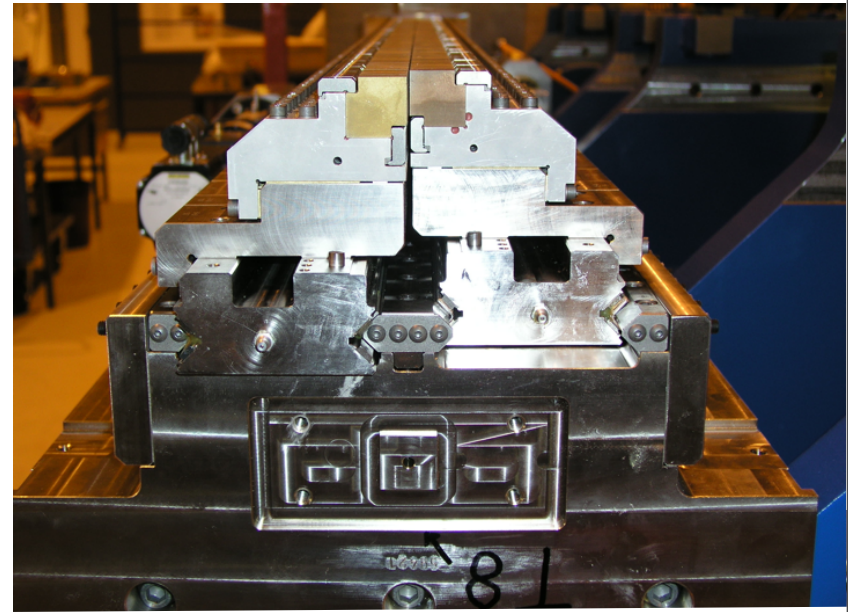
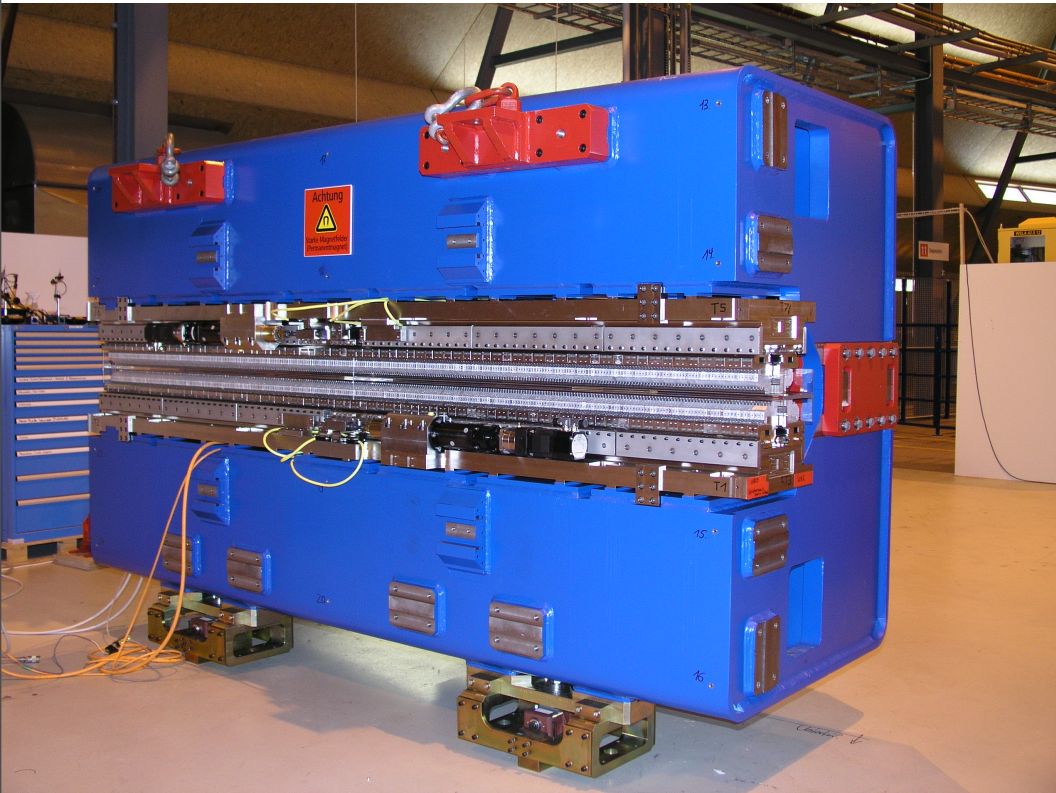
ID	gap
U24	6 - 12 mm
U19	4.5 - 7 mm
U14	4 - 6 mm
	length: 2m

ID	gap
UE56	16 - 70 mm
UE54	16 - 70 mm (up to 28 th harm)
UE44	11.4 mm
	length: 2 - 3.4m

U15, gap > 4mm, length 4m

UE40, gap 6.5mm, length 4m

Undulator Strategy for SwissFEL

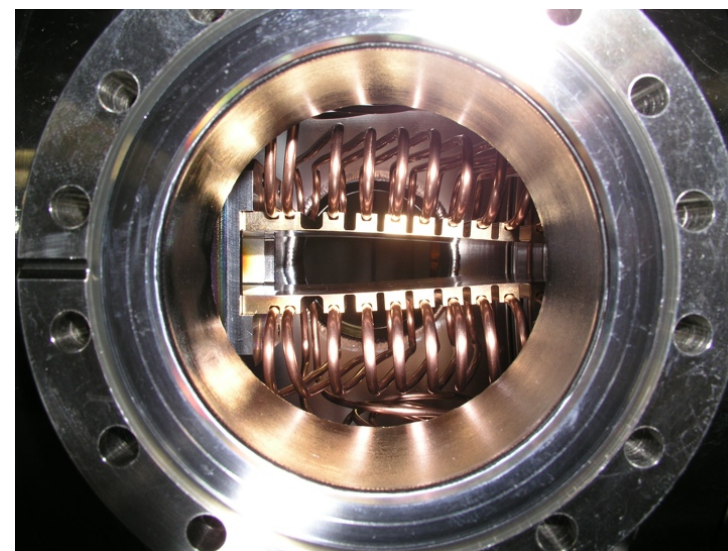
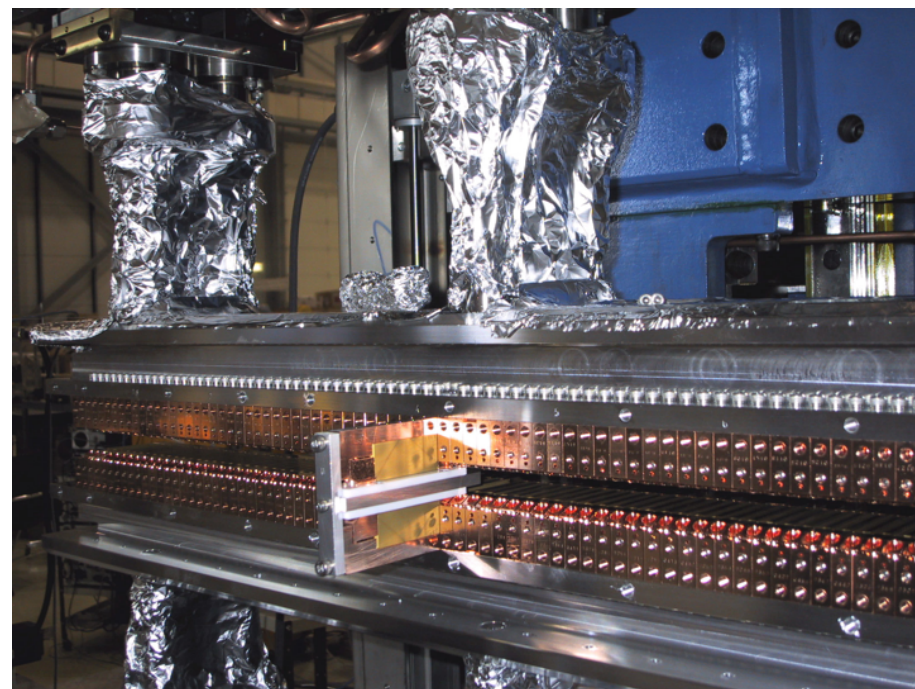
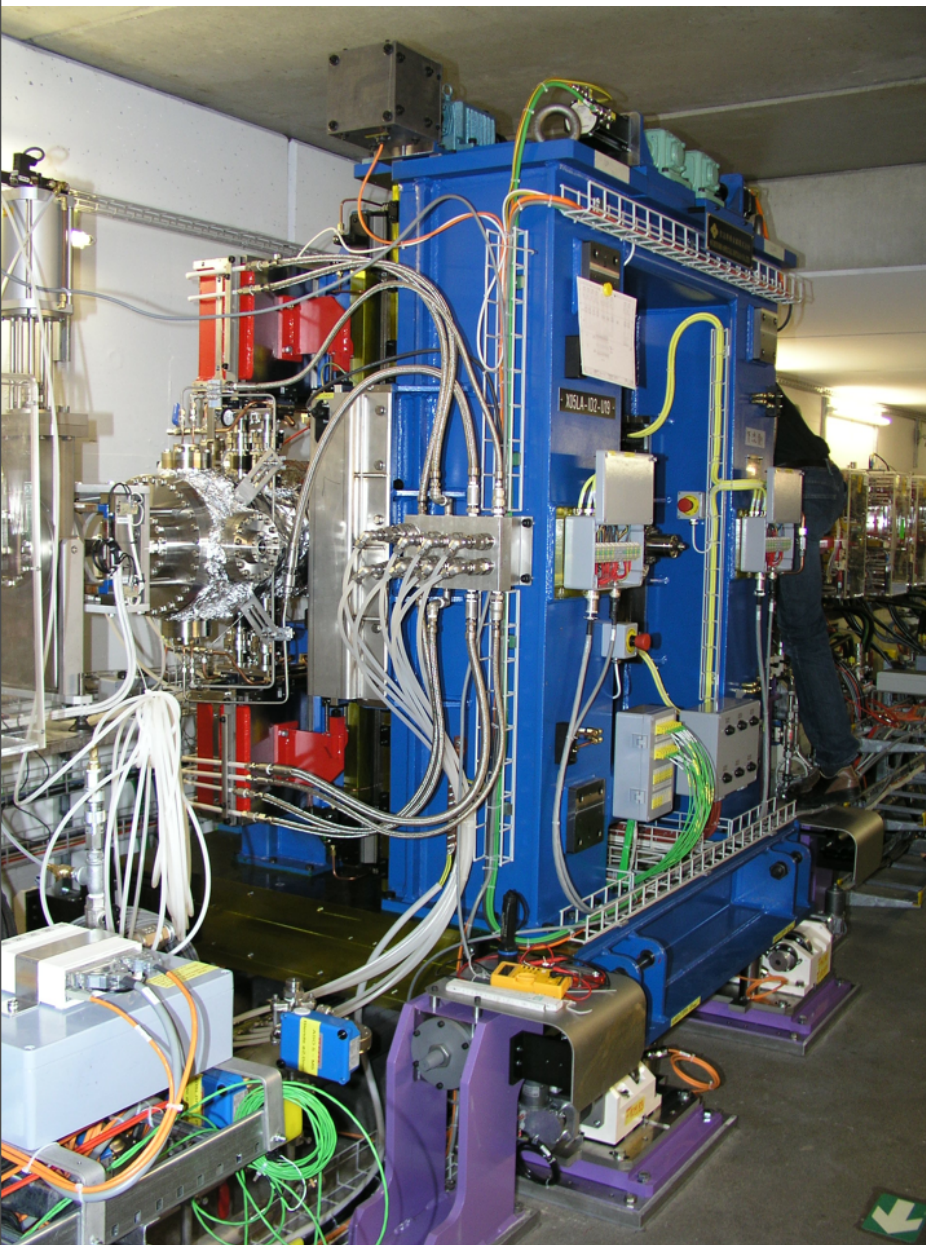


*R. Carr, Adjustable phase undulator, NIM A306, 391 (1991)

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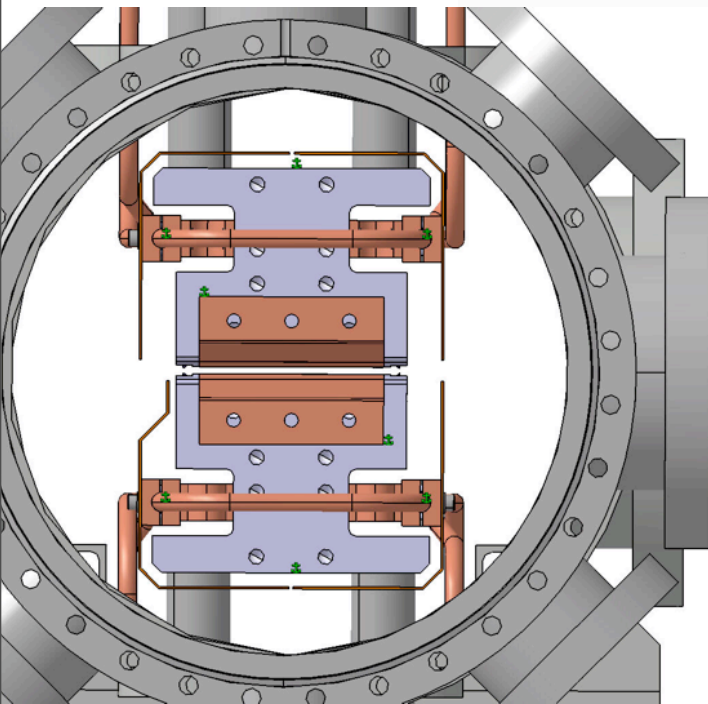
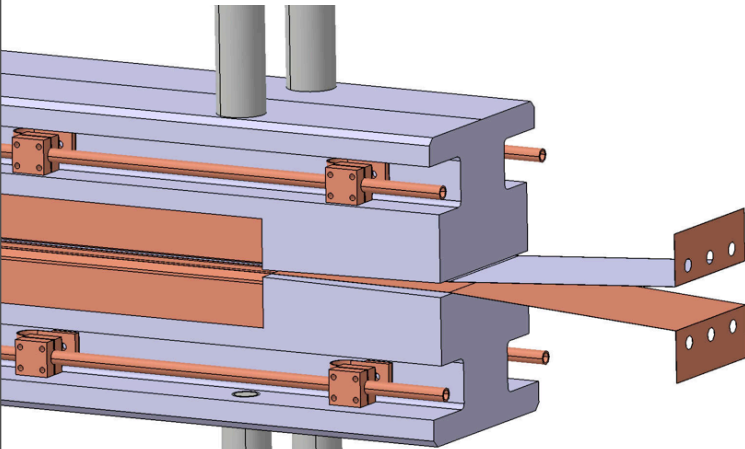
U19 - in vacuum Undulator



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U14 - cryogenic Undulator

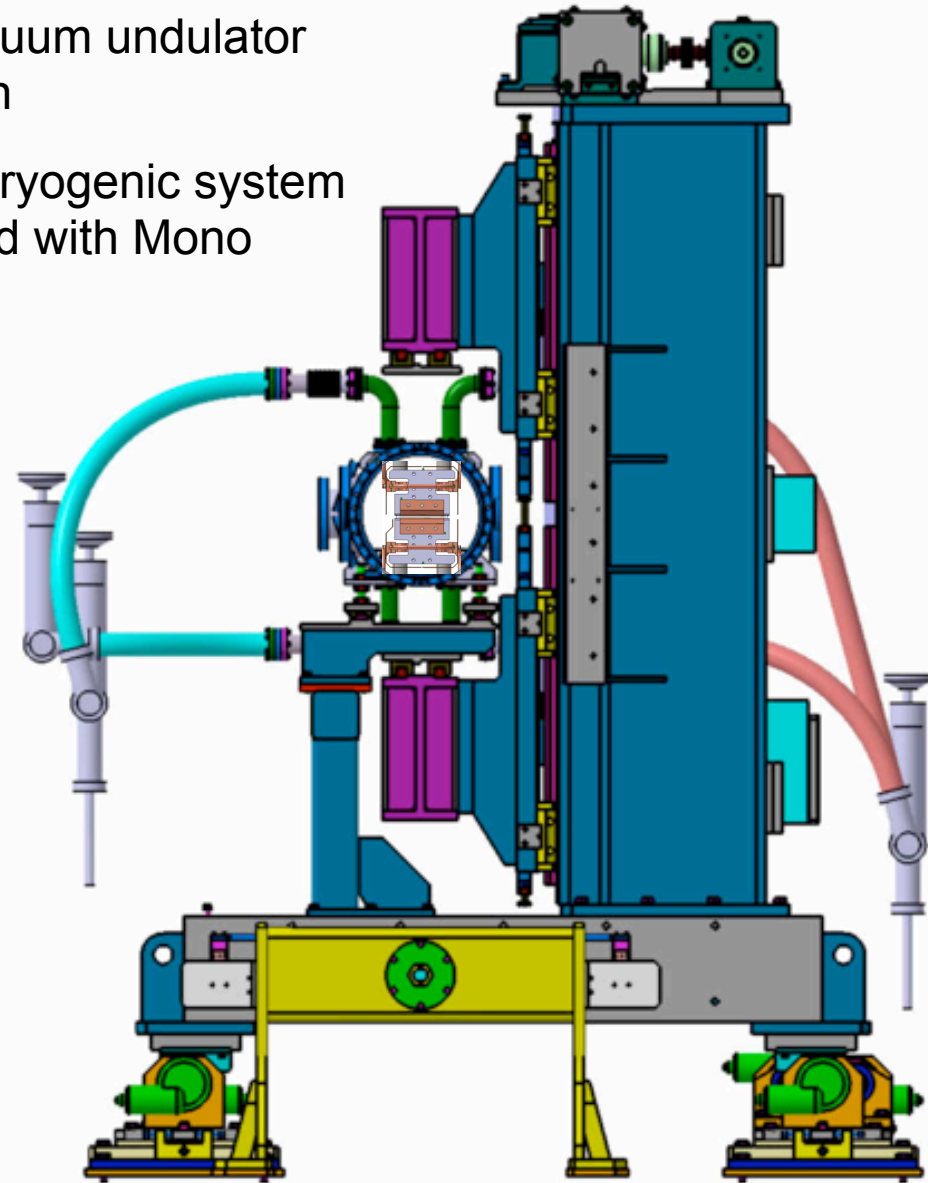


based on standard
in-vacuum undulator
design

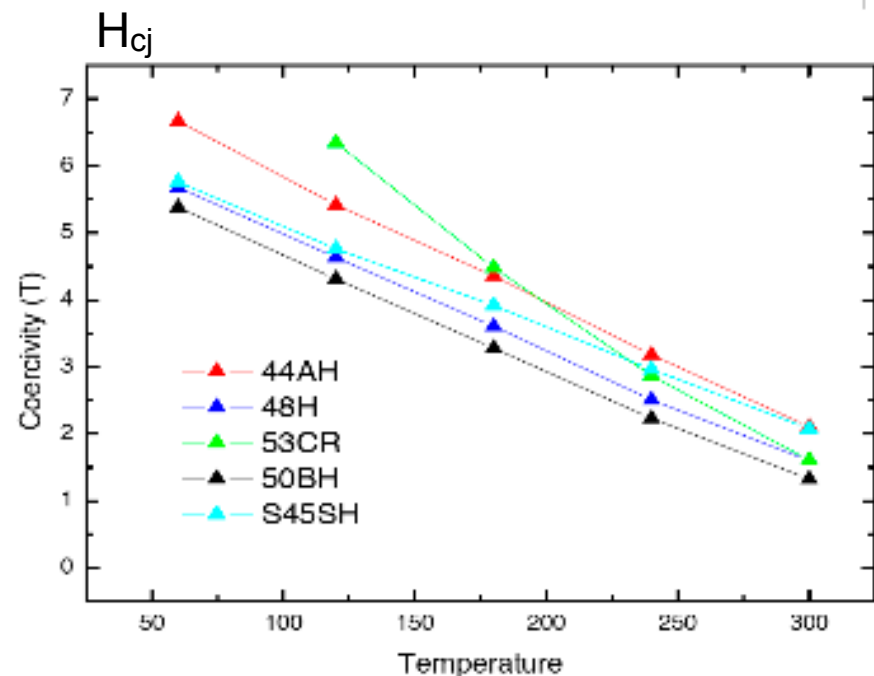
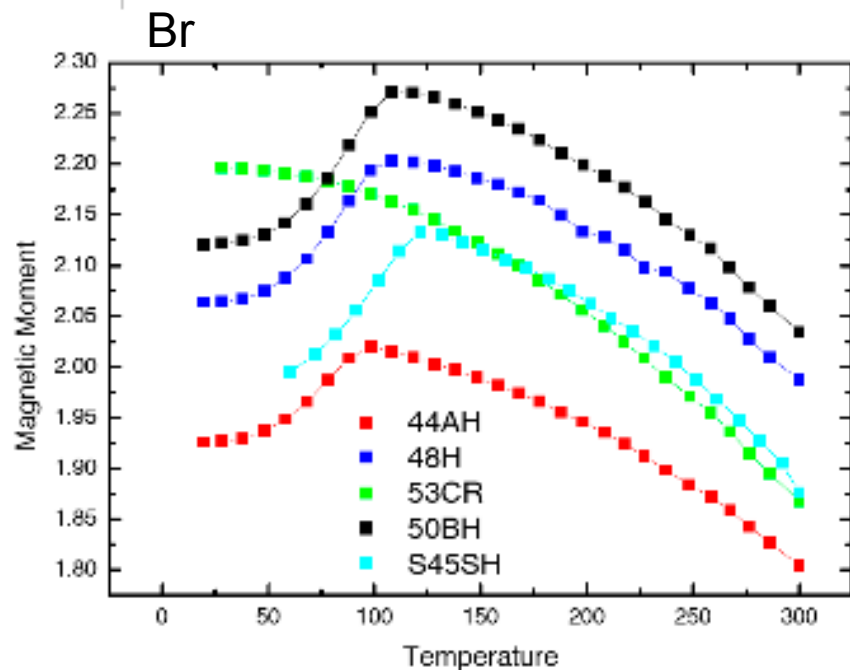
LN2 cryogenic system
shared with Mono



\tilde{z}_y



use dBr/dT and dH_{cj}/dT



high field \Leftrightarrow small period

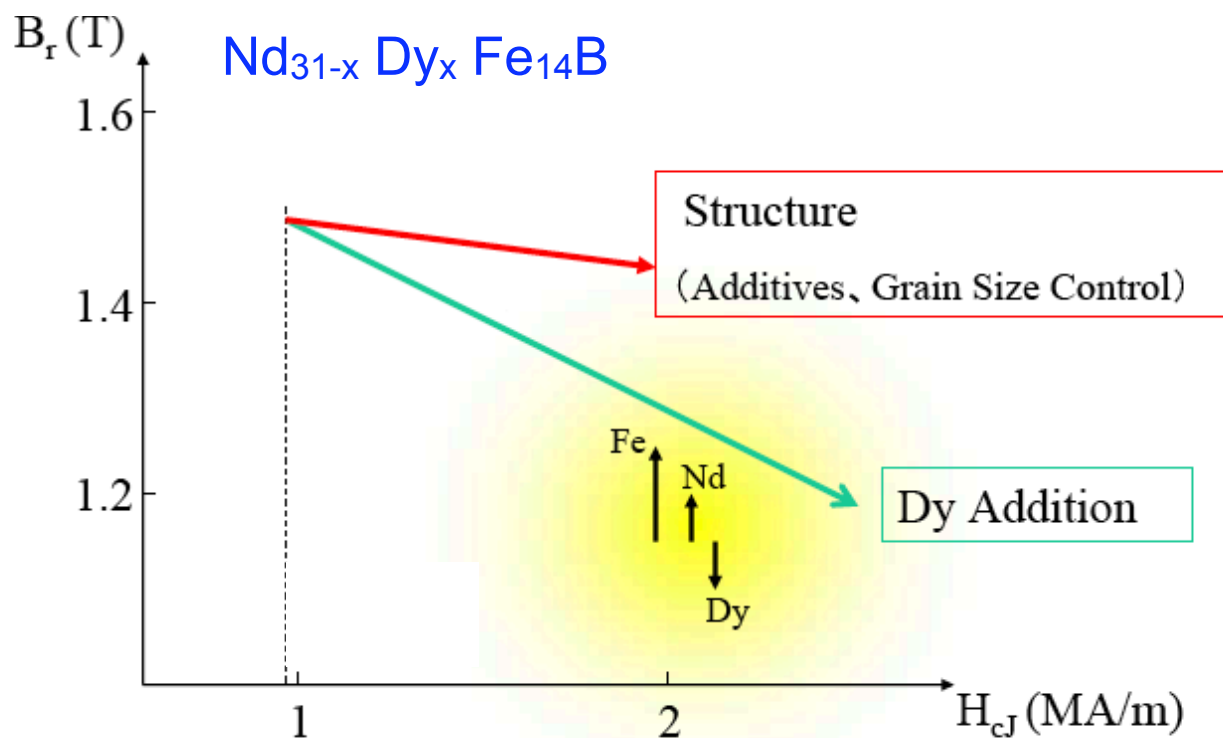
high stability \Leftrightarrow small gaps

CPMU cryogenic permanent magnet undulator

SPring-8 Patent (2003)

2 Undulators (ESRF installed 2008, SPring-8 / PSI (magnetic meas.))

- stabilize magnets by replacement of Nd with Dy ($\text{Dy}_2\text{Fe}_{14}\text{B}$)
increased stability but lower strength (U19: $\text{NdFeB} \sim \text{SmCo}$)



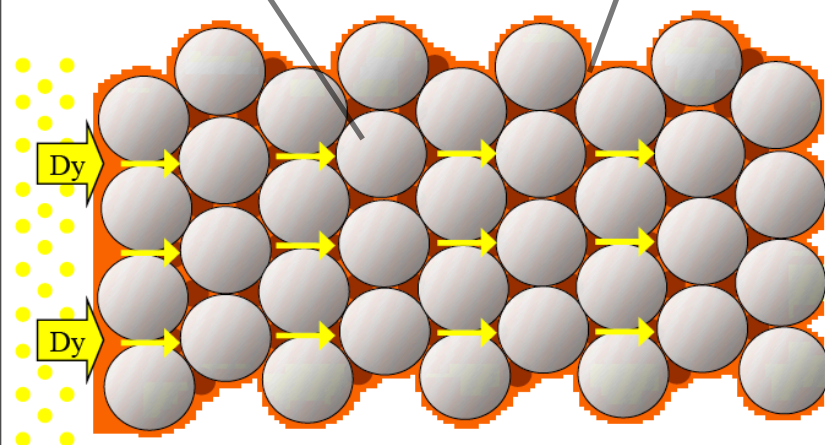
(courtesy of Hitachi Metals Ltd.)

New fabrication technique

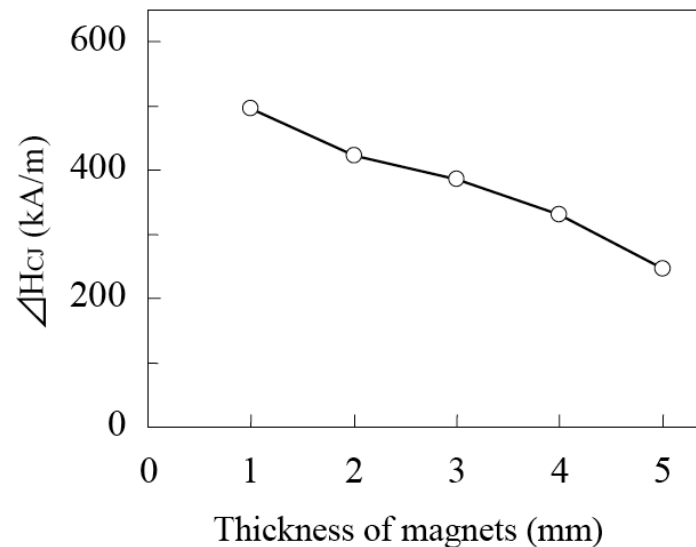
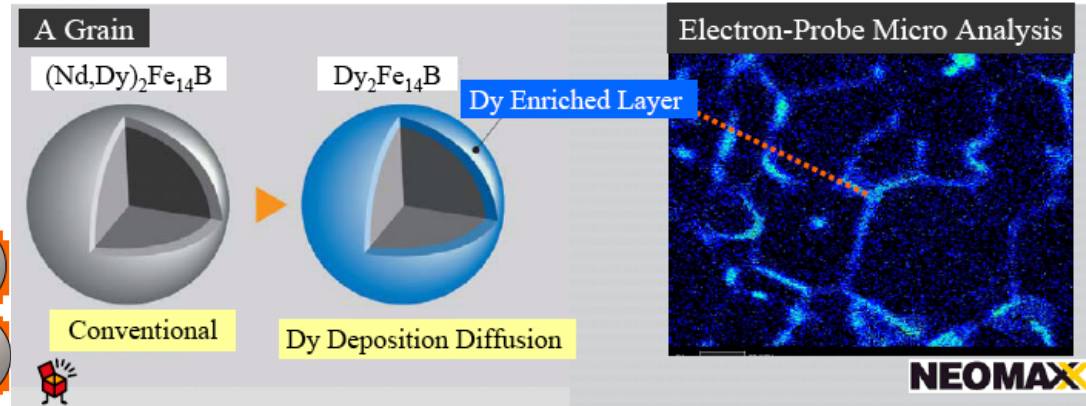
vapor diffusion of Dy into the machined magnet (Hitachi Metals Ltd.)

increase of stabilization without reduction of remanence

main phase crystal grain
grain boundary phase (Nd-rich)

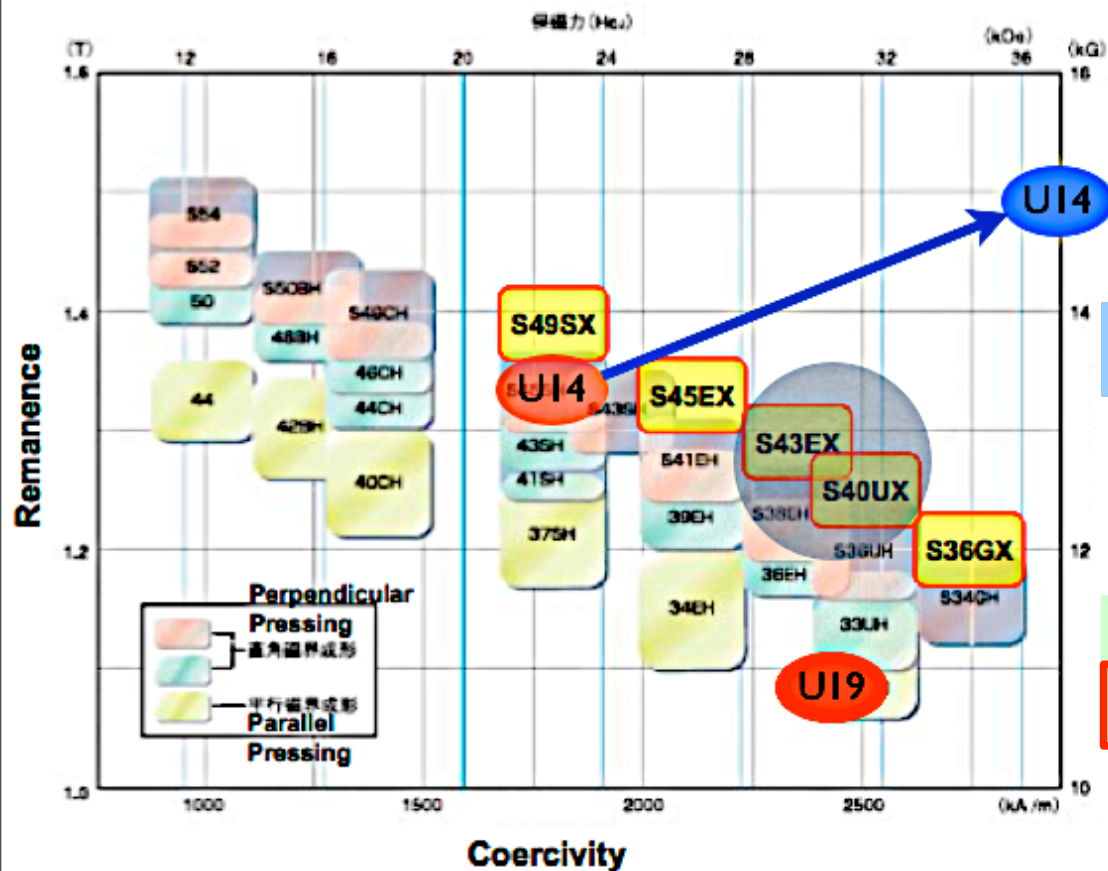


for thin magnets only
(U15 magnets: ~2.25mm)



(all figures courtesy:Hitachi Metals Ltd)

NdFeB grades



Nd₂Fe₁₄Br + Diffused Dy

Material code	Br [T]	Hc _J [kA/m]	Temp Coeff Br [%/°C]	Temp Coeff Hc _J [%/°C]
S49SX	1.36÷1.42	≥1671	-0.11	-0.55
S45EX	1.30÷1.36	≥1990	-0.10	-0.50
S43EX	1.26÷1.32	≥2228	-0.10	-0.48
S40UX	1.22÷1.28	≥2387	-0.10	-0.47
S36GX	1.17÷1.23	≥2626	-0.09	-0.44

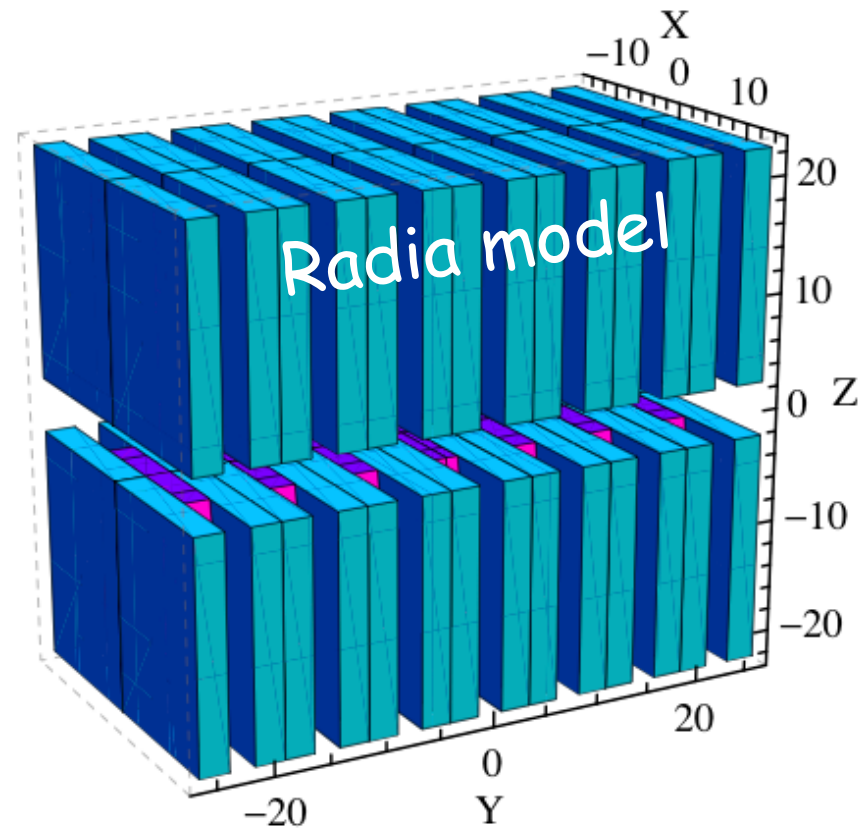
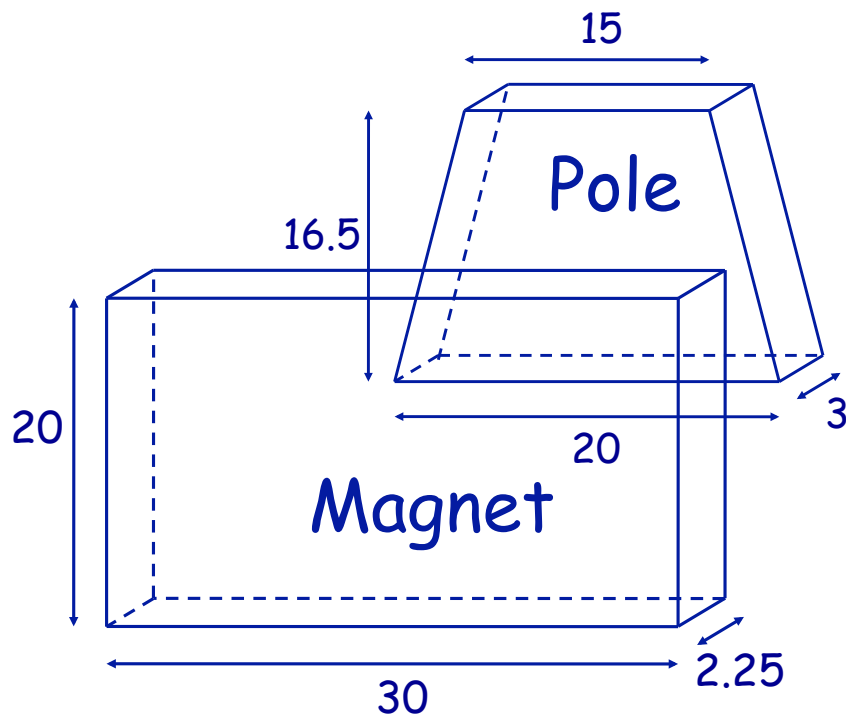
courtesy Hitachi Metals Ltd.

NdFeB grade for SwissFEL U15

Type	Hybrid - In Vacuum				
# units	12				
Period	15				mm
# periods	266 (including ends)				
Magnetic length	3990				mm
K-values	1.8	1.4	1.2	1.0	-
GAP	3.2*	4.2	4.7	5.5	mm
Bz max	1.27	1	0.85	0.7	T
Br	1.25				T
Hc _J	>2400				kA/m
Magnet size	WxHxT=30x20x2.25				mm
Pole size	Wb/WtxHxT=20/15x16.5x3				mm
Max GAP	20.0				mm
ΔGAP	0.3				μm

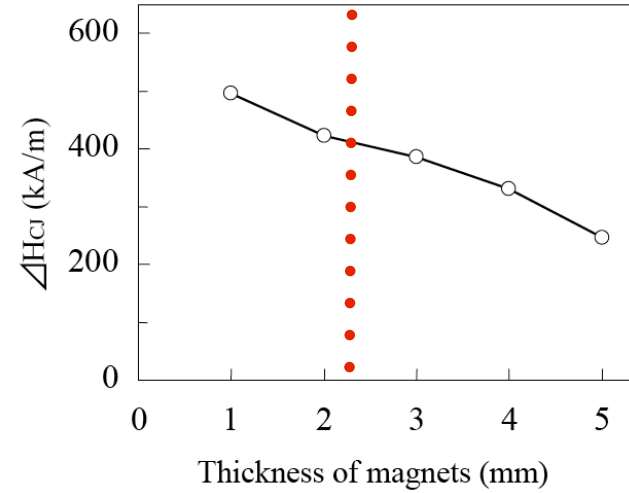
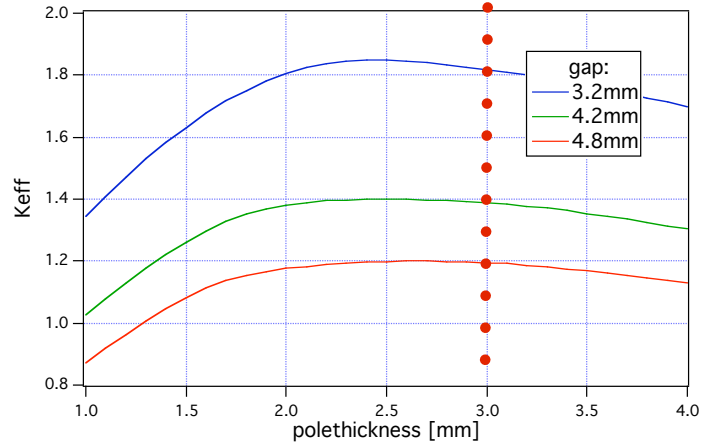
*Minimum magnetic GAP (Vacuum GAP=3mm)

- K-value (B)
- Good field region $\Delta B/B < 10^{-4}$
- Magnetic forces
- Cost \rightarrow material



Polethickness: 3.0mm

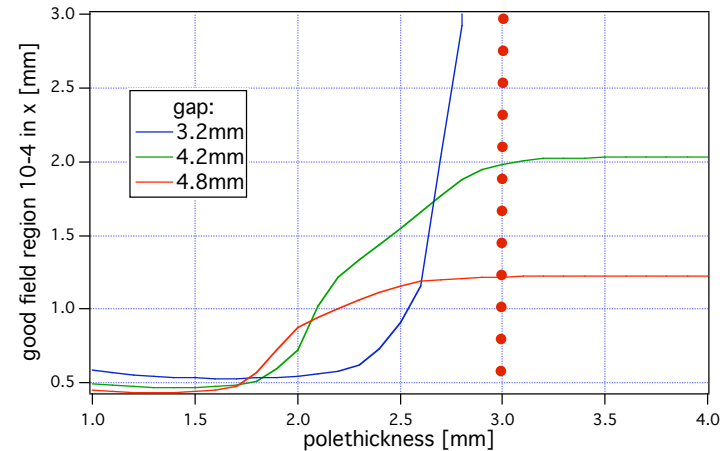
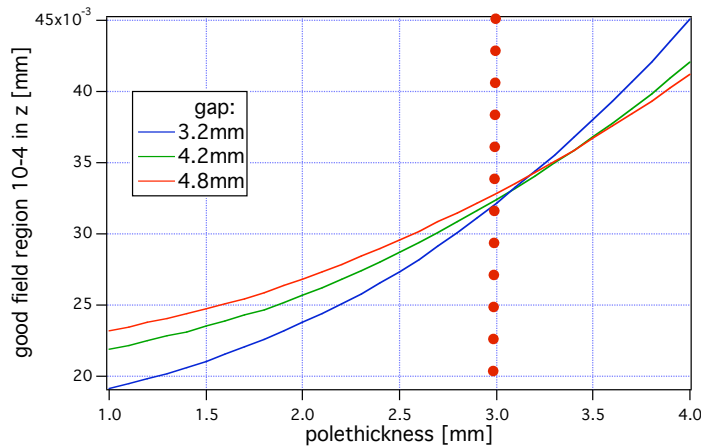
Magnet: 4.5mm (2 x 2.25mm)

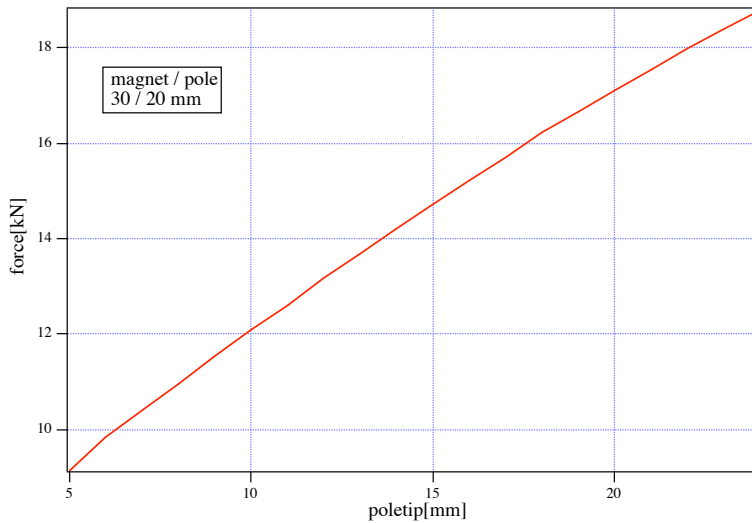
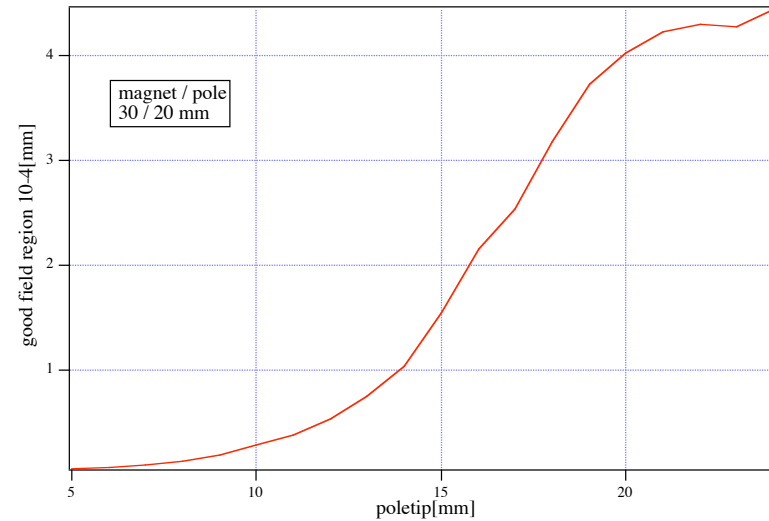
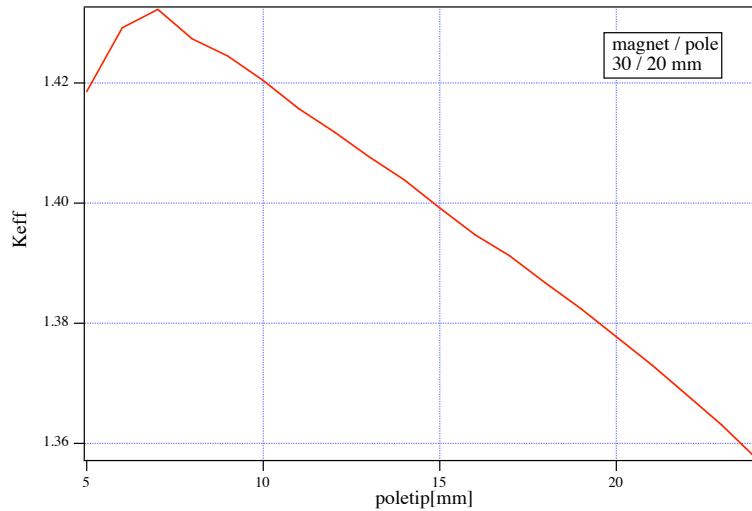


diffused Dy:
increase in
coercivity

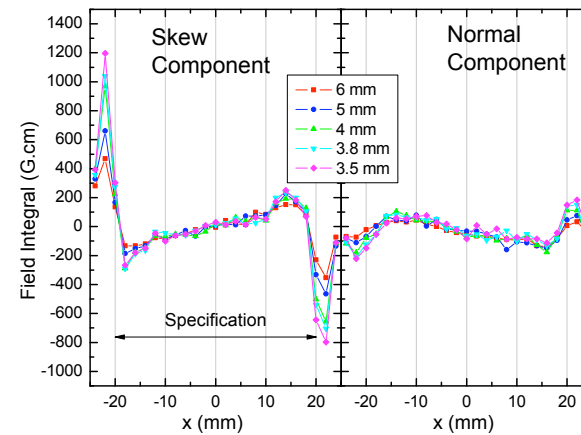
courtesy
Hitachi Metals Ltd.

good field region:



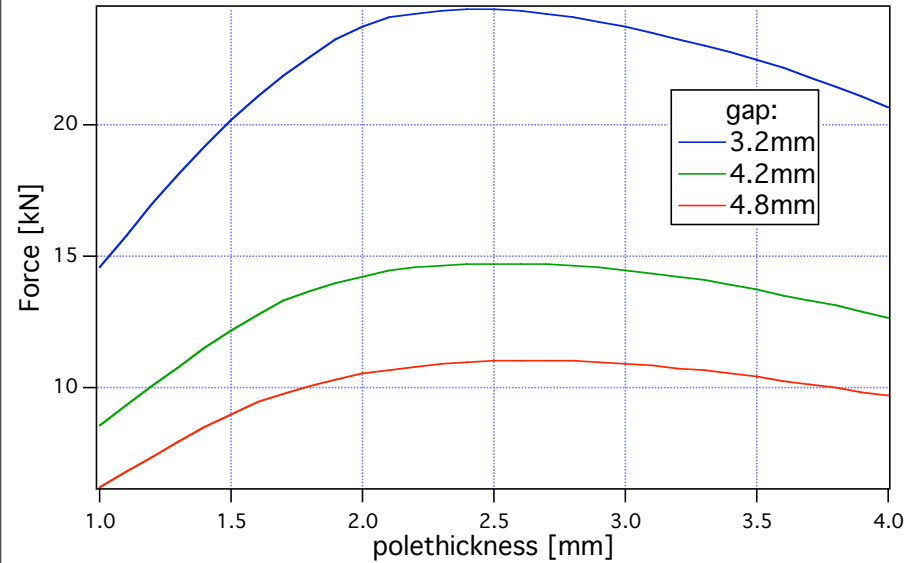
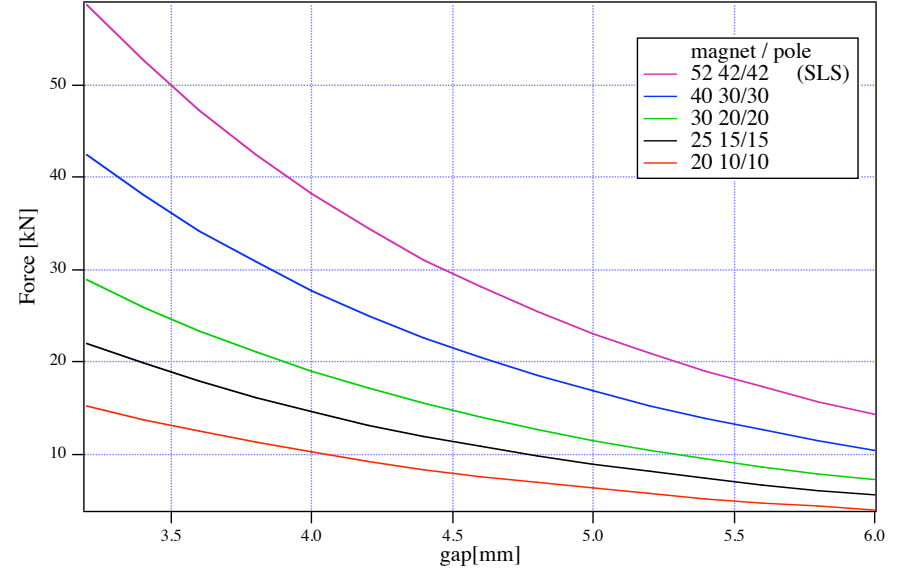
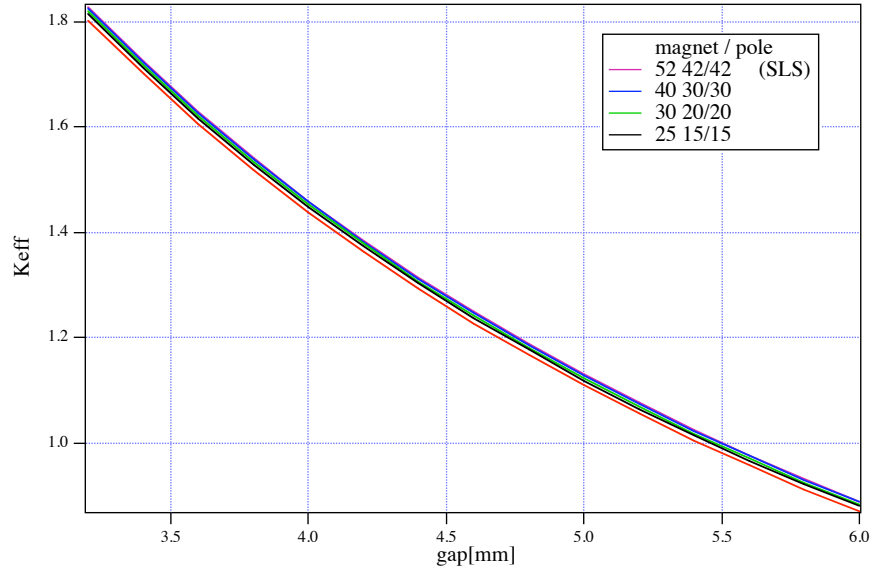


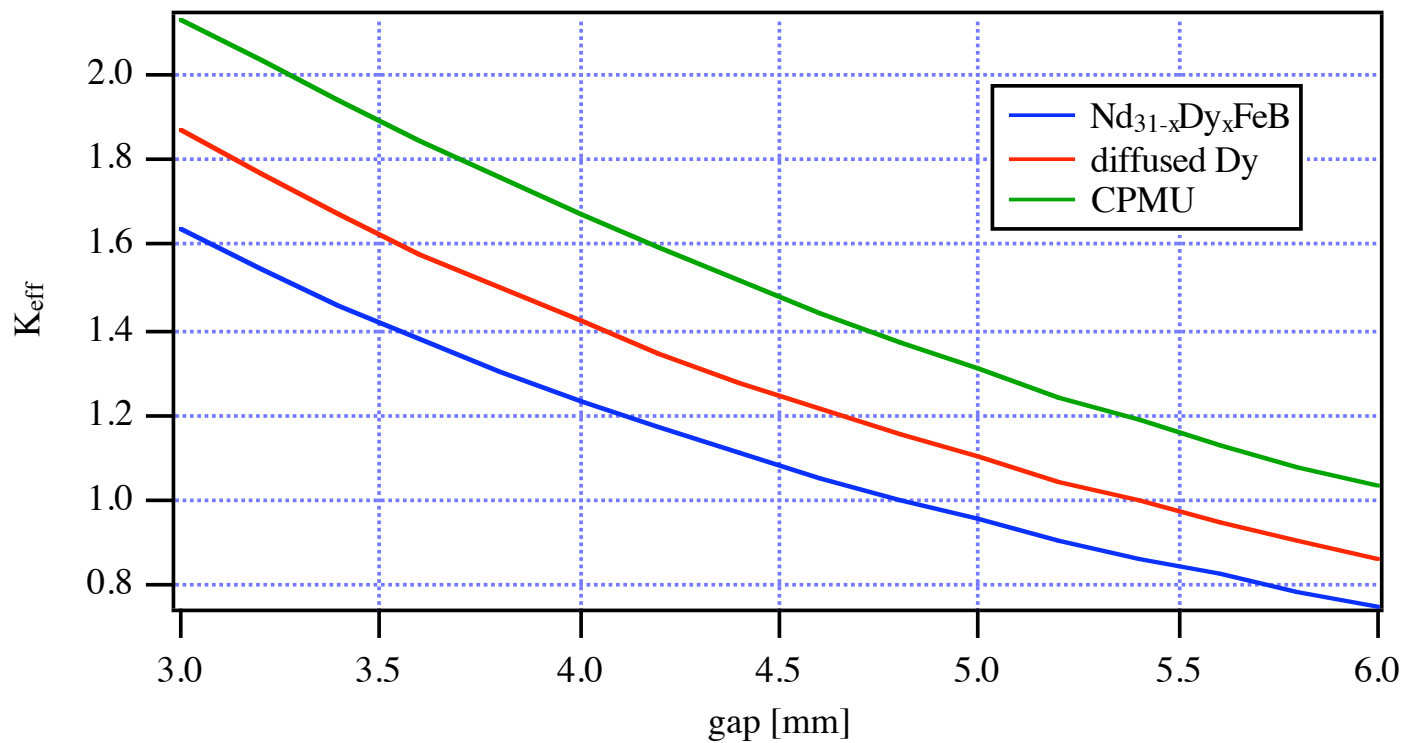
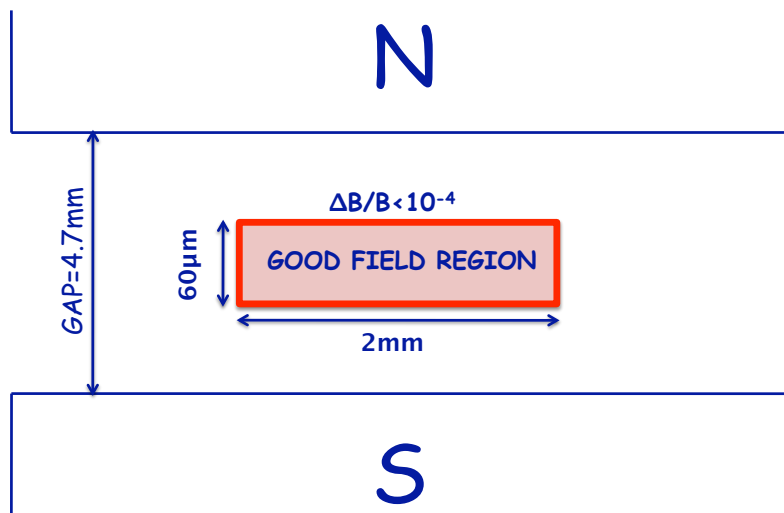
Minimum polewidth:
 good field integral region for U14: ± 18 mm with pole width 42mm
 critical to control magnetic field at the magnet/pole edges
 ➔ U15 with pole tip 15mm: field control ± 5 mm



SLS
CPMU14

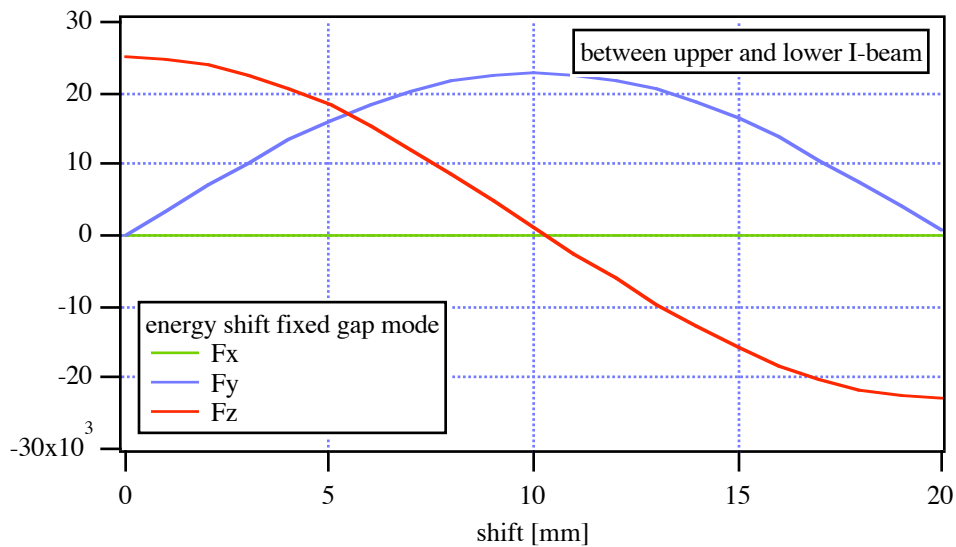
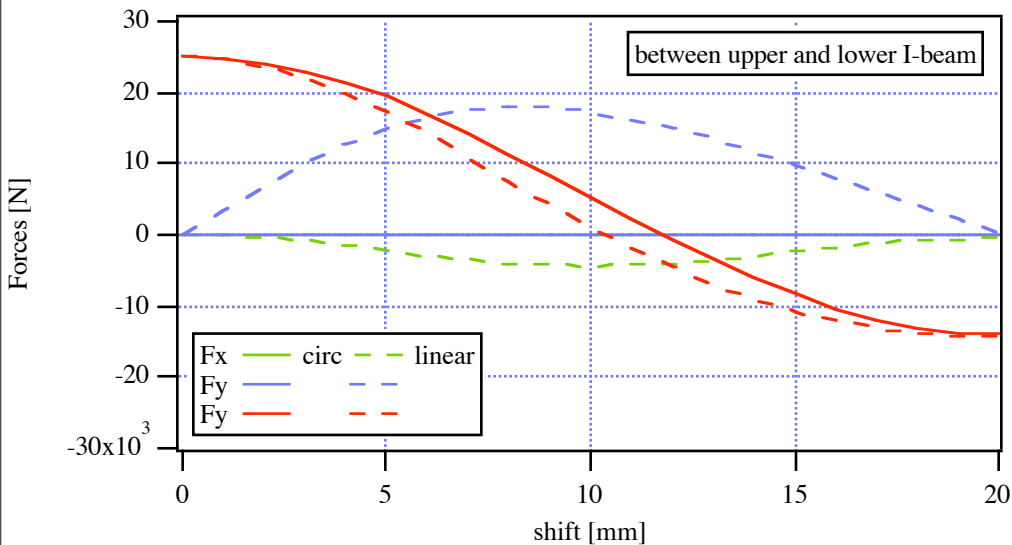
Magnetic Forces





Soft x-ray Undulator zoo (draft)

name	UE40	UE60	U60	U100	U110H	
period	40	60	60	100	110	mm
gap (magnetic)	6.5 (8) - 24	8 - 40	8 - 40	9 - 27	7 -	
K	3.5 - 0.9	5.2 - 0.9	5.2 - 0.9	15.2 - 4.8		mm
gap (vacuum)	5 × 10	6 × 12	6 × 12	8 × 16	6 × 12	mm
gap variation	32	32	32	32	32	mm
open gap / Kmin ²	38.5 / 0.3	40 / 0.86	40 / 0.9	41 / 2.5		
magnet size	20x20x10	20x20x10	40x20x10	40x25x40	30x30x25	mm ³
pole size	-	-	-	20x25x35	-	
remanence	1.08	1.08	1.08	1.25	1.25	T
Bz / Bx	0.94 / 0.81	0.8 / -	0.8 / -	1.63 / -	- / 1.41	T
Kz / Kx	3.5 / 3.0	3.2 / -	3.5	15.2 / -	- / 14.5	
type	APPLE II	APPLE II	PPM 4 × 1	Hybrid	APPLE II LV fixed	
units	6	2	1	2	1	
unit length	4	4	4	4	4	m
number of periods	98	64	64	38	35	



Magnets for UE40 / UE60

	Sm ₂ Co ₁₇	NdFeB		
grade		standard Dy	diffused Dy	CPMU
radiaton hard	yes	yes		
Br [T]	1.1	1.08	1.25	1.5
dB/dT [%/K]	-0.035	-0.1	-0.1	flat top
permeability	1.01/1.04	1.06/1.15		
mech. prop.	brittle	good		
suitable for	UE40	UE40	U15	U15

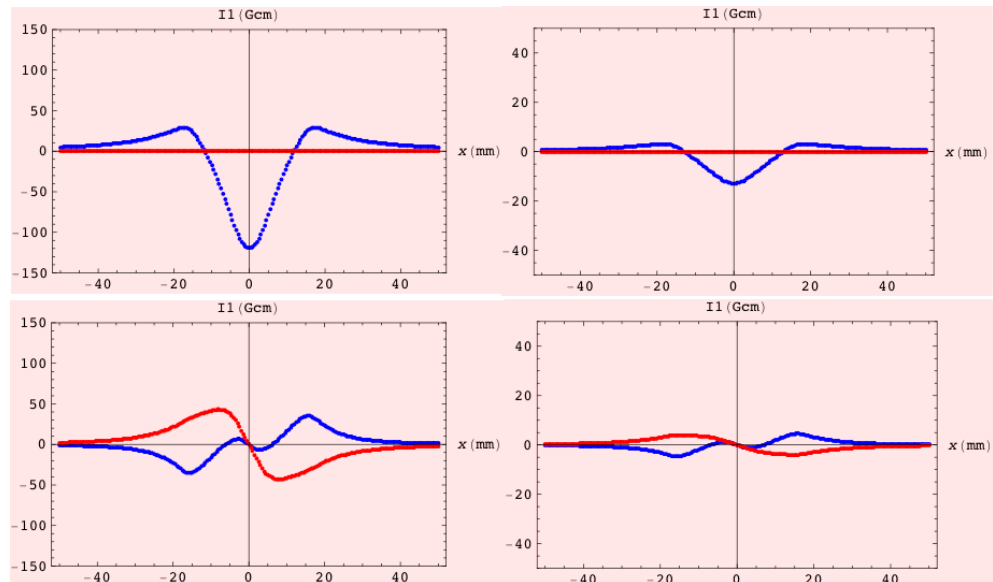
Sm₂Co₁₇ is an alternative

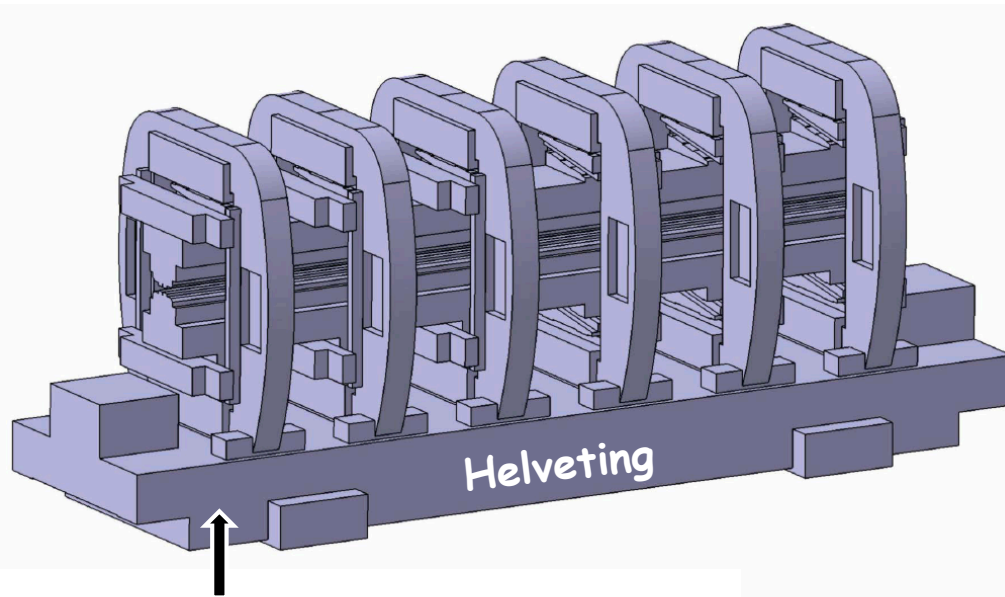
dB/dT
less nonlinearities

smaller permeability
causes lower shift dependent
field integral errors

NdFeB

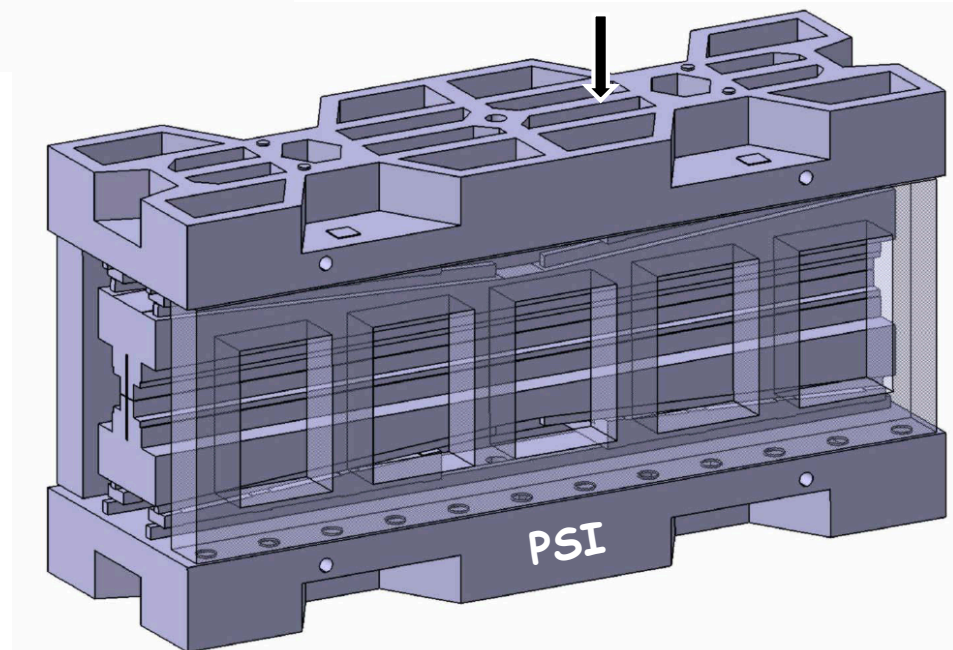
Sm₂Co₁₇

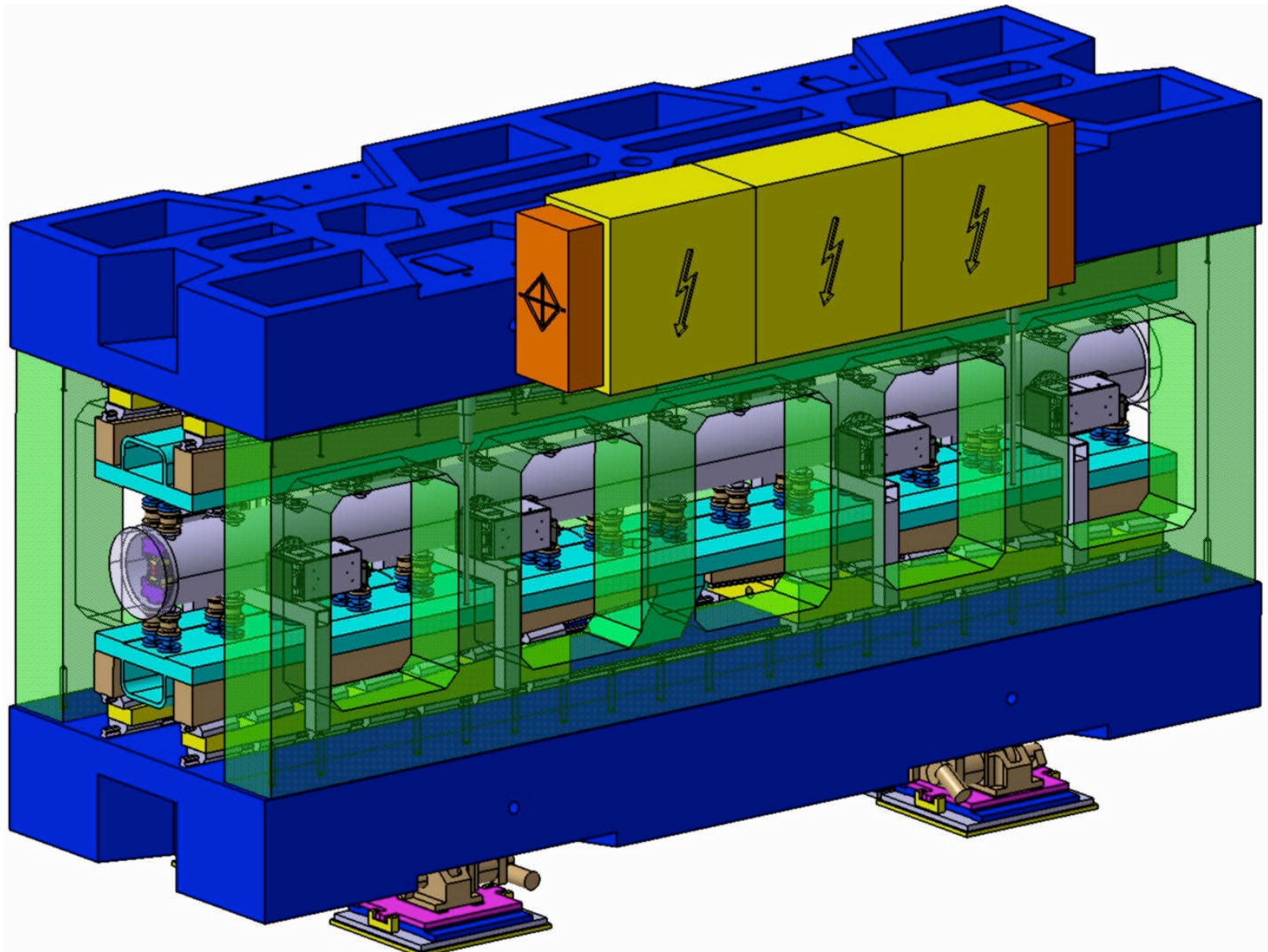




frame (base&sides) cast mineral
 gap drive wedges with 4 motors
 nearly full support of I-beam
 gap change due to load: within
 $3\mu\text{m}$ (CATIA FEM single model
 only further studies required)
 precise gap settings of 1G
 ($0.3\mu\text{m}$)

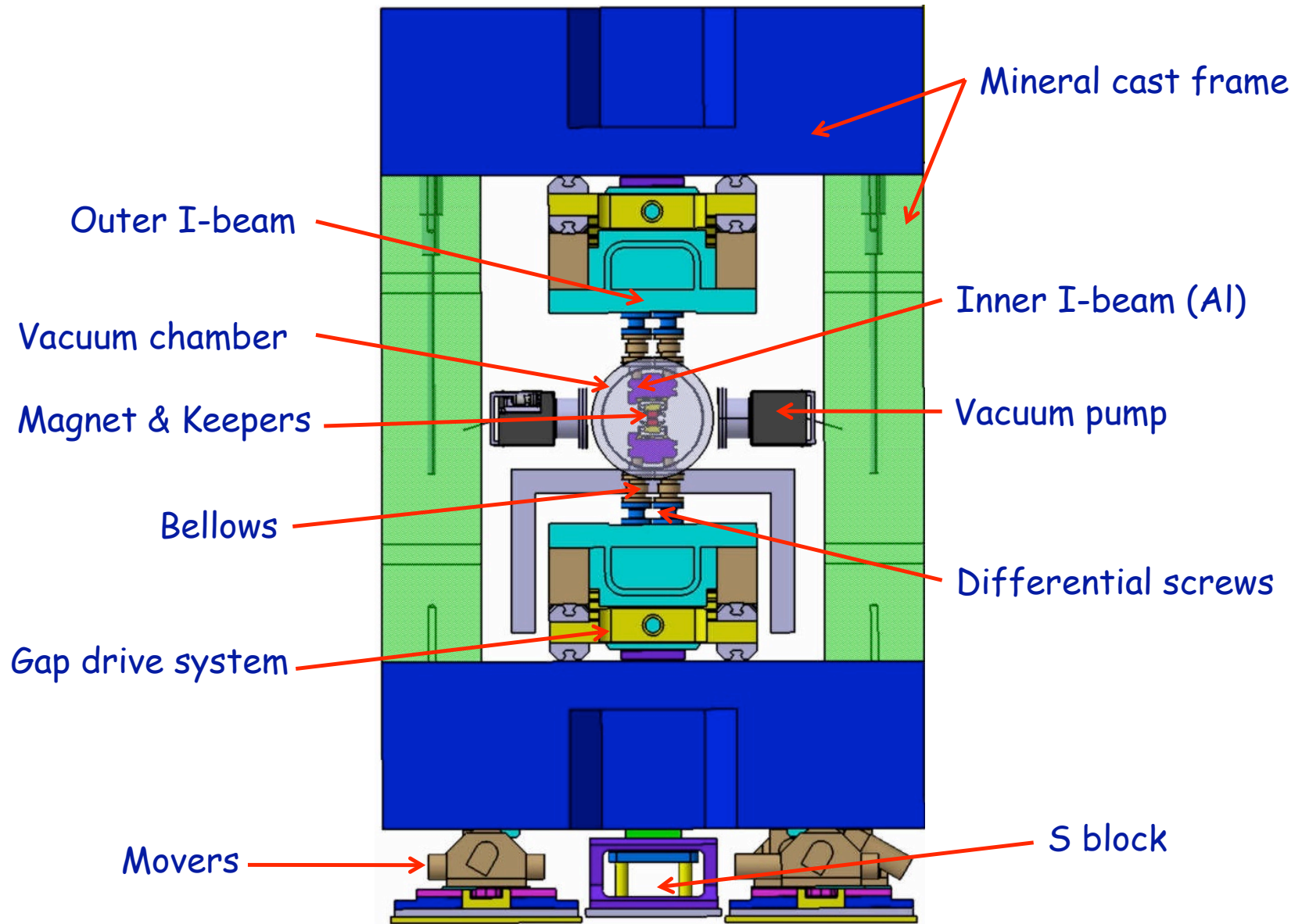
Base: cast mineral
 Windows: cast iron
 Gap drive: 12 motorized wedges
 pro: active correction of the bendings
 due to complexity in drive system
 (number of motors / encoder units only
 the choice if active correction really
 needed
 for use with APPLE II longitudinal
 reinforcement required (then similar to
 PSI)





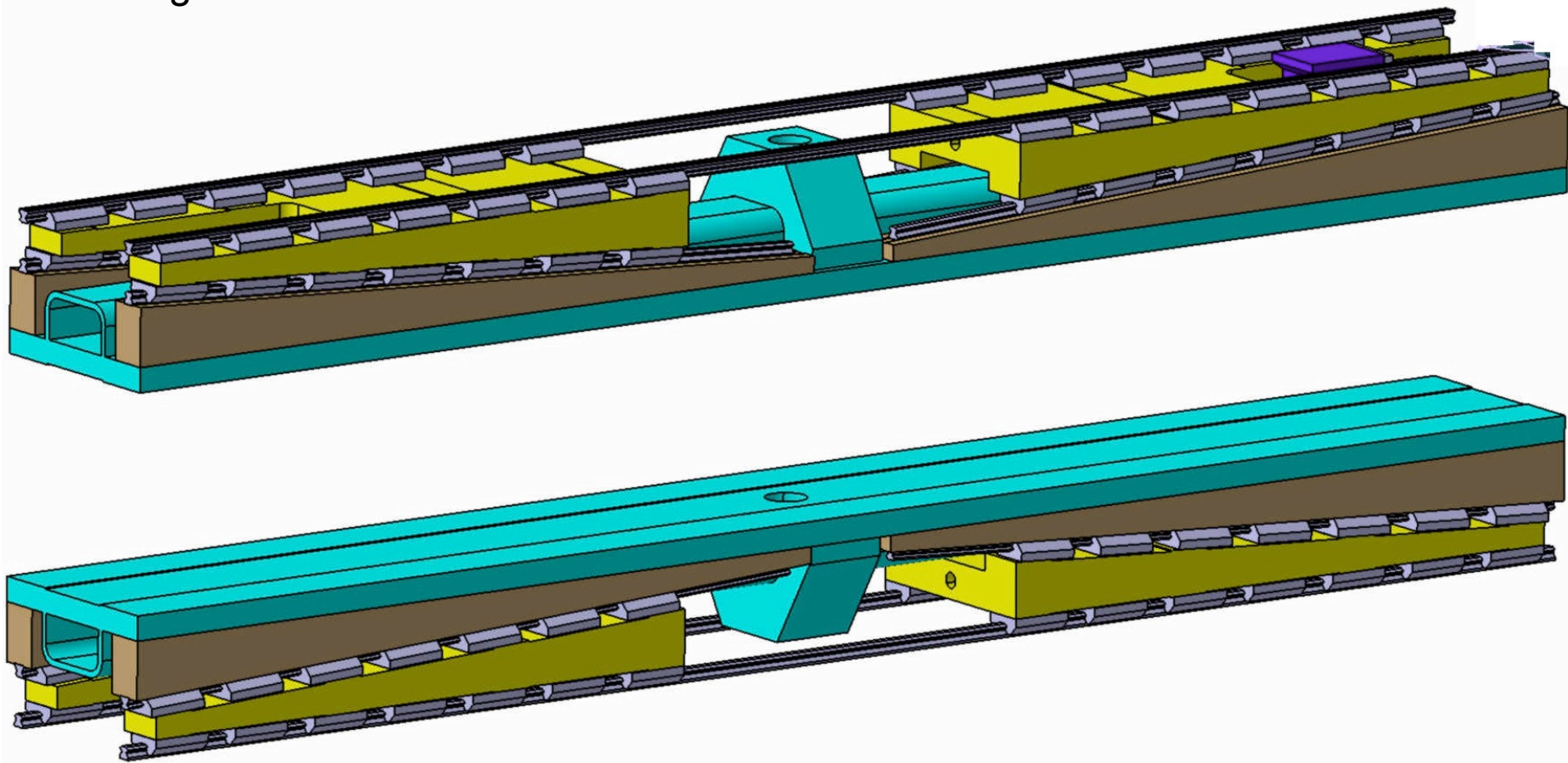
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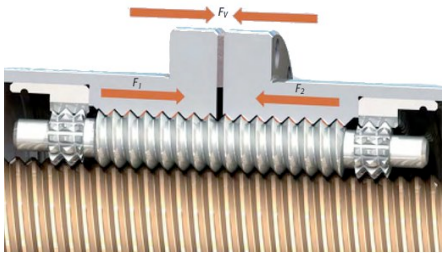
Gap drive based on wedges

to transfer the stiffness of the
lower girder to the I beam

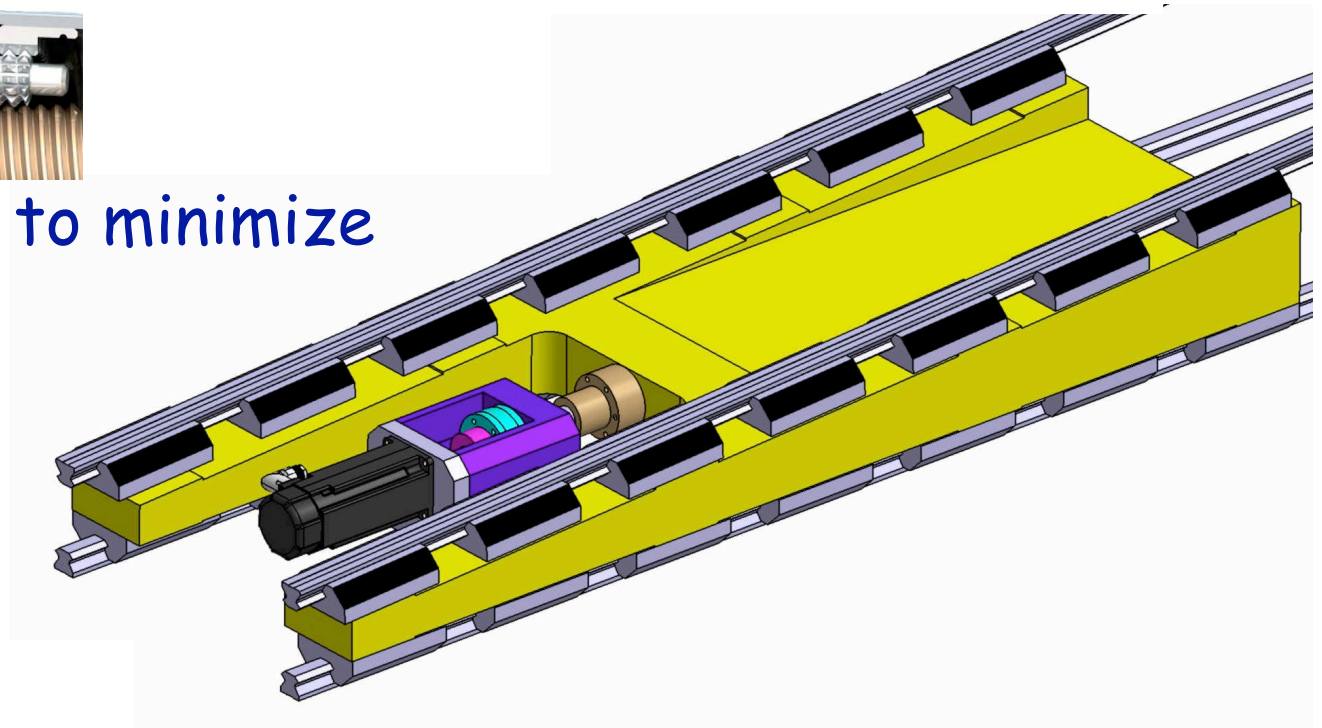
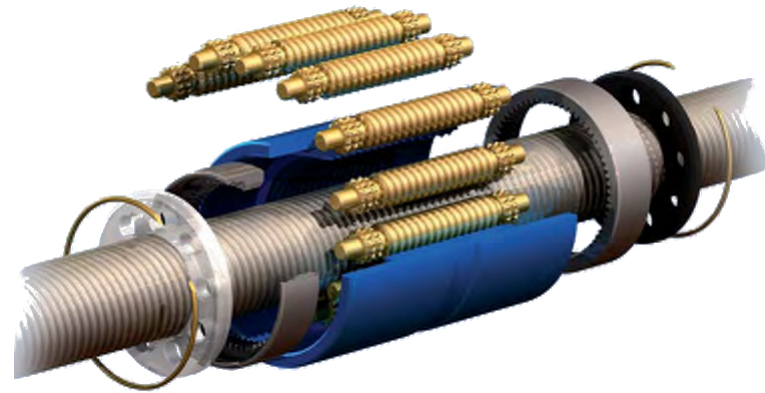


all wedges have to be machined
together!

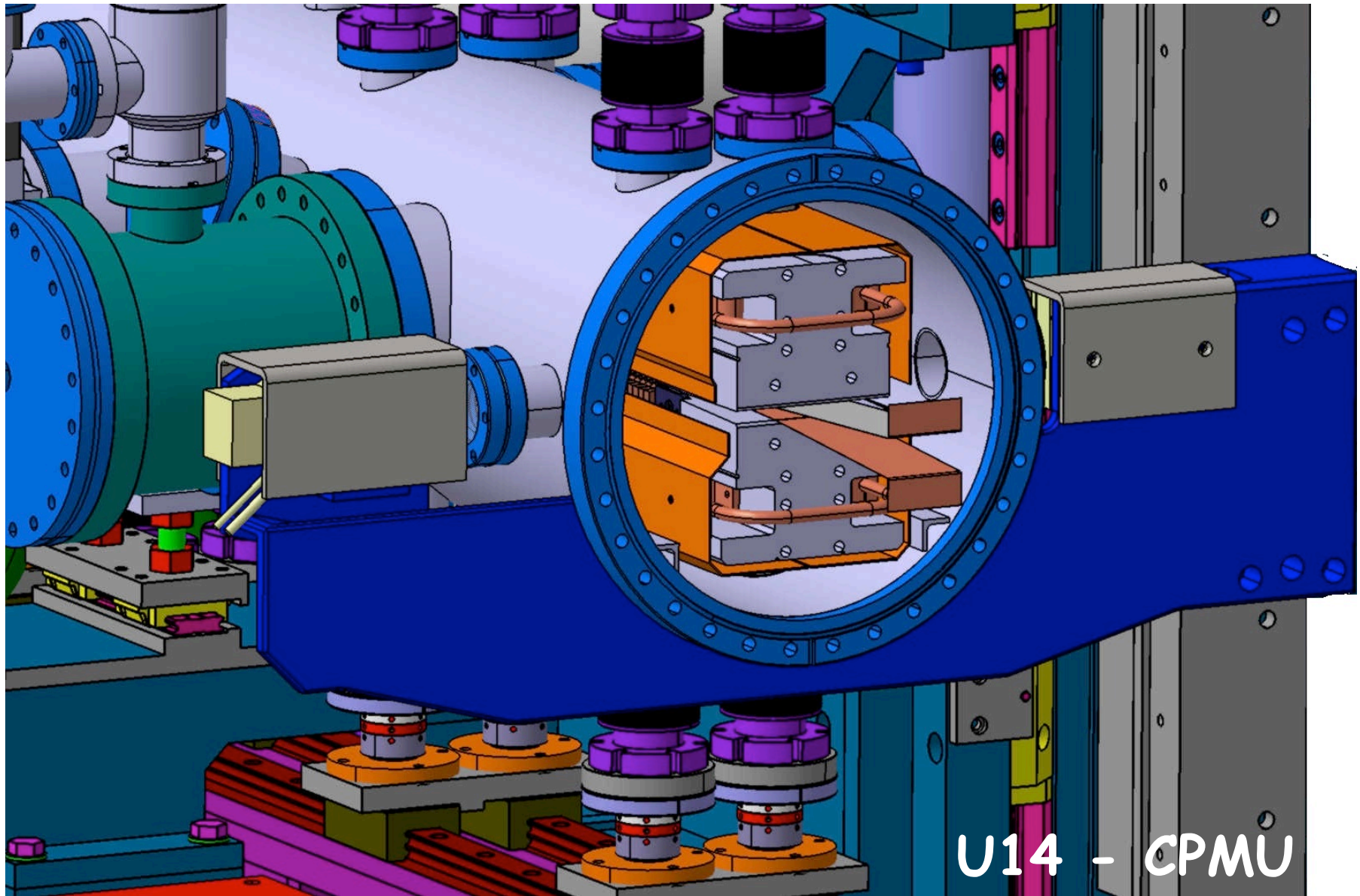
Satellite roller screws
 1mm/turn \rightarrow
 no need for gearbox!



Pre loading to minimize
 backlash



Gap measurement (optical)



U14 - CPMU

Gap measurement (optical)

3 Models

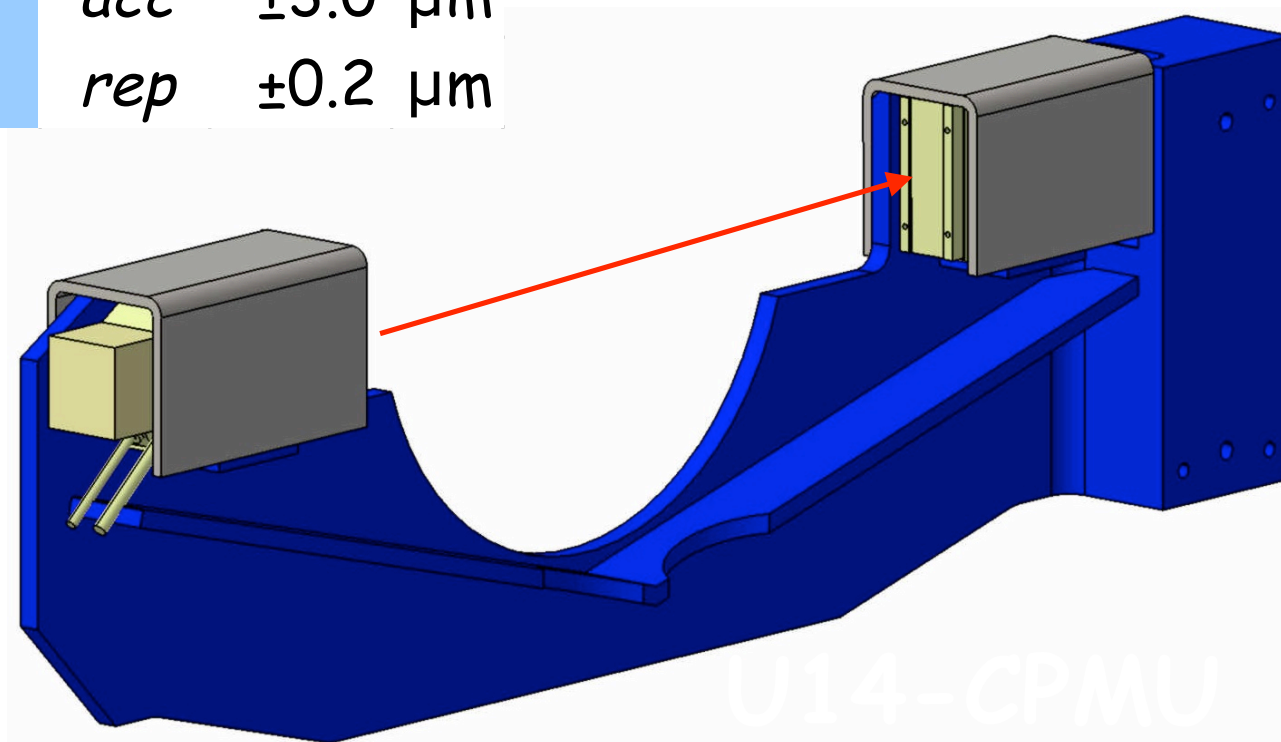
"6mm"

acc $\pm 0.5 \mu\text{m}$ *rep* $\pm 0.06 \mu\text{m}$

"30mm"

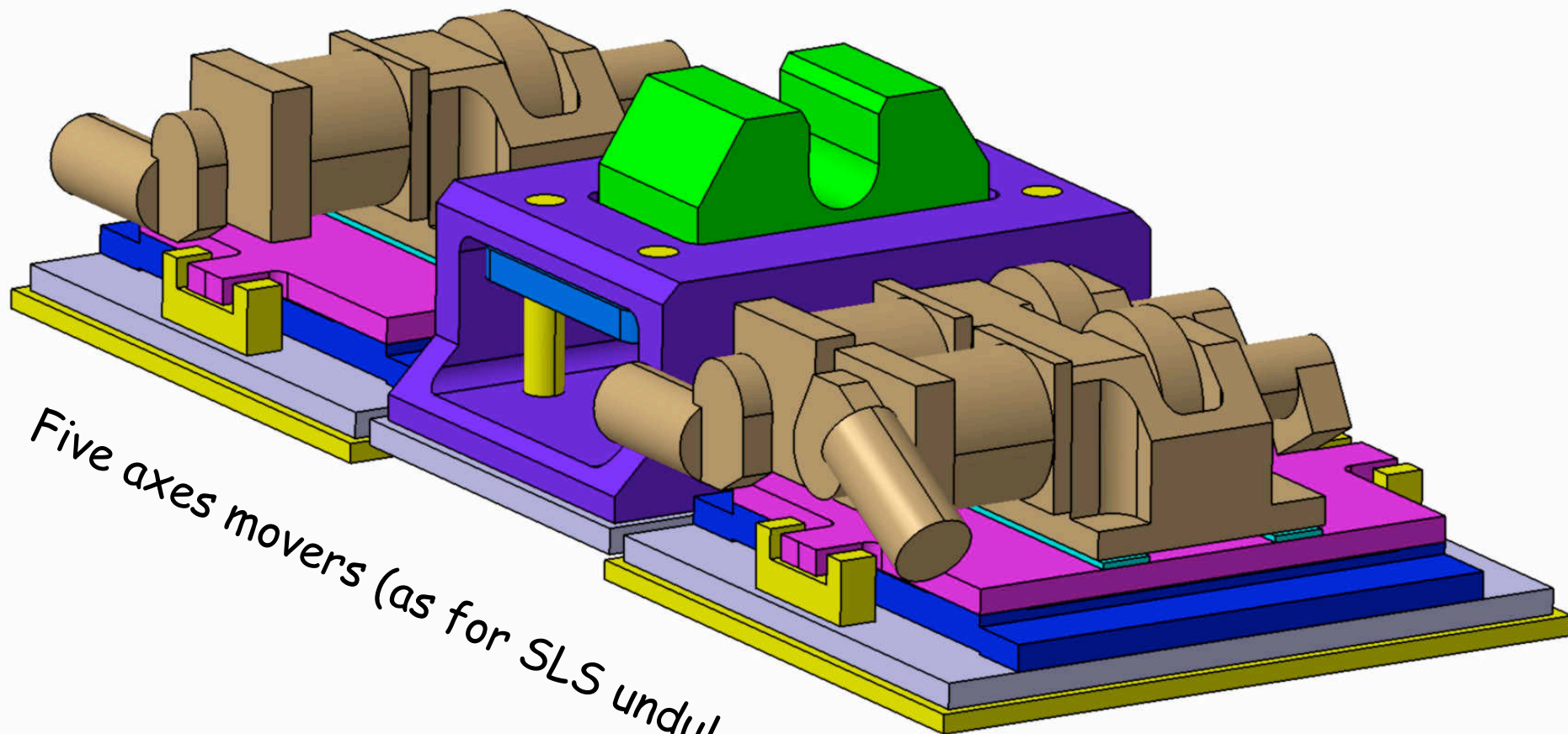
acc $\pm 2.0 \mu\text{m}$ *rep* $\pm 0.15 \mu\text{m}$

"65mm"

acc $\pm 3.0 \mu\text{m}$ *rep* $\pm 0.2 \mu\text{m}$ 

Cam-shaft mover (Stanford)

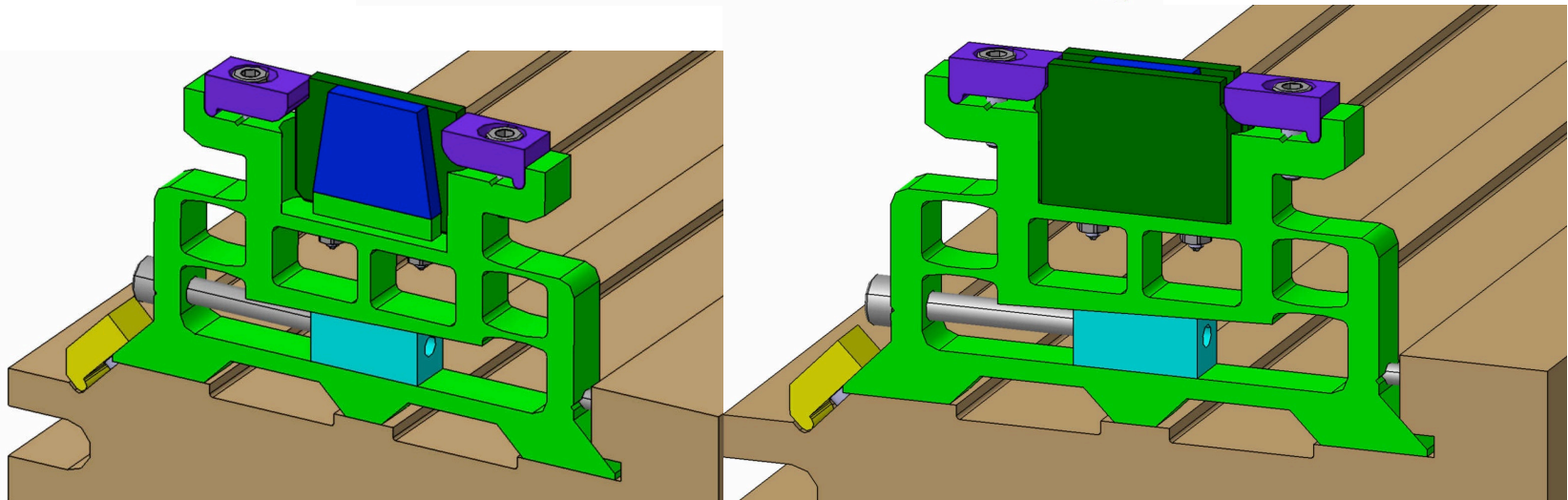
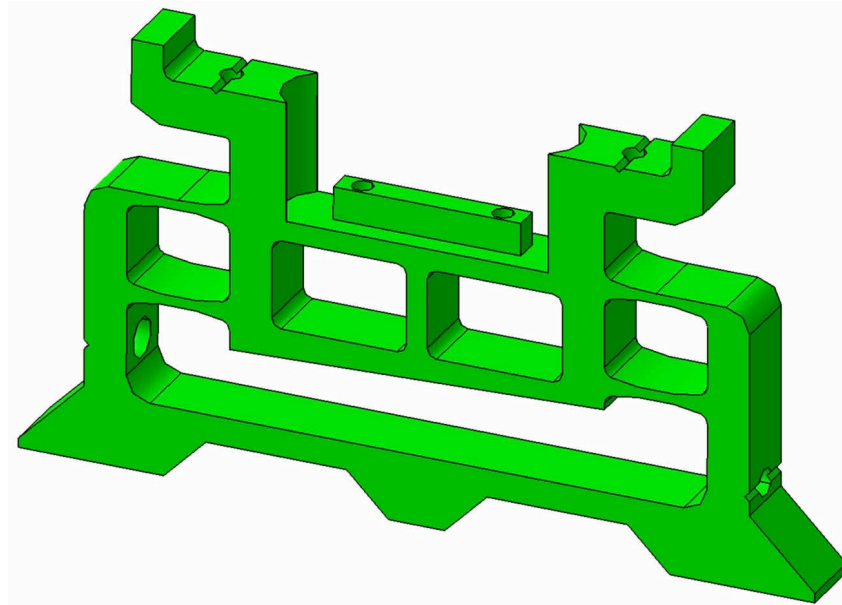
To block the s position



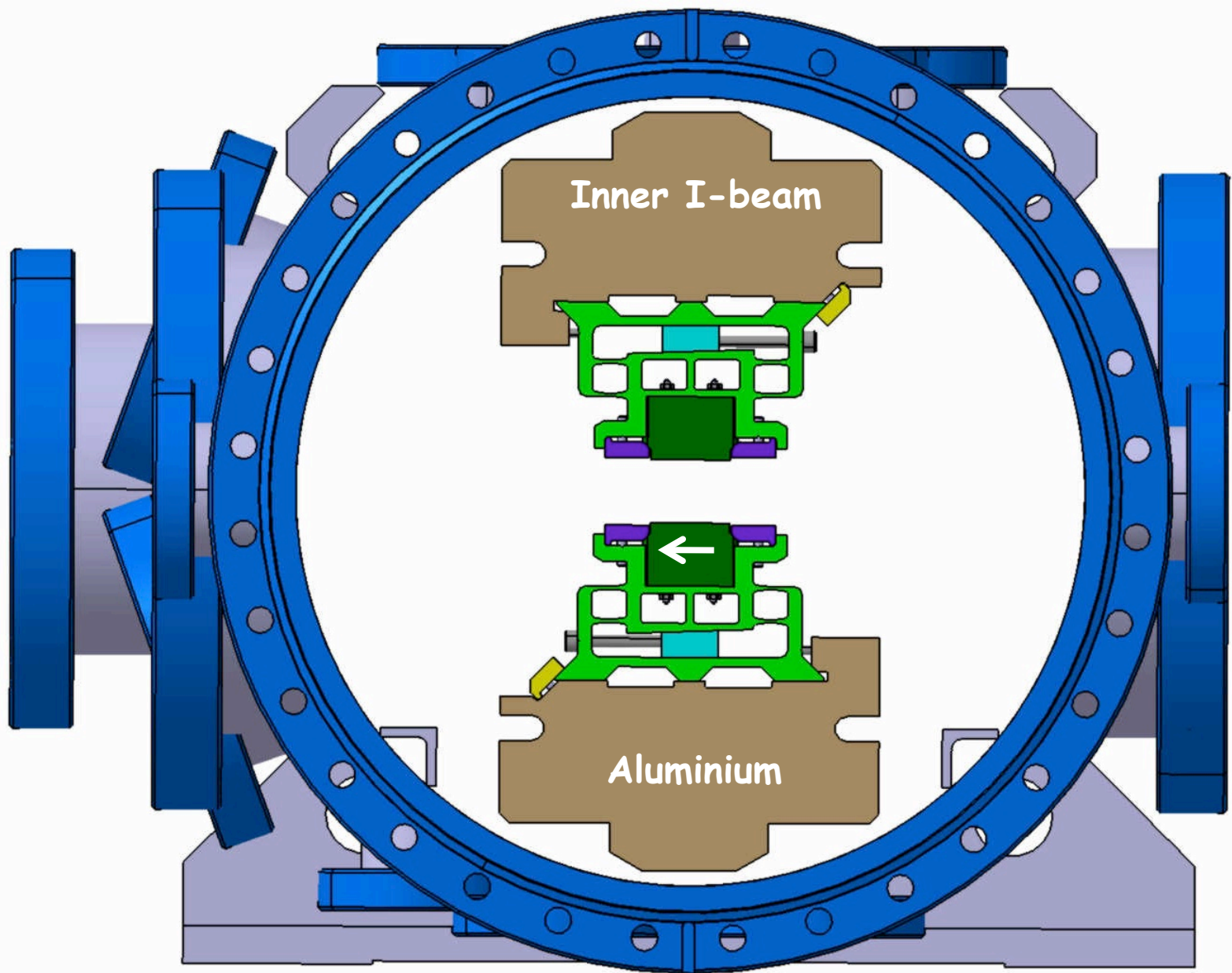
Five axes movers (as for SLS undulators)

Adjustable Keeper

extruded Al

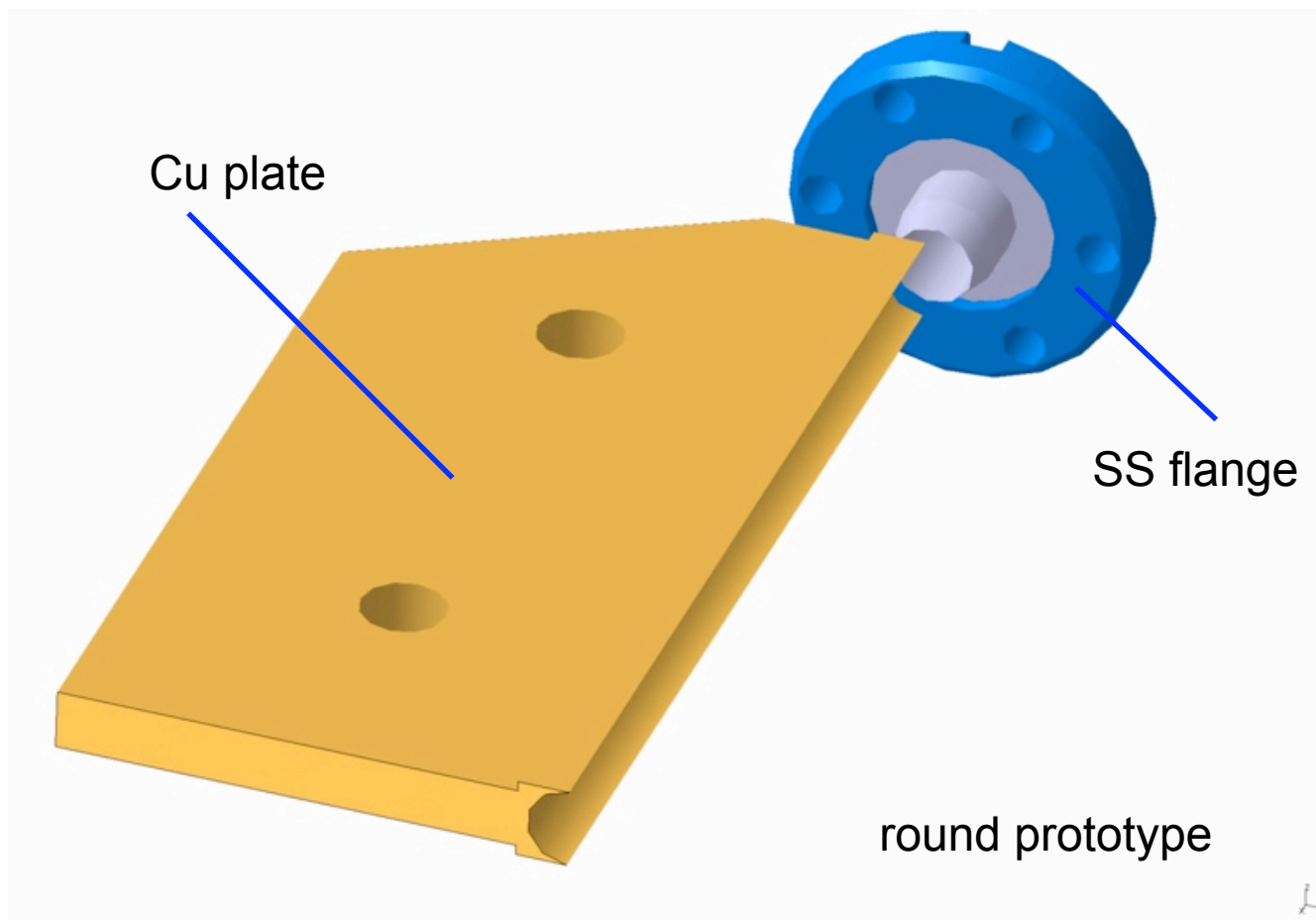


U15 vacuum vessel

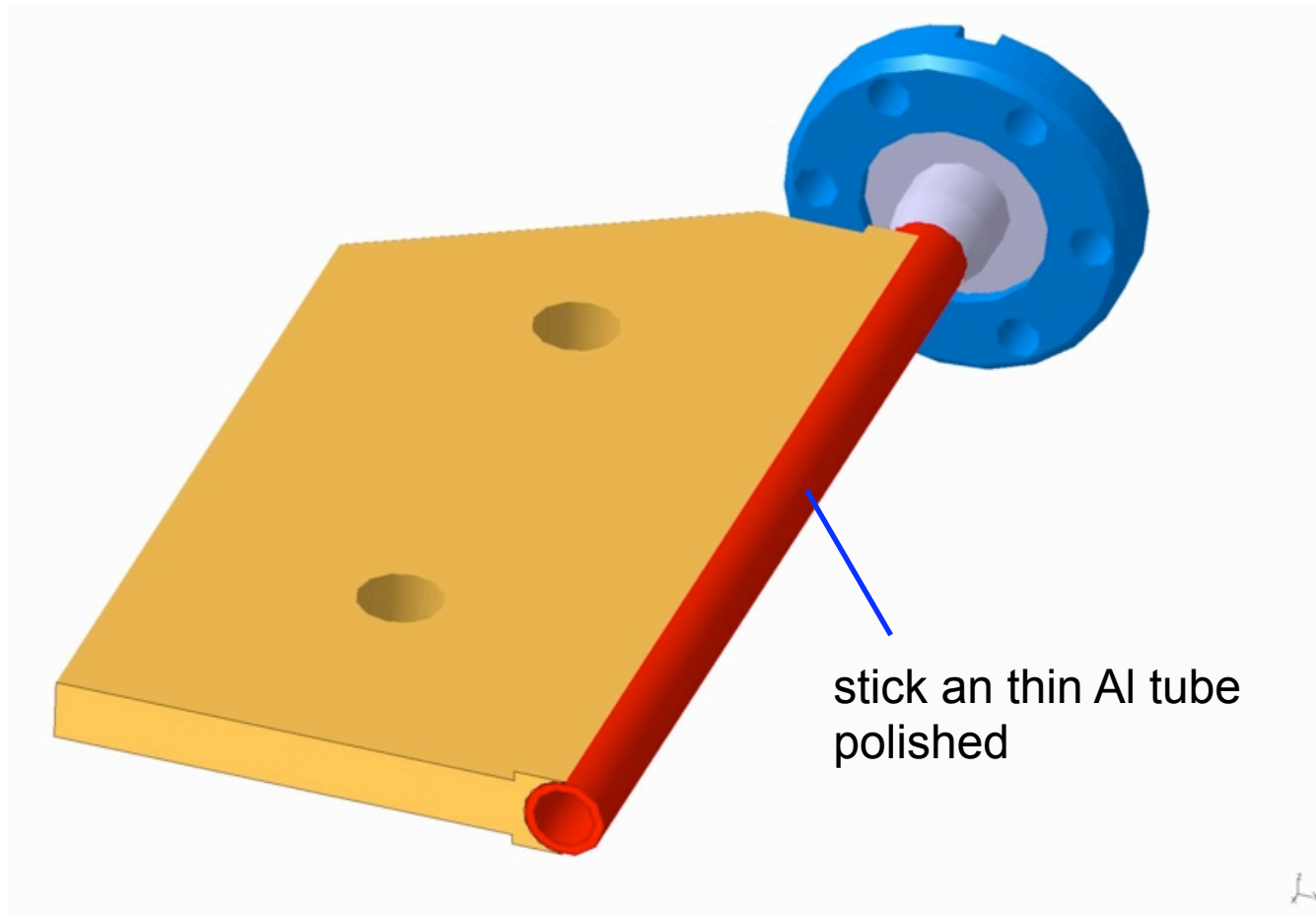


Vacuum chamber

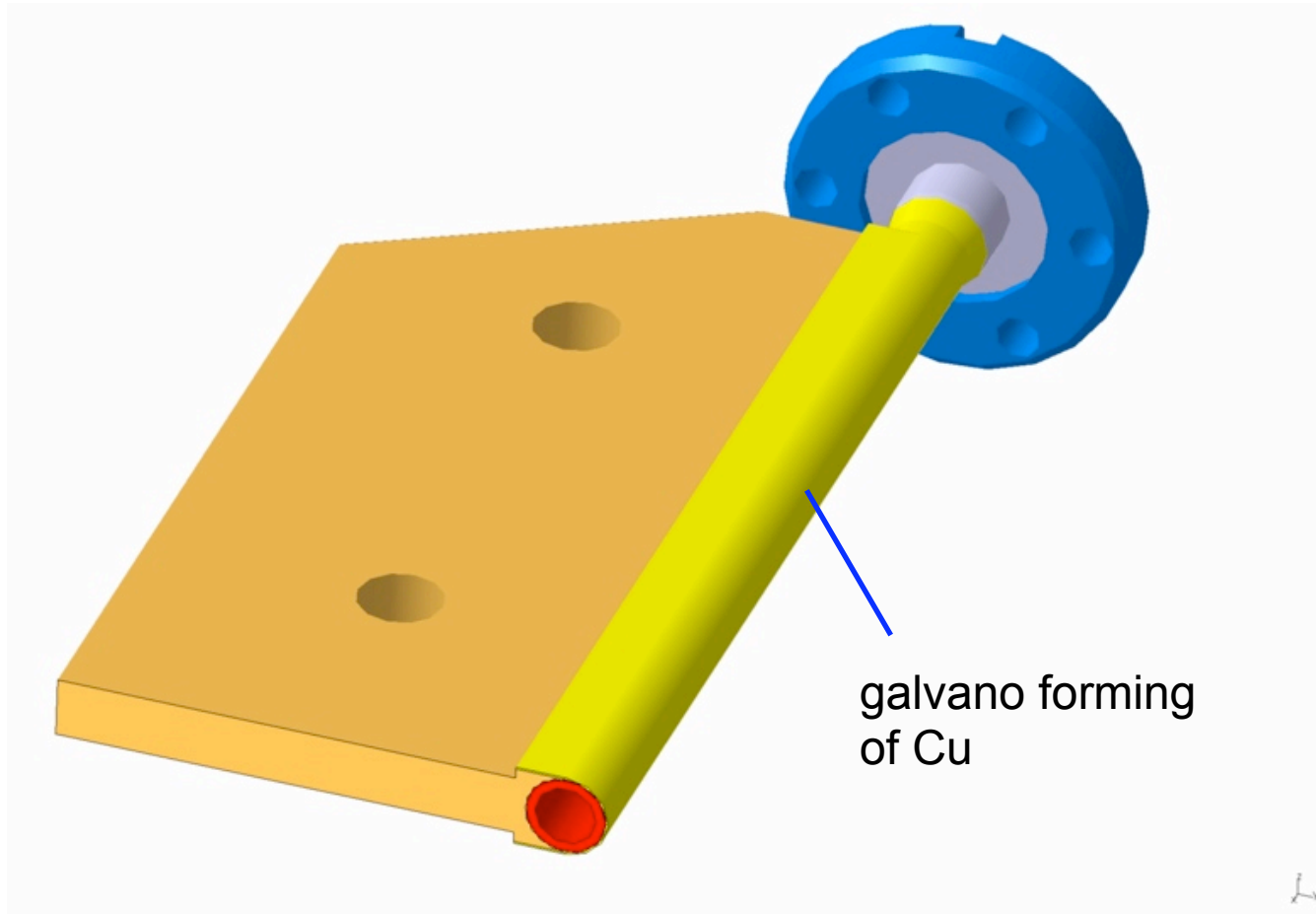
new fabrication process for vacuum chamber (Lothar Schulz)



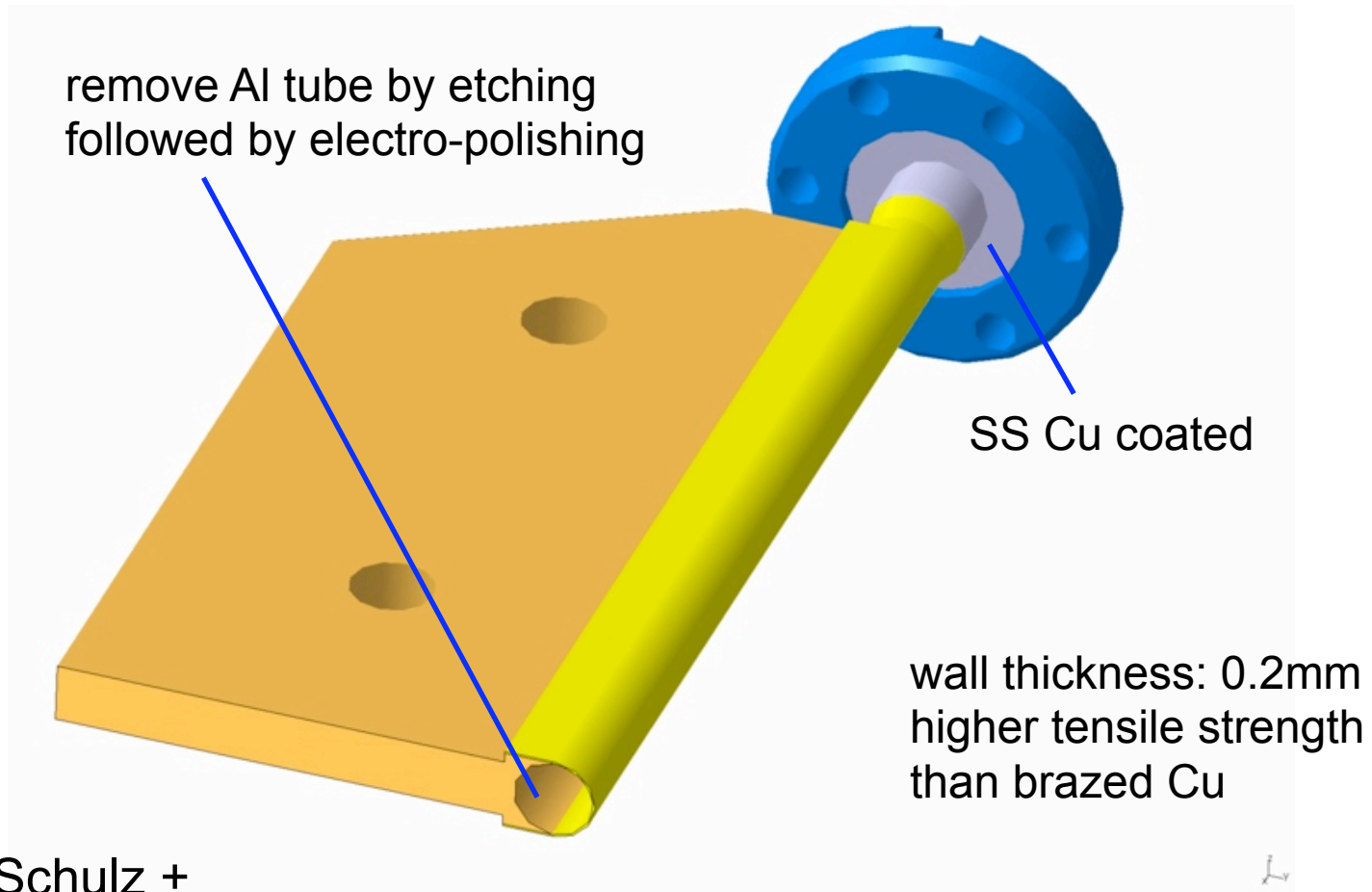
Vacuum chamber



Vacuum chamber



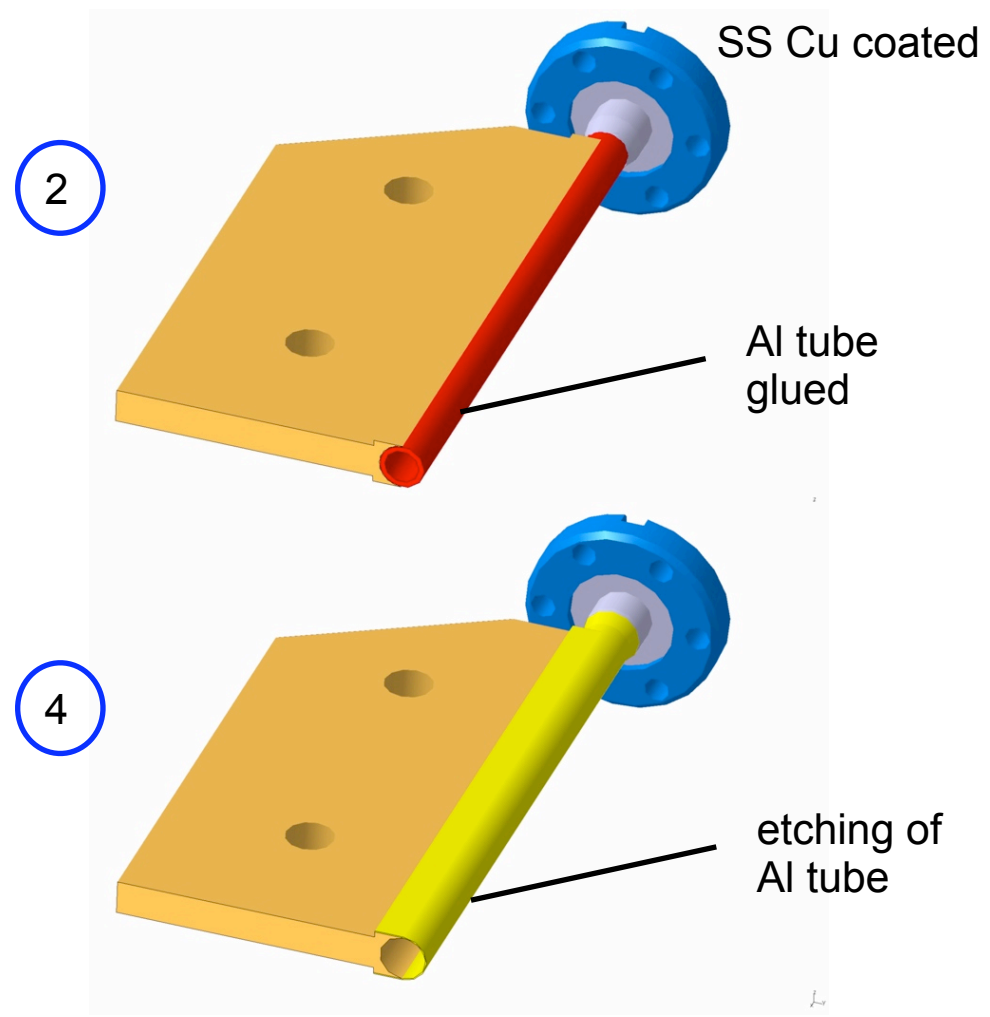
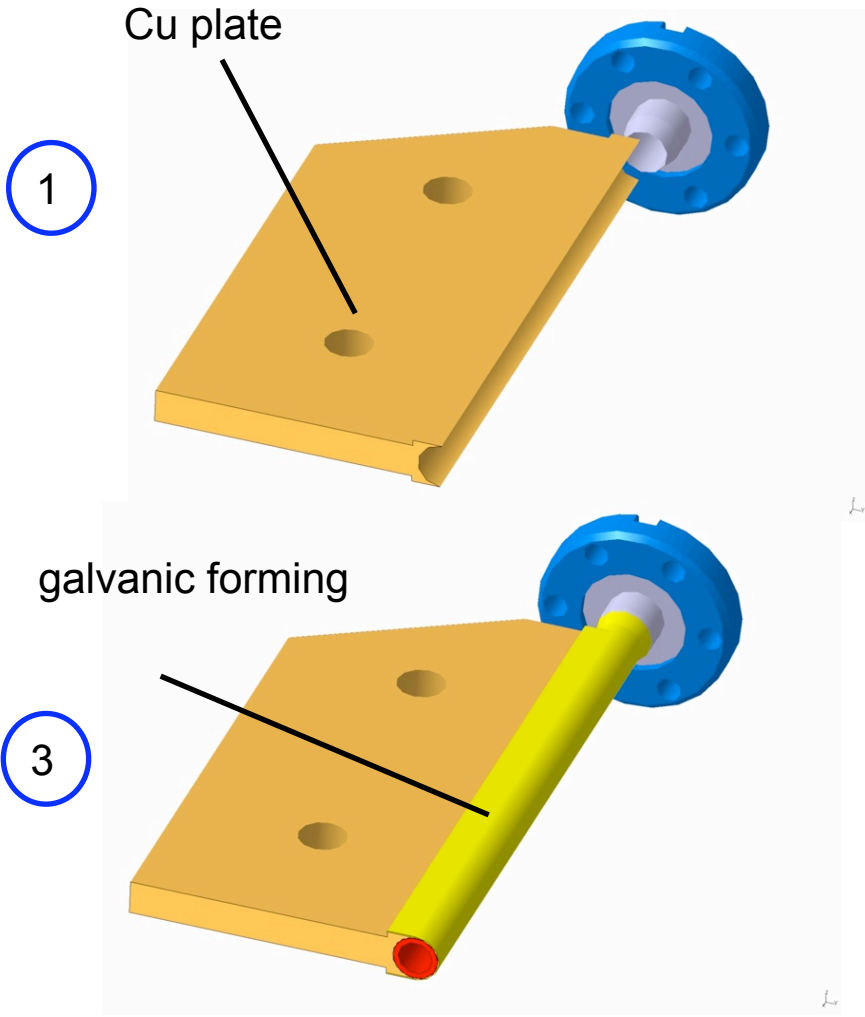
Vacuum chamber

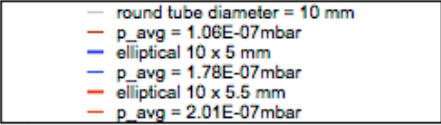


Lothar Schulz +
Galvano-T , Siegen, Germany,
www.galvano-t.de

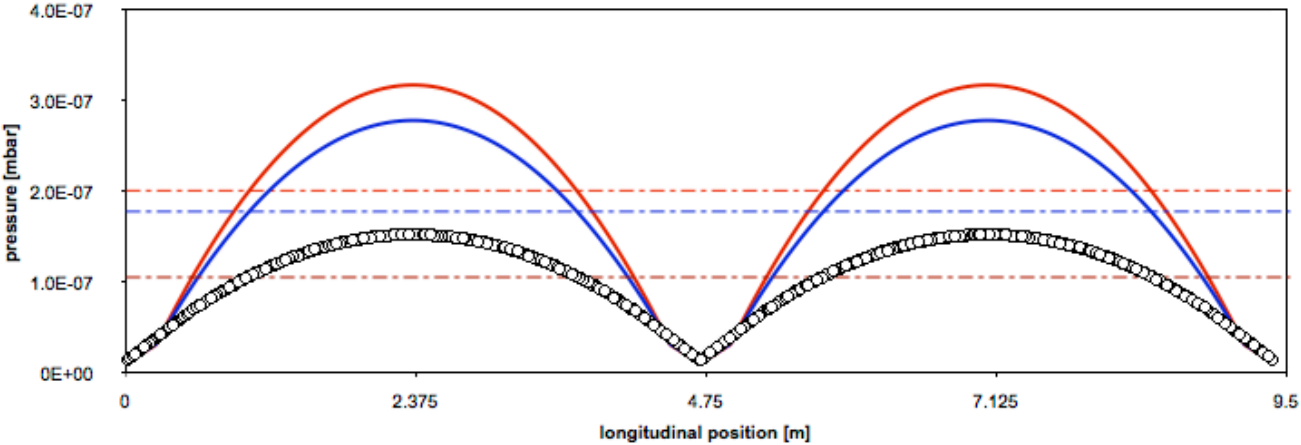
Vacuum chamber

Lothar Schulz +
Galvano-T, Siegen, Germany

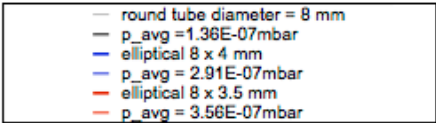




pressure distribution in UE40 chamber

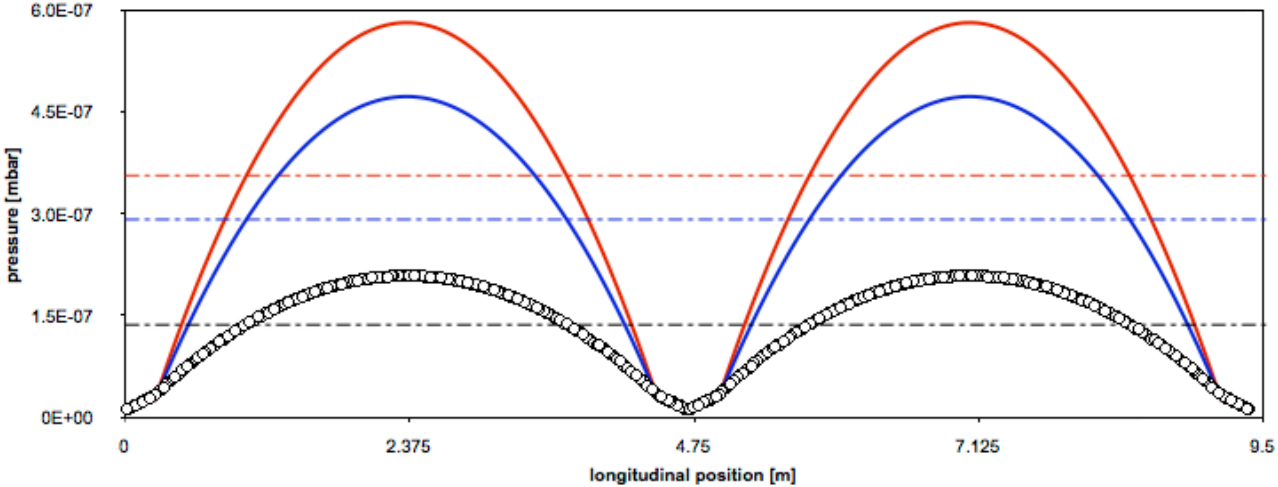


$2 \cdot 10^{-7}$ mbar



pressure distribution in U15 chamber

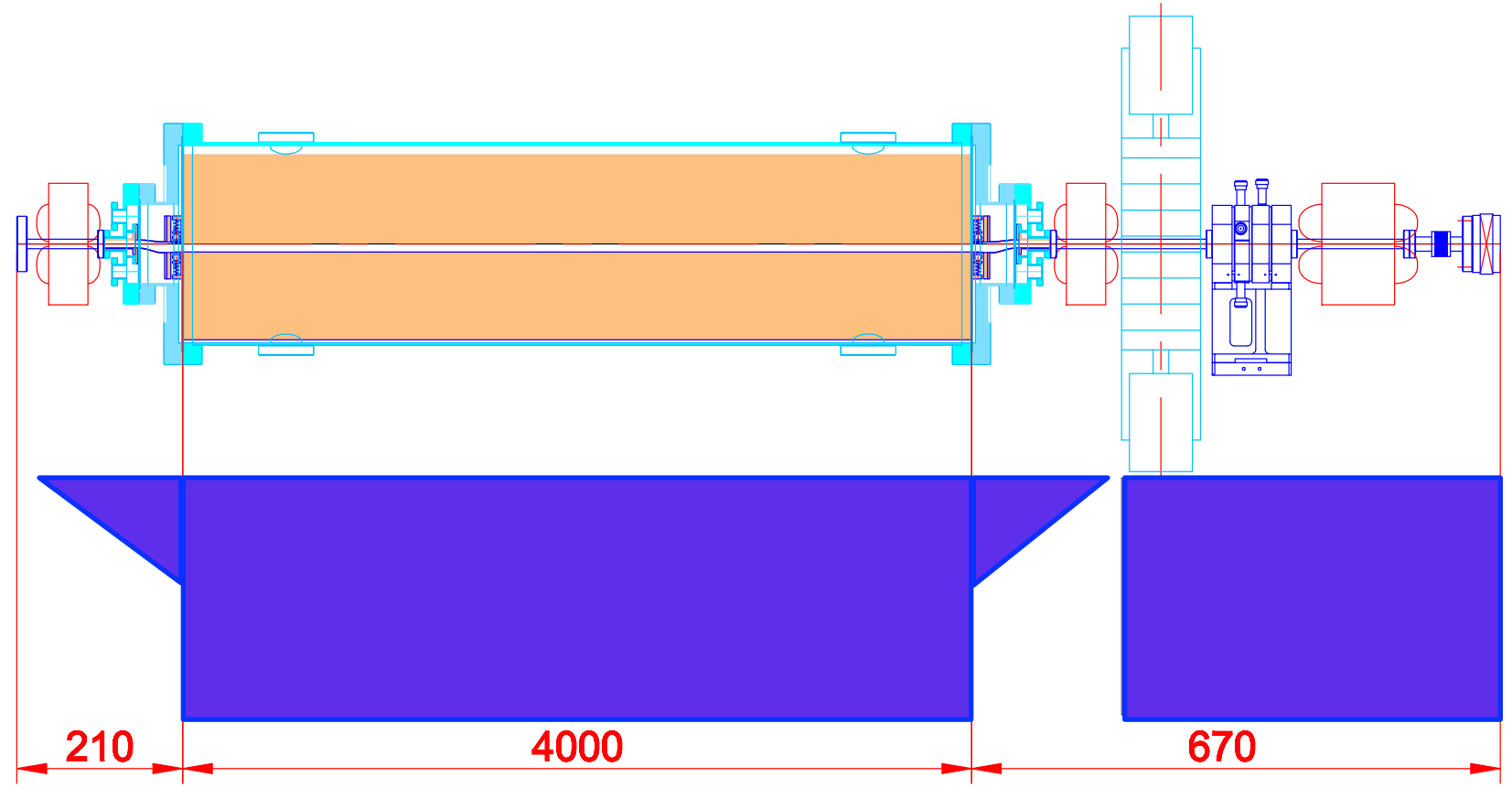
$3.5 \cdot 10^{-7}$ mbar



Qal
Tap

U15

Tap
Qal
PM
BPM
Q/C
Bellow
SV



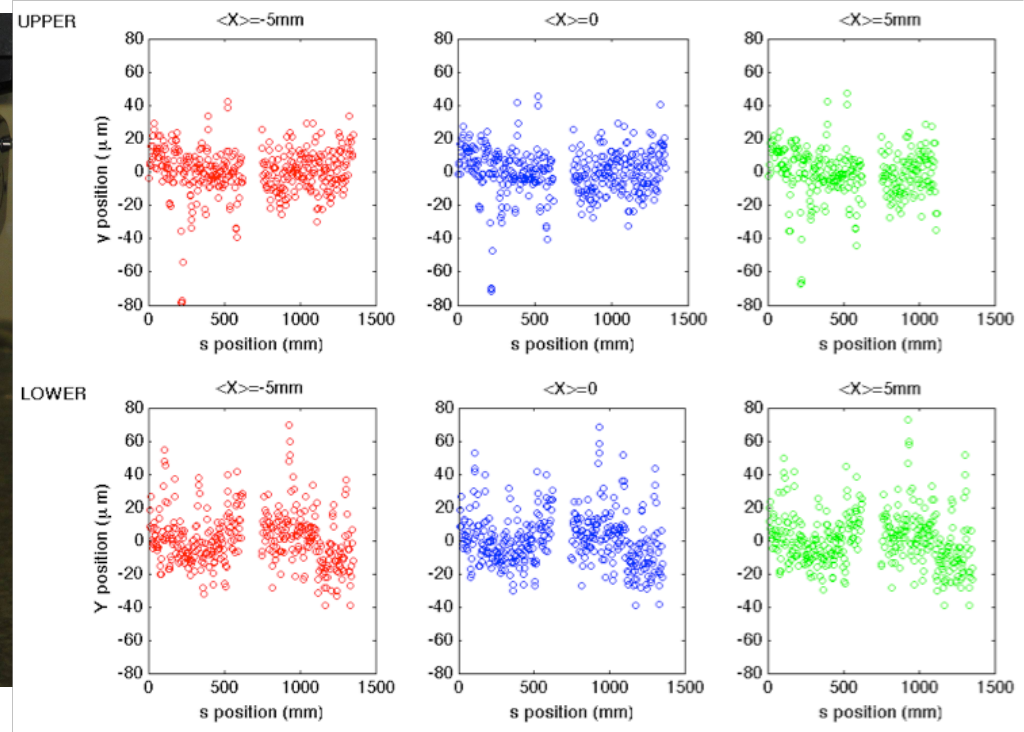
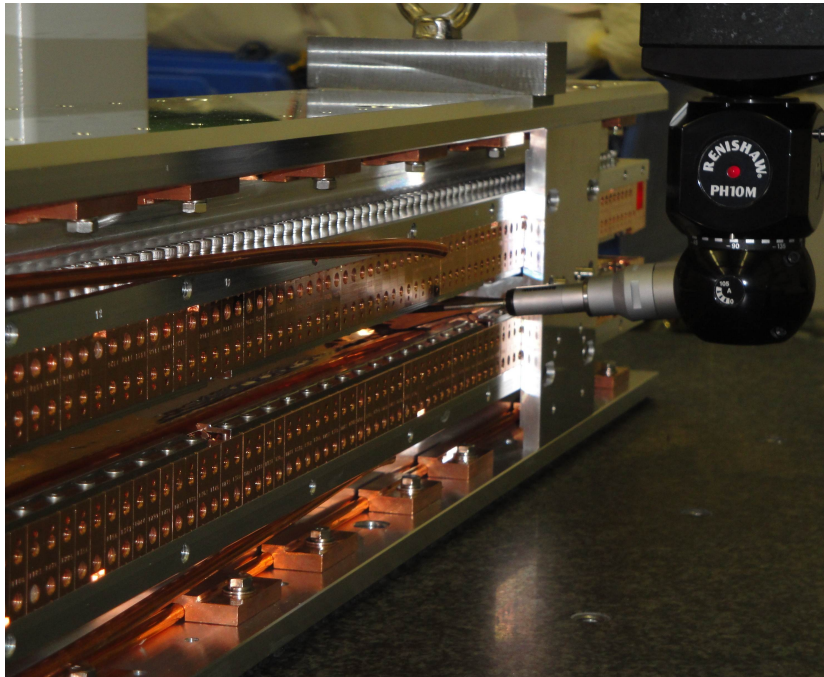
SwissFEL 6 GeV

U15 CELL Layout

Side View

19.04.2010

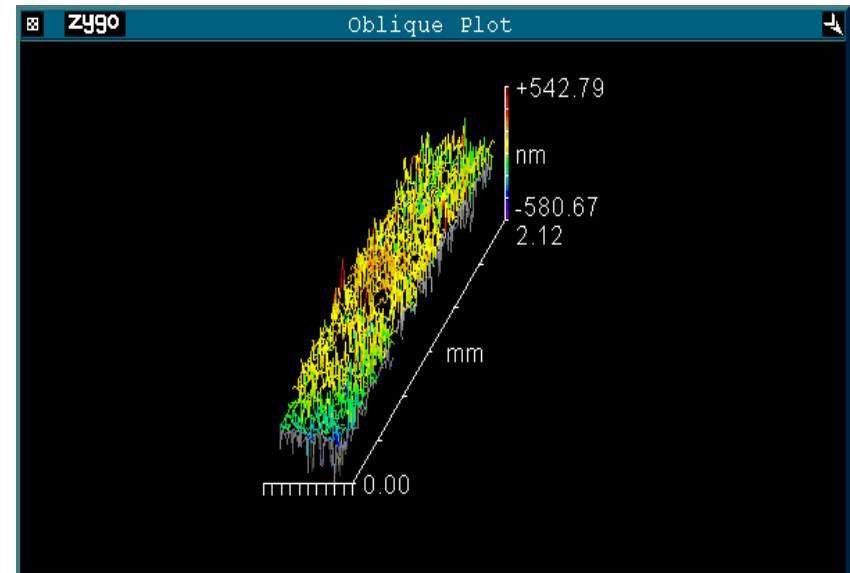
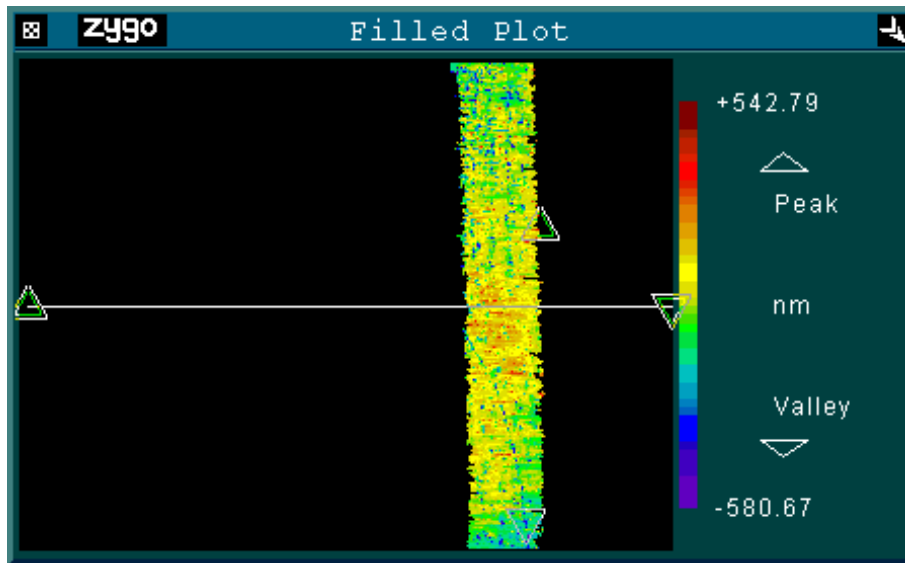
L. Schulz



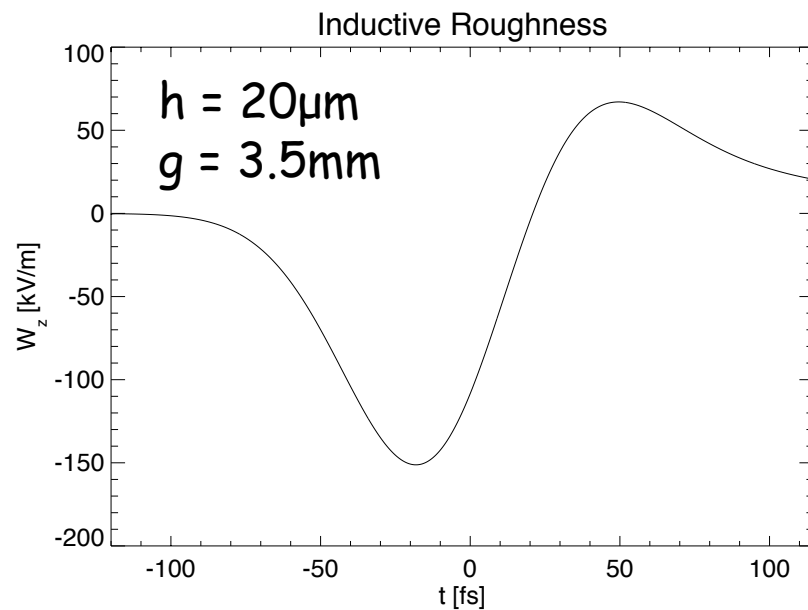
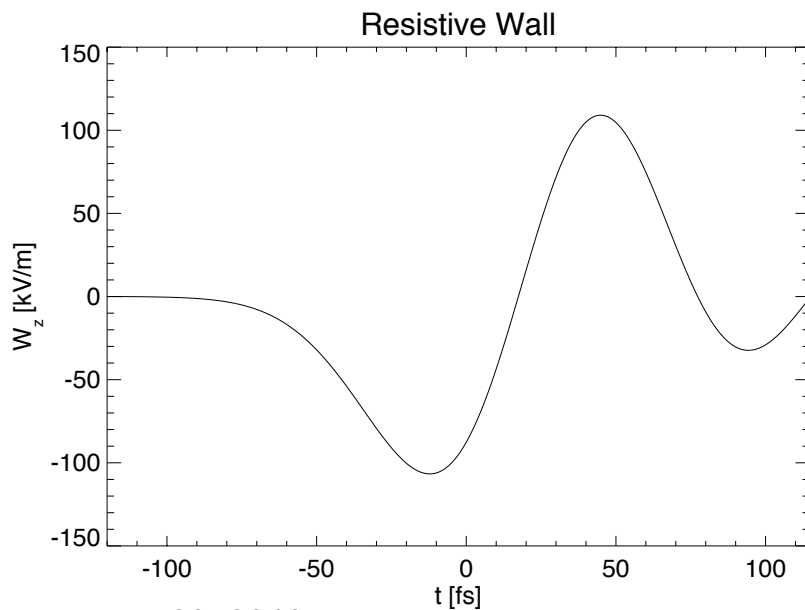
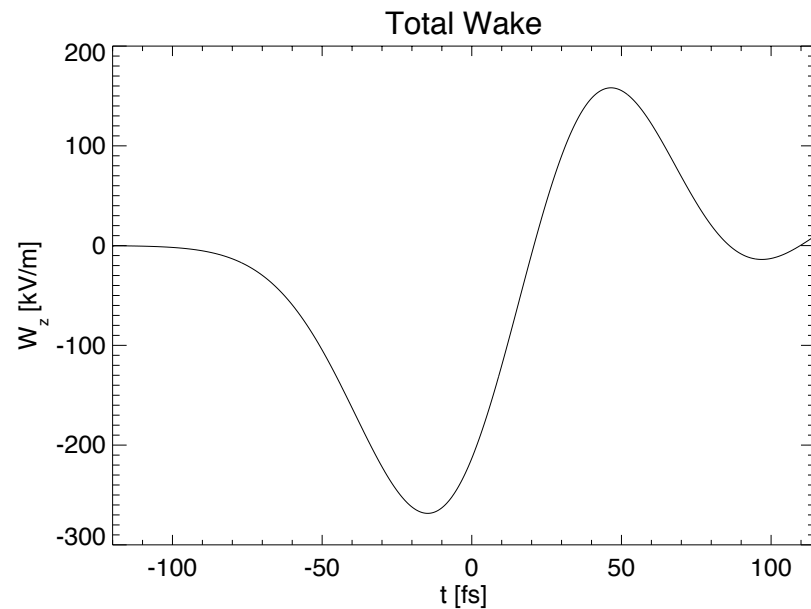
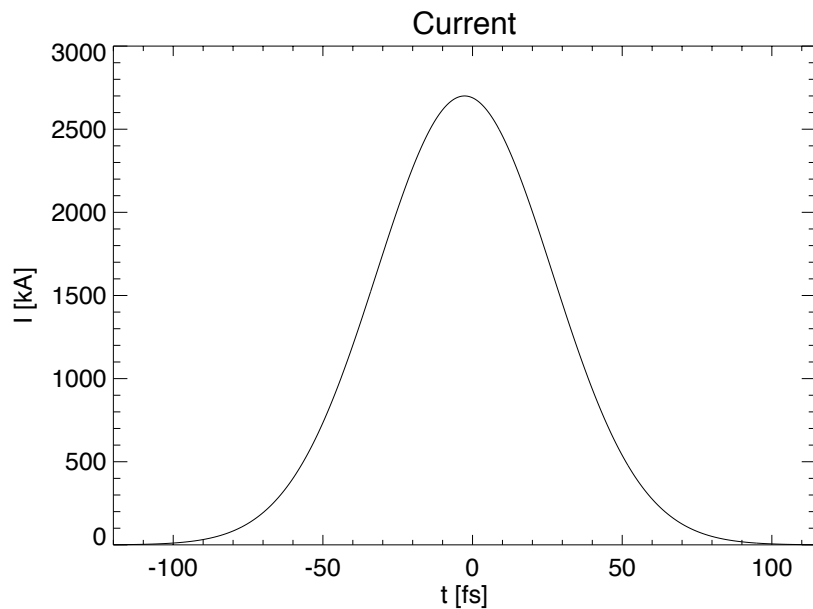
	$\langle X \rangle = -5\text{mm}$	$\langle X \rangle = 0$	$\langle X \rangle = 5\text{mm}$	
UPPER	16.7	16.1	16.1	[μm]
	11.8	12.1	12.4	
LOWER	15.1	14.8	14.6	
	17.2	17.7	17.7	

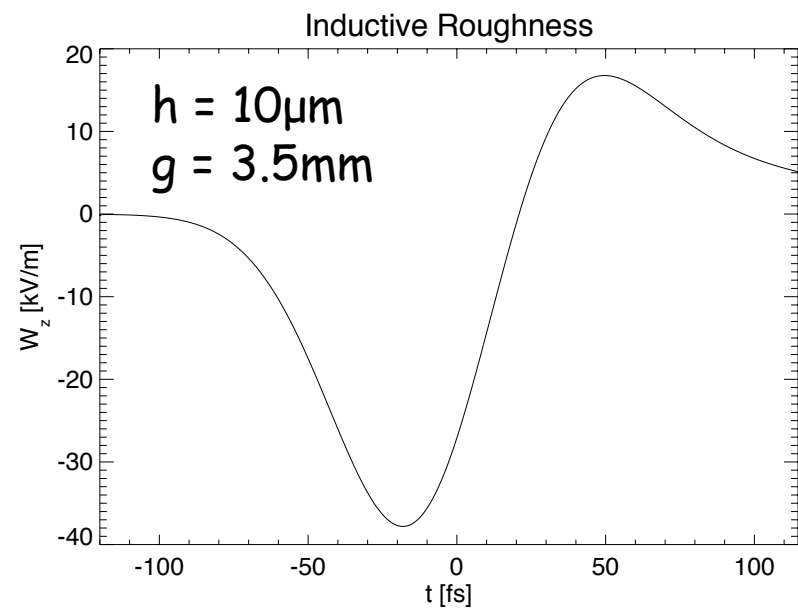
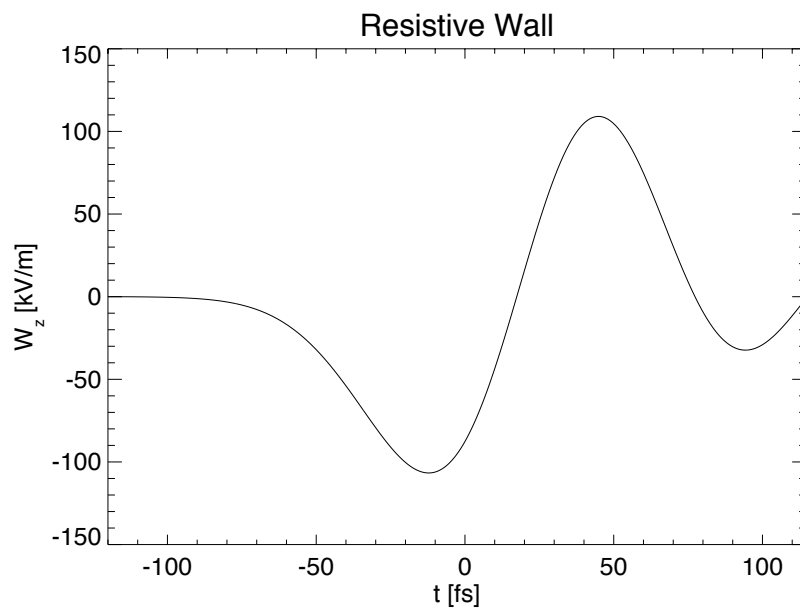
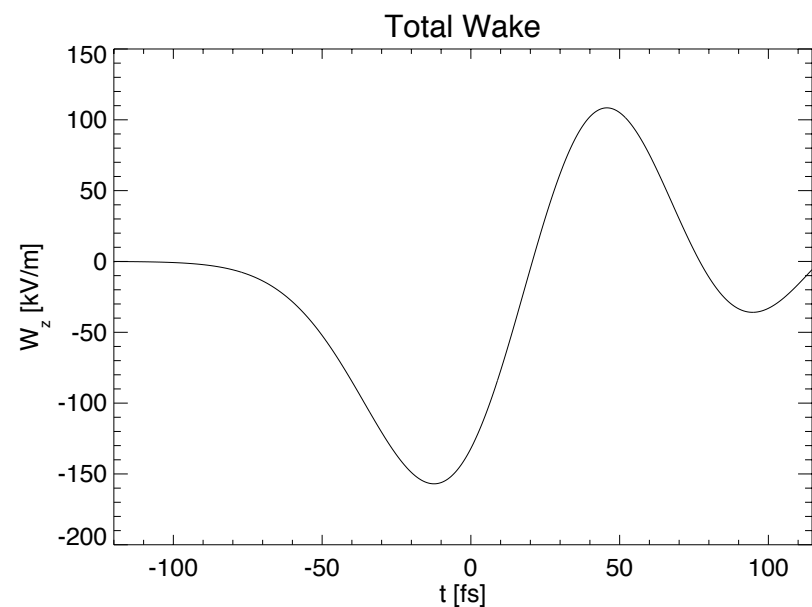
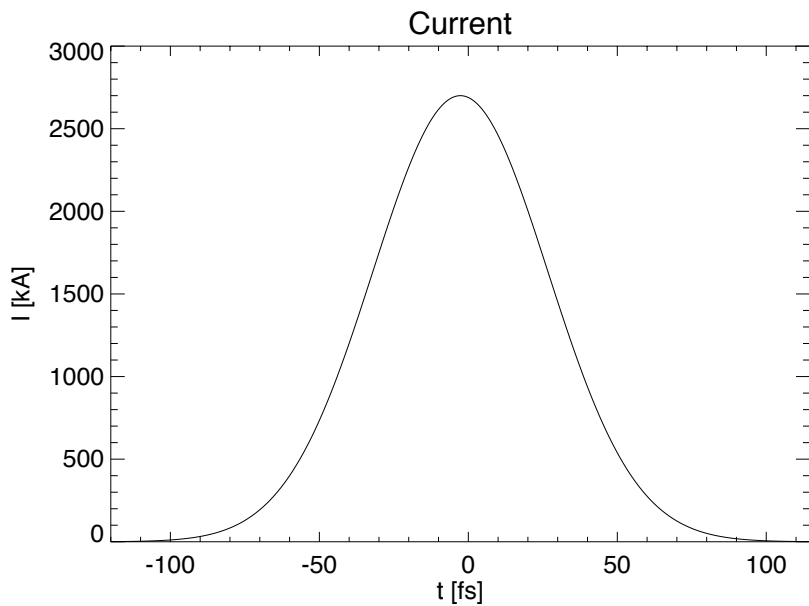
Surface Roughness of Cu-Ni foil

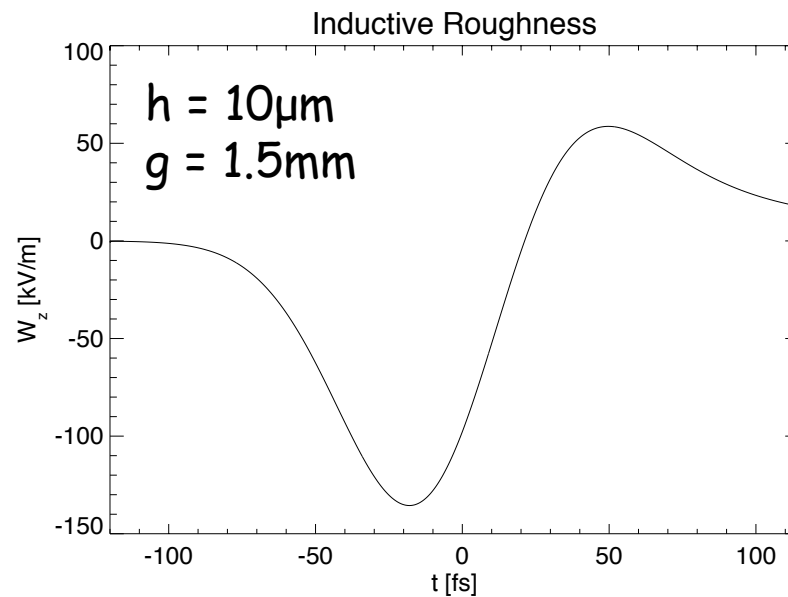
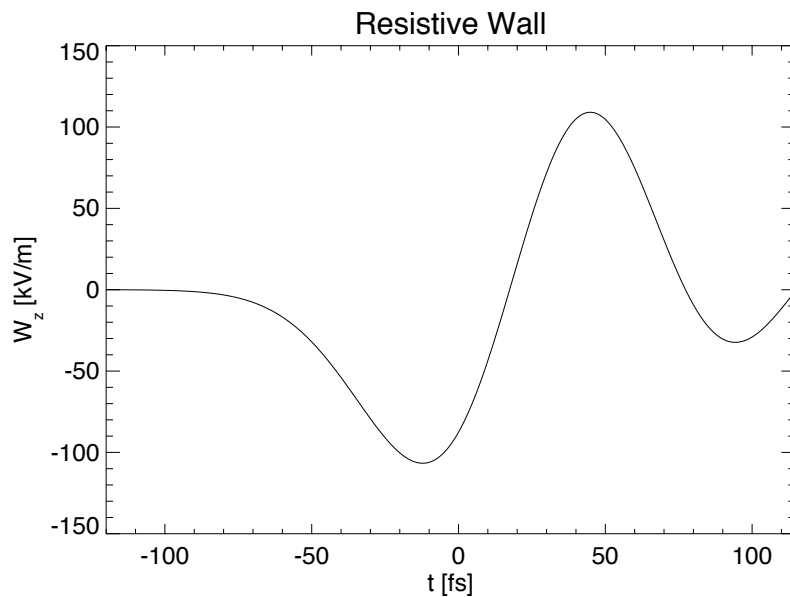
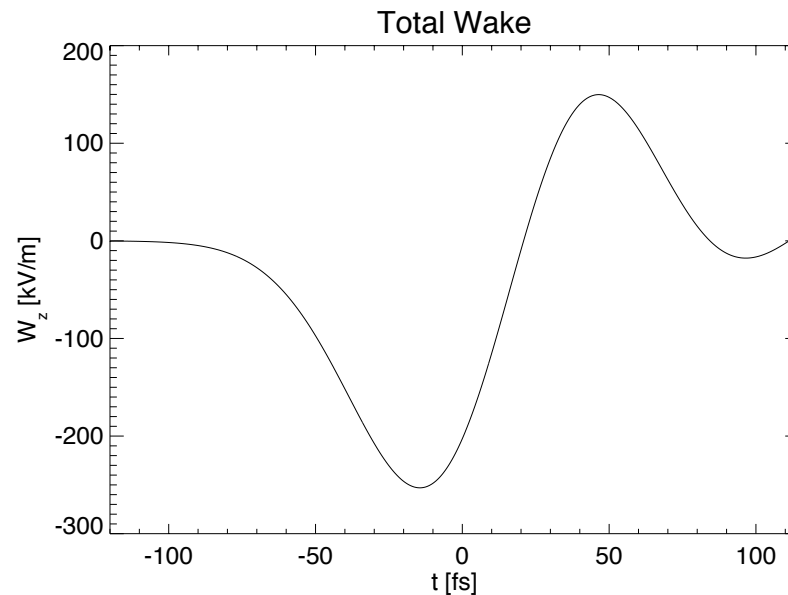
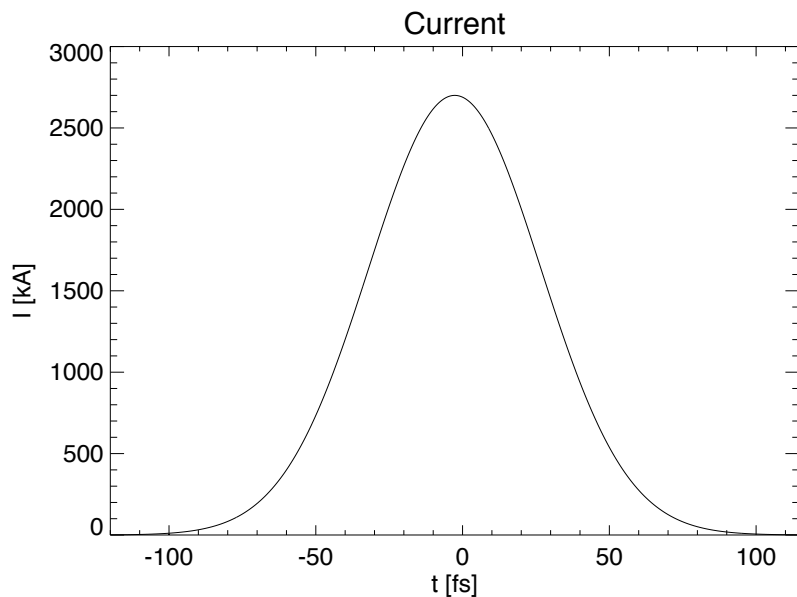
Number	RMS (nm)	PV* (nm)
1	119.55	1123.47
2	126.77	1521.51
3	102.95	1084.19
4	102.73	1083.45
∅	113.00	1203.15



Wake fields (Sven Reiche)







Conceptual Design & Review (CDR)

PSI

Detail Design & Review (DDR)

PSI (Industry)

Public call for tender (WTO) for Prototype production

Prototype	Manufacture	Industry
	Assembly	Industry/PSI
	Optimization	PSI
	Evaluation	PSI

Public call for tender (WTO) for Series production

Series	Manufacture	Industry
	Assembly	Industry/PSI
	Optimization	PSI
	Evaluation	PSI
	Installation	PSI

- ❑ The Master Company is the selected bidder for manufacture of the undulators
- ❑ The Master Company is responsible for the procurements of all the components but "magnets"
- ❑ To guarantee the specifications PSI shall make guidelines to the Master Company for some sub-systems:
 - ❑ Frame
 - ❑ Vacuum system (vessel, pumps, valves, bellows, gauges, taper)
 - ❑ Electrical system (motor, encoder, breaks)
 - ❑ Alignment system (movers)
 - ❑ Controls
- ❑ The Master Company is responsible for the assembly of all the components but the vacuum chamber (PSI)

A. Imhof; 2. November 2009

Jahr	2009		2010				2011				2012				2013				2014				2015				2016								
Quartal	3	4	1	2	3	4	1	2	3	4	1	2	3	4	1	2	3	4	1	2	3	4	1	2	3	4	1	2	3	4					
UE40	3D/2D-Konstruktion				A	Herstellung: Prototyp								E																	V	Herstellung			
U15	3D/2D-Konstruktion		A	Herstellung: Prototyp				E	V	Herstellung (11 Stk)										Vermessung (24Mt)															
Mod.	3D/2D- Konstruktion				A	Herstellung (3 Stk)						Vermessung (12Mt)																							

E= Evaluation = Finales Design-Review und magnetische Vermessung

A = Ausschreibung

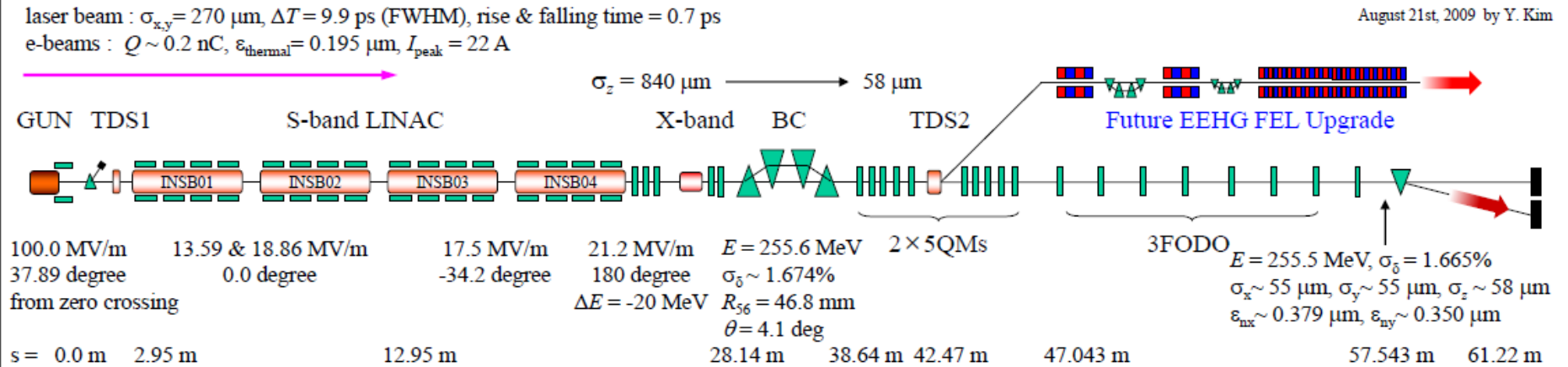
V = Vergabe

	Von	Bis	Dauer [Monat]	Tätigkeit	Aufwand [MannMonat]	Personal
1	Juli 2009	Dez. 2009	6	3D-Konstruktionen	60	10
2	Jan. 2010	April 2010	4	2D-Zeichnungen	20	5
3	Mai 2010	Aug. 2010	4	Devisierung & Auftragsvergabe	15	3
4	Sept. 2010	Sept. 2011	12	Herstellung des Prototypen: Überwachung	20	2
5	Okt. 2011	Dez. 2012	3	Evaluation	3	1
6	Jan. 2013	Mai 2013	4	Vergabe der Serie	12	3
7	Juni 2013	Dez. 2014	19	Herstellung, Überwachung	38	2
8	Jan. 2015	Jan. 2016	12	Lieferung, Vermessung, Montage	60	5
			64		228	3.5

T. Schmidt April 28, 2010

Freitag, 30. April 2010

August 21st, 2009 by Y. Kim



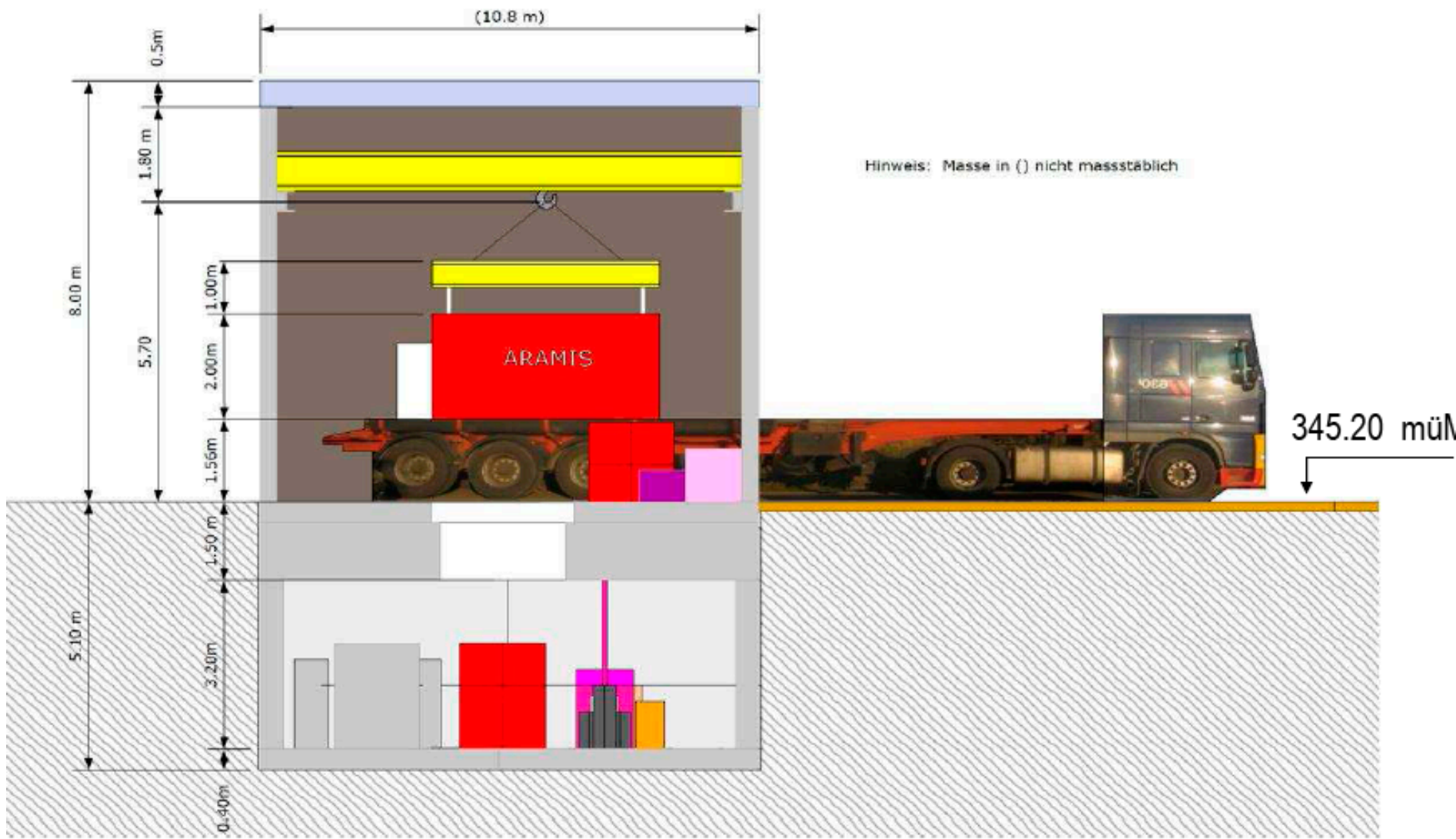
U15 full size prototype will be used for EEHG seeding

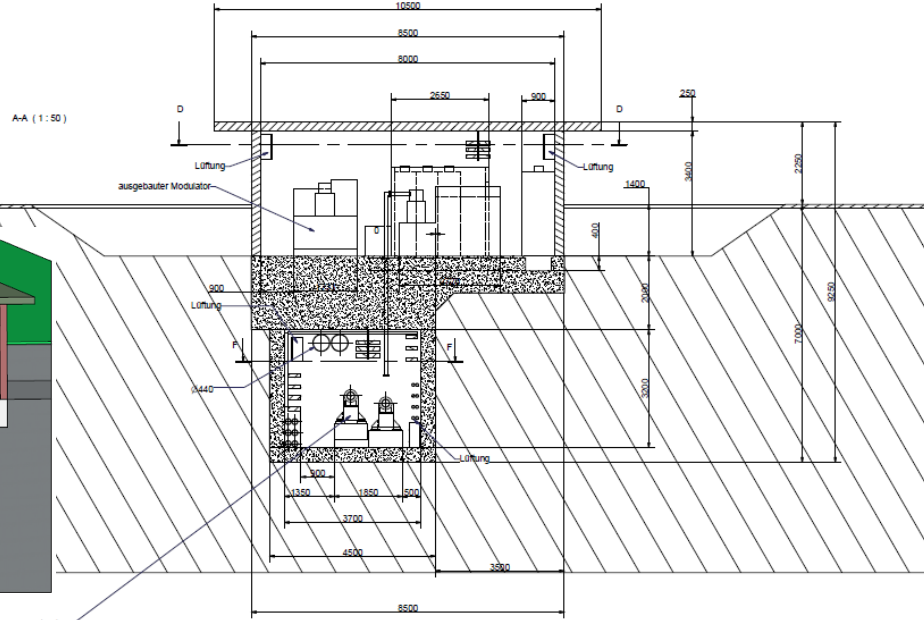
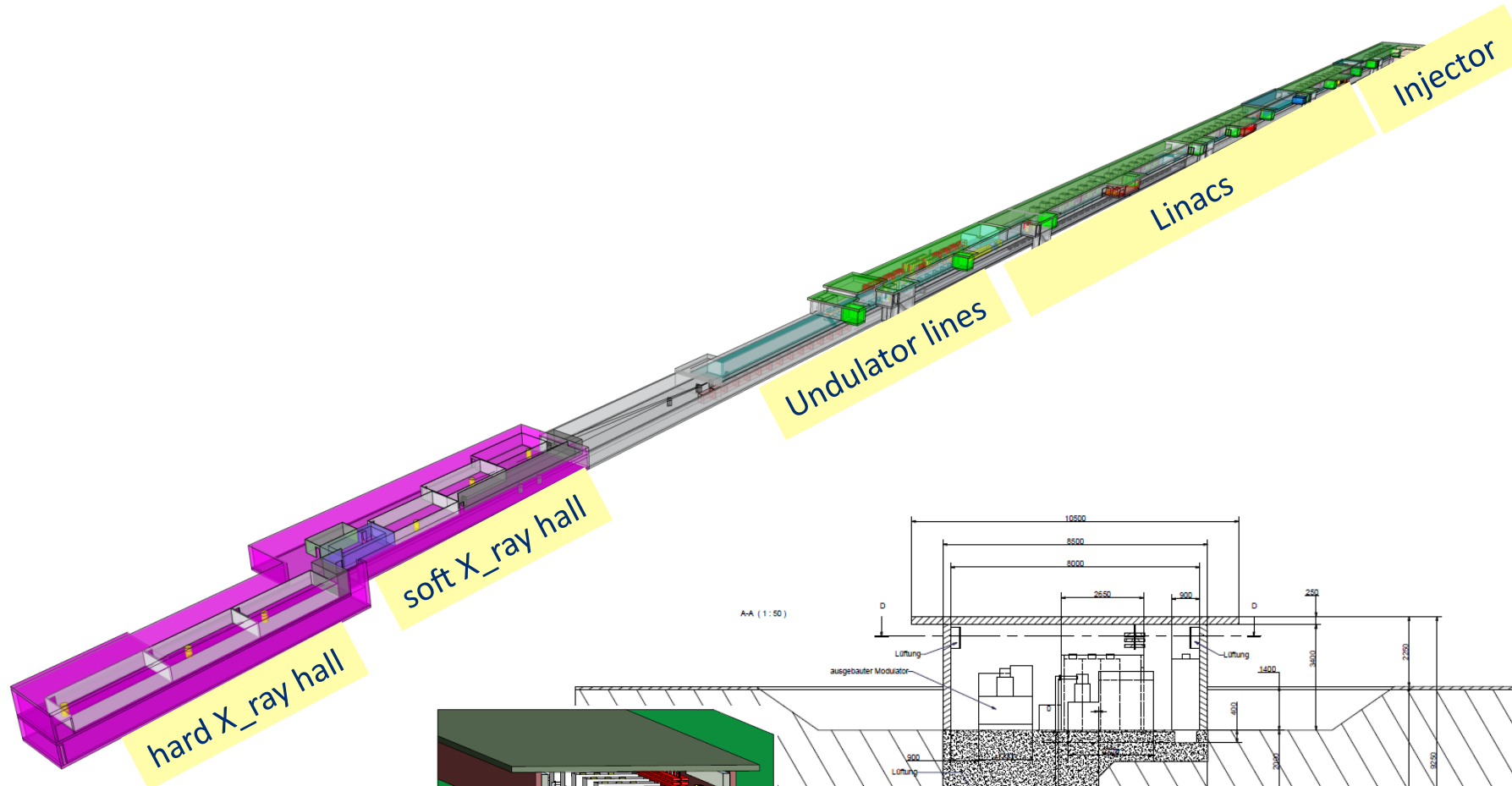
saturation expected with 50nm

UE40 small units for modulators

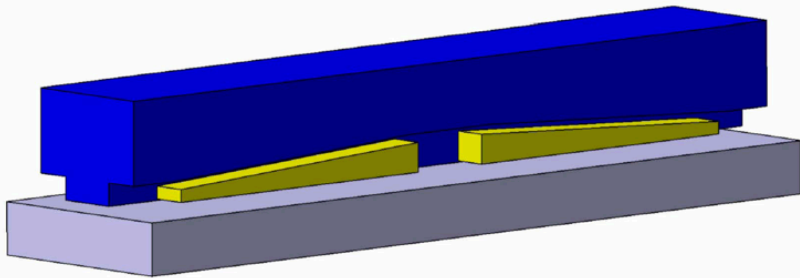
- ❑ We are at the end of the conceptual design:
 - ❑ All key components have been identified
 - ❑ and solutions have been produced → ongoing validation
- ❑ We should be ready for the first call for tender in September 2010
- ❑ Next step is to finalize the DDR, two options:
 - ❑ PSI alone
 - ❑ PSI + industries
- ❑ Still open the option of a U15 non in-vacuum for the series production: R&D ongoing on the U40 vacuum chamber...

Thanks for your support

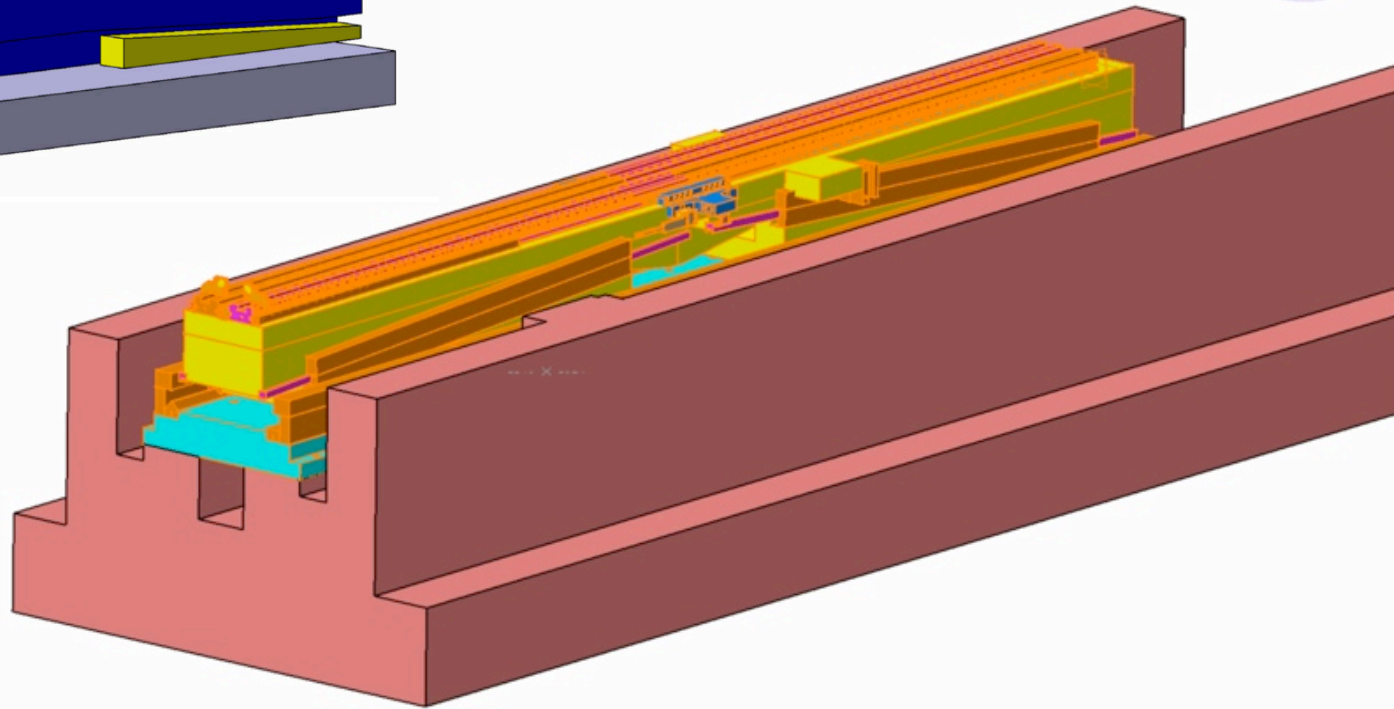
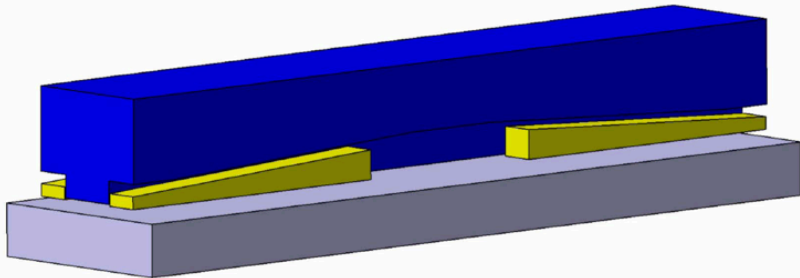




Wedge gap adjustment



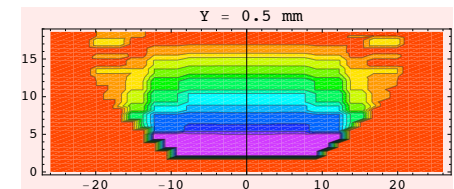
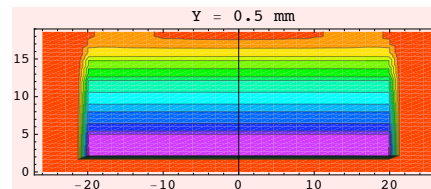
to transfer the stiffness of the lower girder to the I beam



	NdFeB NMX 27VH	Sm ₂ Co ₁₇	NdFeB diffused Dy	NdFeB CPMU
Radiation hard	☺	☺	☺	☺
dB/dT	-0.1 %/K	-0.035 %/K	-0.1 %/K	plateau
Permeability	1.06 / 1.15	1.01 / 1.04	1.06 / 1.15	1.06 / 1.15
mech. properties		more sensitive	improved	improved
Remanence B _r	1.08 T	1.1 T	> 1.25 T	1.5 T
suitable for	U40 / UE40	U40 / UE40	U15	U15

U15

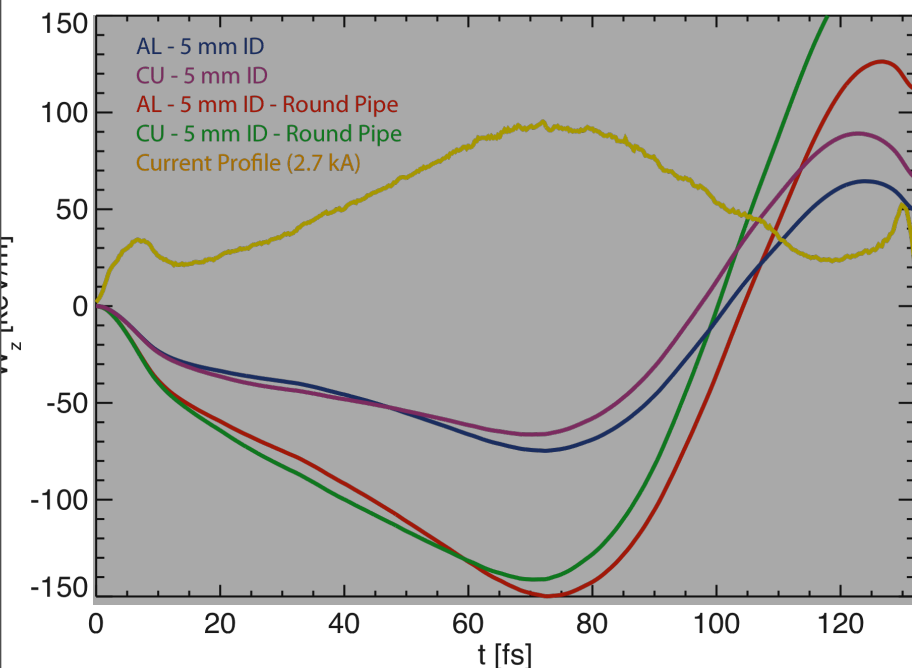
use of Dy diffused NdFeB at RT and
flux concentration on axis: B_r ↑ F ↓



UE40

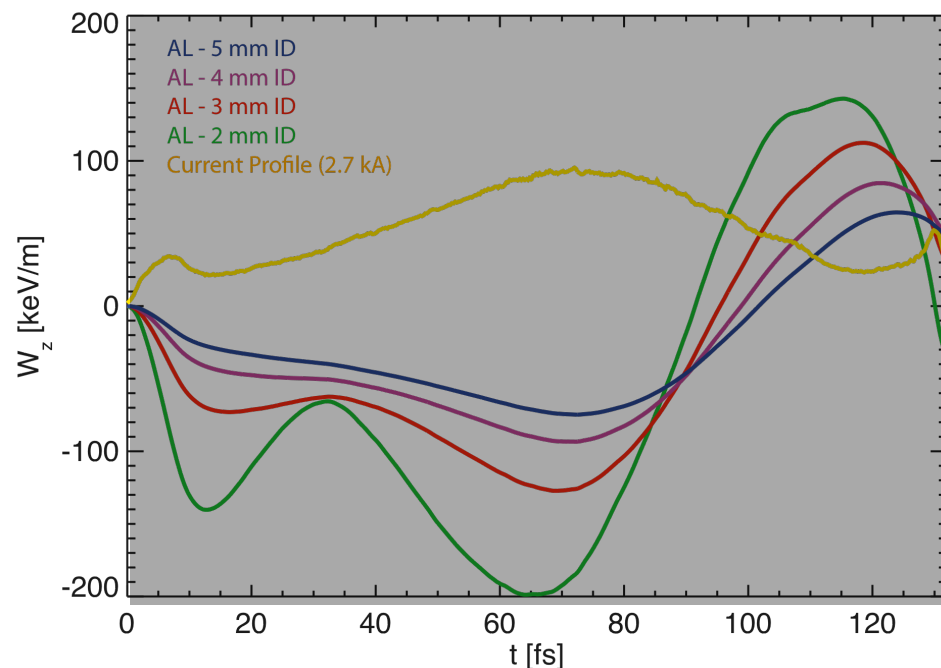
FEL operation allows for small gap 6.5mm magnetic 5mm vacuum gap
small magnet blocks 20 x 20 mm + low B_r > NdFeB or Sm₂Co₁₇

Wakefield Effects (Stupakov-Bane Model)



UE40 - fixed vacuum chamber

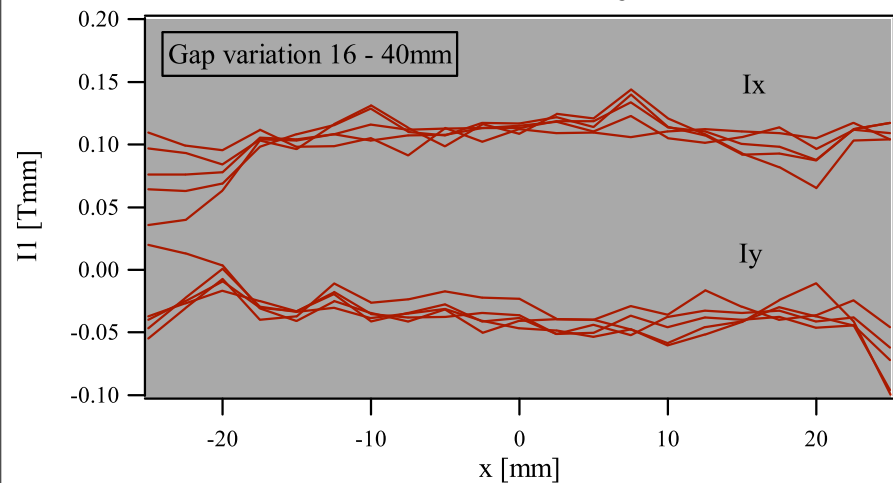
gap: 5mm elliptical
flattens current profile



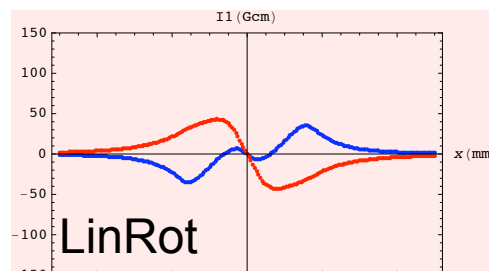
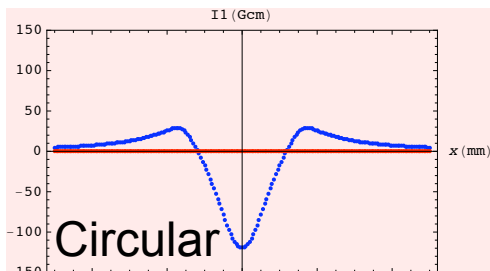
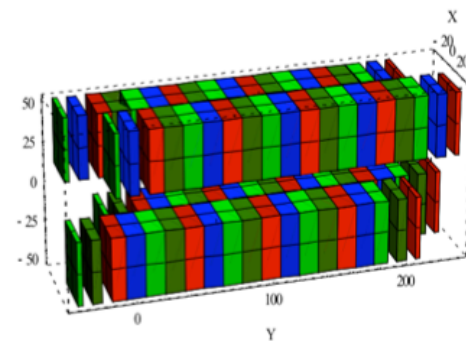
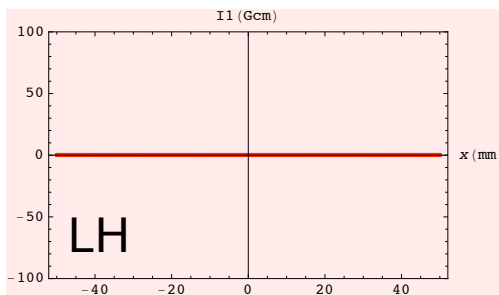
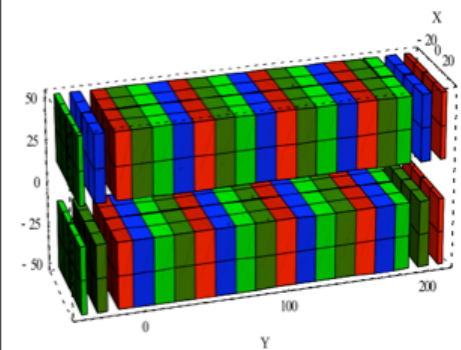
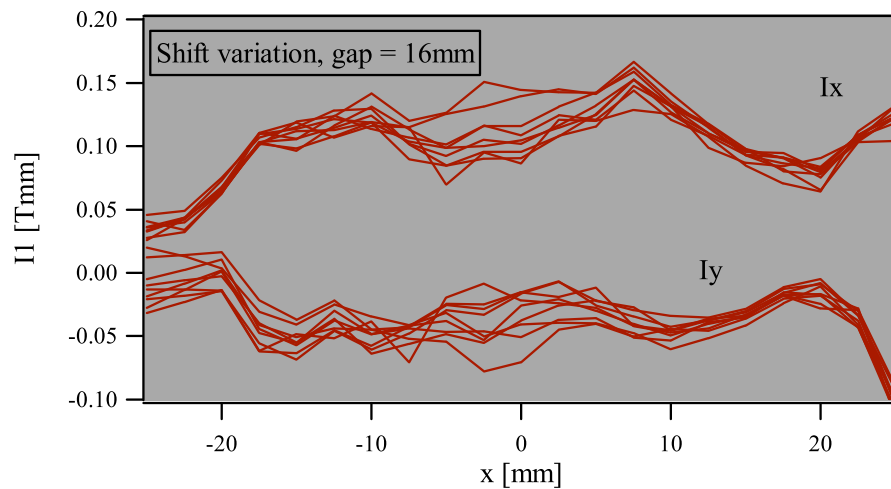
U15 - in vacuum undulator

minimum gap: 4mm

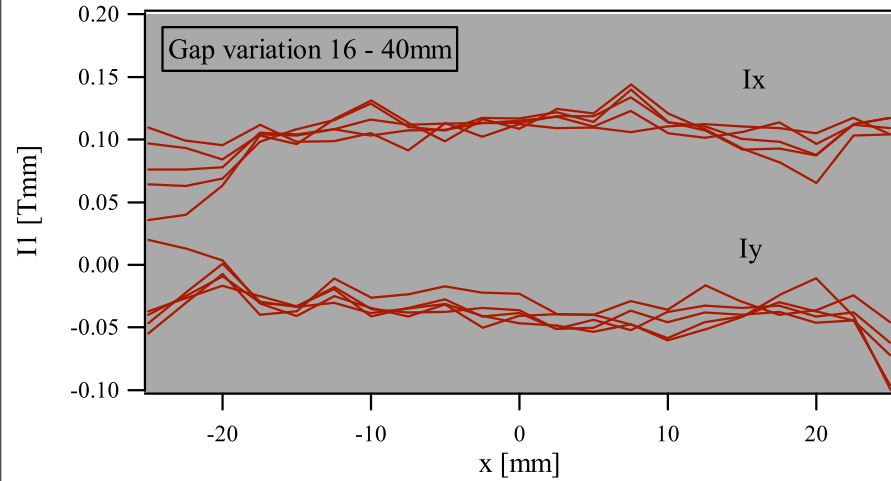
Field Integrals $\int B dy$



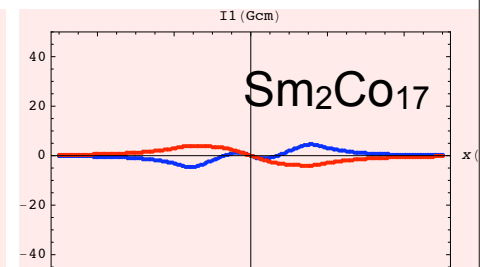
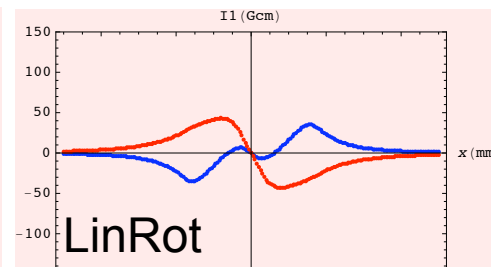
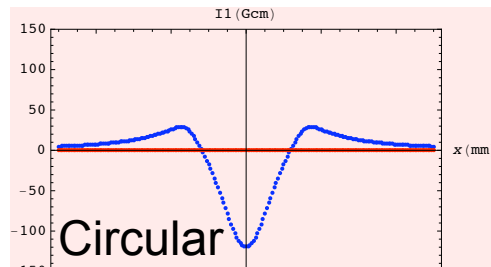
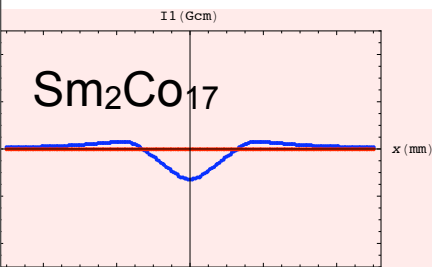
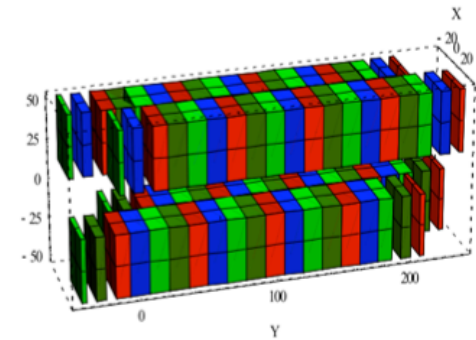
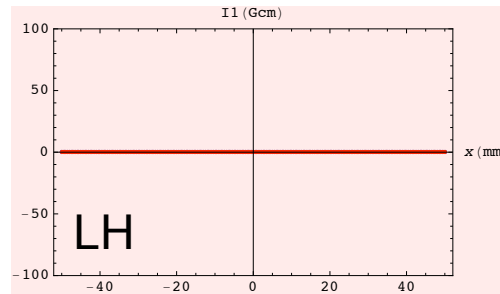
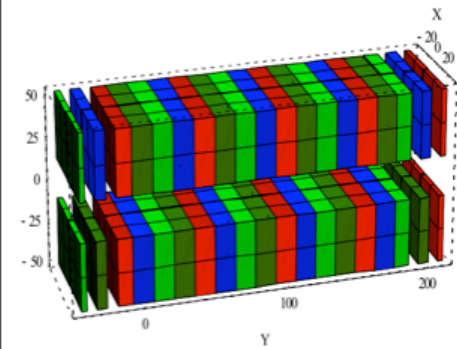
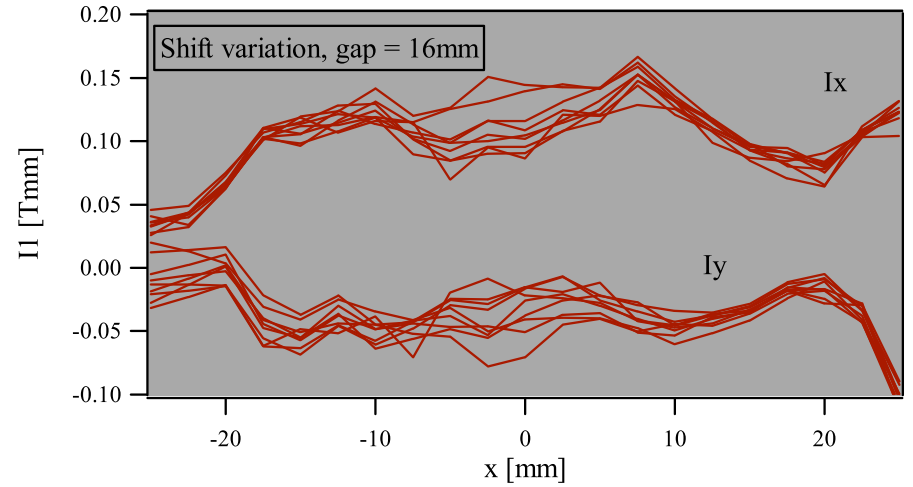
Systematic error due to $\mu - 1$ effect $\mu_{\perp} = 1.06, \mu_{\parallel} = 1.15$ for NdFeB



Field Integrals $\int B dy$



Systematic error due to $\mu - 1$ effect
 $\mu_{\perp} = 1.06, \mu_{\parallel} = 1.15$ for NdFeB



□ Single stretch wire

□ Moving wire → integrals

□ Pulsed wire → trajectory

□ Hall sensor bench

