

# Quindos Measuring Report



3D-Application Center

|                    |                    |                   |                         |
|--------------------|--------------------|-------------------|-------------------------|
| Description        | 2 X 2 FIXTURE BASE | Customer          | L. MANGER               |
| Drawing Number     | PF-391-522-01      | Serial Number     | 04                      |
| Remarks            |                    | Article Number    |                         |
| Supplier           | OSV                | Delivery Date     |                         |
| Delivery Note      |                    | Delivery Volume   |                         |
| Lot Number         |                    | Lot Size          |                         |
| Test Schedule      |                    | Sample Size       |                         |
| Production Machine |                    | Production Tool   |                         |
| Production Date    |                    | Production Time   |                         |
| Order              | 88-2600-1          | Department        | MET. QUALITY INSPEC     |
| Inspector          | kcaban             | Inspection Date   | 02-SEP-2009, 10:33:41   |
| Measuring Device   | PMM 12 10 6 #496   | Measuring Program | Quindos7 - V 7.1.9240-B |
| User Name          | kcaban             | WKP Name          | NO\$NAME                |

| Text                | Eval. | Actual     | Nominal | Up.To1. | Low.To1. | Act-Nom  | Graphic |
|---------------------|-------|------------|---------|---------|----------|----------|---------|
| <b>DAT\$PLA_D</b>   |       | <b>PLA</b> |         |         |          |          |         |
| FORM                |       | 0.00062    | 0.00000 | 0.00100 | 0.00000  | 0.00062  |         |
| <b>PROF_P364(1)</b> |       | <b>PLA</b> |         |         |          |          |         |
| FORM                |       | 0.00004    | 0.00000 | 0.00200 | 0.00000  | 0.00004  |         |
| Z                   |       | 0.36403    | 0.36400 | 0.00200 | -0.00200 | 0.00003  |         |
| <b>PROF_P364(2)</b> |       | <b>PLA</b> |         |         |          |          |         |
| FORM                |       | 0.00003    | 0.00000 | 0.00200 | 0.00000  | 0.00003  |         |
| Z                   |       | 0.36414    | 0.36400 | 0.00200 | -0.00200 | 0.00014  |         |
| <b>PROF_P364(3)</b> |       | <b>PLA</b> |         |         |          |          |         |
| FORM                |       | 0.00008    | 0.00000 | 0.00200 | 0.00000  | 0.00008  |         |
| Z                   |       | 0.36382    | 0.36400 | 0.00200 | -0.00200 | -0.00018 |         |
| <b>PROF_P364(4)</b> |       | <b>PLA</b> |         |         |          |          |         |
| FORM                |       | 0.00005    | 0.00000 | 0.00200 | 0.00000  | 0.00005  |         |
| Z                   |       | 0.36394    | 0.36400 | 0.00200 | -0.00200 | -0.00006 |         |
| <b>DY_P50(1)</b>    |       | <b>PLA</b> |         |         |          |          |         |
| Y                   |       | 0.49747    | 0.50000 | 0.01000 | -0.01000 | -0.00253 |         |
| <b>DY_P50(2)</b>    |       | <b>PLA</b> |         |         |          |          |         |
| Y                   |       | 0.49891    | 0.50000 | 0.01000 | -0.01000 | -0.00109 |         |
| <b>DY_2P05(1)</b>   |       | <b>PLA</b> |         |         |          |          |         |
| Y                   |       | 2.05011    | 2.05000 | 0.01000 | -0.01000 | 0.00011  |         |
| <b>DY_2P05(2)</b>   |       | <b>PLA</b> |         |         |          |          |         |
| Y                   |       | 2.05220    | 2.05000 | 0.01000 | -0.01000 | 0.00220  |         |
| <b>DX_P40(1)</b>    |       | <b>PLA</b> |         |         |          |          |         |
| X                   |       | 0.39840    | 0.40000 | 0.01000 | -0.01000 | -0.00160 |         |
| <b>DX_P40(2)</b>    |       | <b>PLA</b> |         |         |          |          |         |
| X                   |       | 0.39681    | 0.40000 | 0.01000 | -0.01000 | -0.00319 |         |
| <b>DX_2P60(1)</b>   |       | <b>PLA</b> |         |         |          |          |         |
| X                   |       | 2.59897    | 2.60000 | 0.01000 | -0.01000 | -0.00103 |         |

| Text                      | Eval. | Actual   | Nominal | Up.To1. | Low.To1. | Act-Nom     | Graphic |
|---------------------------|-------|----------|---------|---------|----------|-------------|---------|
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|---------------------------|-------|---------|------------|---------|----------|-------------|-----------|
| Text                      | Eval. | Actual  | Nominal    | Up.To1. | Low.To1. | Act-Nom     | Graphic   |
| <b>DX_2P60(2)</b>         |       |         | <b>PLA</b> |         |          |             |           |
| X                         |       | 2.59735 | 2.60000    | 0.01000 | -0.01000 | -0.00265    |           |
| <b>TOP\$PIN(1)</b>        |       |         | <b>CIR</b> |         |          |             |           |
| FORM                      |       | 0.00003 |            |         |          |             |           |
| DM                        |       | 0.06256 |            |         |          |             |           |
| X                         |       | 0.20248 | 0.20000    |         |          | 0.00248     |           |
| Y                         |       | 0.37596 | 0.38000    |         |          | -0.00404    |           |
| <b>POS_TOP\$PIN(1)</b>    |       |         | <b>POI</b> |         |          |             |           |
| POSITN                    |       | 0.00949 | 0.00000    | 0.00300 | 0.00000  | 0.00949     | 0.00649 ◀ |
| <b>TOP\$PIN(2)</b>        |       |         | <b>CIR</b> |         |          |             |           |
| FORM                      |       | 0.00001 |            |         |          |             |           |
| DM                        |       | 0.06267 |            |         |          |             |           |
| X                         |       | 2.79927 | 2.80000    |         |          | -0.00073    |           |
| Y                         |       | 0.37986 | 0.38000    |         |          | -0.00014    |           |
| <b>POS_TOP\$PIN(2)</b>    |       |         | <b>POI</b> |         |          |             |           |
| POSITN                    |       | 0.00149 | 0.00000    | 0.00300 | 0.00000  | 0.00149     |           |
| <b>BOT\$PIN(1)</b>        |       |         | <b>CIR</b> |         |          |             |           |
| FORM                      |       | 0.00006 |            |         |          |             |           |
| DM                        |       | 0.06267 |            |         |          |             |           |
| X                         |       | 2.38223 | 2.38400    |         |          | -0.00177    |           |
| Y                         |       | 1.40187 | 1.40200    |         |          | -0.00013    |           |
| <b>POS_BOT\$PIN(1)</b>    |       |         | <b>POI</b> |         |          |             |           |
| POSITN                    |       | 0.00355 | 0.00000    | 0.00300 | 0.00000  | 0.00355     | 0.00055 ◀ |
| <b>BOT\$PIN(2)</b>        |       |         | <b>CIR</b> |         |          |             |           |
| FORM                      |       | 0.00003 |            |         |          |             |           |
| DM                        |       | 0.06263 |            |         |          |             |           |
| X                         |       | 1.82855 | 1.82800    |         |          | 0.00055     |           |
| Y                         |       | 0.46754 | 0.46900    |         |          | -0.00146    |           |
| <b>POS_BOT\$PIN(2)</b>    |       |         | <b>POI</b> |         |          |             |           |
| POSITN                    |       | 0.00311 | 0.00000    | 0.00300 | 0.00000  | 0.00311     | 0.00011 ◀ |
| <b>BOT\$PIN(3)</b>        |       |         | <b>CIR</b> |         |          |             |           |
| FORM                      |       | 0.00005 |            |         |          |             |           |
| DM                        |       | 0.06263 |            |         |          |             |           |
| X                         |       | 1.15413 | 1.15300    |         |          | 0.00113     |           |
| Y                         |       | 0.46711 | 0.46900    |         |          | -0.00189    |           |
| <b>POS_BOT\$PIN(3)</b>    |       |         | <b>POI</b> |         |          |             |           |
| POSITN                    |       | 0.00440 | 0.00000    | 0.00300 | 0.00000  | 0.00440     | 0.00140 ◀ |
| <b>PLA_P364</b>           |       |         | <b>PLA</b> |         |          |             |           |
| FORM                      |       | 0.00032 |            |         |          |             |           |
| Z                         |       | 0.36398 |            |         |          |             |           |
| <b>PAR_A</b>              |       |         | <b>PLA</b> |         |          |             |           |
| PARALL                    |       | 0.00054 | 0.00000    | 0.00200 | 0.00000  | 0.00054     |           |

| Text                      | Eval. | Actual | Nominal  | Up.To1. | Low.To1. | Act-Nom     | Graphic |
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