SLAC Traveler for LCLS-II HXU Measurement Results

This traveler is intended to document the checking of the final magnetic measurements of an Undulator Segment performed on the Kugler bench in the Magnetic Measurement Facility (MMF) at SLAC after the completion of the tuning process. It contains basic performance indicators compared against tolerances as well as documentary information both in graphical and textual representation.

Serial number from magnet label:	29H129-MOSO-005
Device name from magnet label:	HXU-005

Measurement Procedure:

The measurements have been carried out after the undulator segment had been fully tuned according to the "LCLS-II Undulator Test Plan" (LCLS-TN-17-1).

Evaluation of Hall Probe Scans: Data Listings A

MATLAB function "EvaluateUndulatorField" on	08/17/2019 16:26	
A. SCAN PARAMETERS		
z Scanning Date & Time Range	08/09/2019 18:19 - 08/10/2019 14:42	
Undulator Temperature	20.1289±0.0075	°C
x axis position	0.000206	mm
y axis position	-0.025805	mm
Calibration Position	B	
Close Loop Encoder	Full Gap	
Dead Band Gap	0.12	μm
Total number of poles per strongback	260	
Number of full field poles	254	
Number of core poles	246	
First core pole #	8	
Last core pole #	253	
Average λ_u	26.002	mm
RMS λ_u	14.5	μm
Scans averaged	3	
Tuning Gap	9.002	mm
Commissioning Gap	7.905	mm

Evaluation of Hall Probe Scans at Tuning Gap: Data Listing B

MATLAB function "EvaluateUndulatorField" on	08/17/2019 16:26	
B. CORE EVALUATIONS FOR TUNING GAP		
Tuning Gap Scanning Date & Time Range	08/09/2019 23:24	
Tuning Gap Temperature	20.14±0.08	°C
Planar Hall Effect Correction Range	1.543000 - 4.868200	m
Planar Hall Effect x Corr Function	-0.02 G + (z - 1.543000 m)×0.08 G/m	
Planar Hall Effect y Corr Function	+0.21 G + (z - 1.543000 m)×-0.05 G/m	
Coil Range	1.405681 - 5.005681	m
$\langle \lambda_u \rangle$	26.002±0.001	mm
$\langle k_u \rangle$	241.65±0.01	1/m
$\langle K_u \rangle$	1.9928±0.0003	
$\langle K_{\mathrm{eff}} \rangle$ @ Tuning Temperature	1.99337±0.00001	
$\langle L_{\mathrm{eff}} \rangle$	3.32790±0.00004	m
$\langle L_{2\pi} \rangle$	0.077661±0.000003	m
I1X (Cell Range Total)	+4.40	μTm
I2X (Cell Range Total)	-31.91	μTm^2
I1Y (Cell Range Total)	-12.37	μTm
I2Y (Cell Range Total)	+4.20	μTm^2
PI (Cell Range Total)	19,209.4	T^2mm^3
Phase Shake	1.84	degXray
Cell Phase Advance (over 4.012667)	49,250.0 (137×360-70.0)	degXray
Undulator Entrance Phase	2486.5±0.1	degXray
Undulator Exit Phase	2483.5±0.1	degXray
Undulator Phase Imbalance: Entrance - Exit	2.9±0.2	degXray
Cell Entrance min. Phase Shifter Correction	33.5	degXray
Cell Exit min. Phase Shifter Correction	36.5	degXray

Evaluation of Hall Probe Scans at Commissioning Gap: Data Listing C

MATLAB function "EvaluateUndulatorField" on	08/17/2019 16:26	
C. CORE EVALUATIONS FOR COMMISSIONING GAP		
Commissioning Gap Scanning Date & Time Range	08/09/2019 23:24	
Commissining Gap Temperature	20.14±0.08	°C
Planar Hall Effect Correction Range	1.543200 - 4.868200	m
Planar Hall Effect x Corr Function	-0.12 G + (z - 1.543200 m)×0.12 G/m	
Planar Hall Effect y Corr Function	+0.30 G + (z - 1.543200 m)×-0.06 G/m	
Coil Range	1.405680 - 5.005680	m
$\langle \lambda_u \rangle$	26.002±0.001	mm
$\langle k_u \rangle$	241.65±0.01	1/m
$\langle K_u \rangle$	2.3392±0.0003	
$\langle K_{\text{eff}} \rangle$ @ Tuning Temperature	2.33965±0.00001	
$\langle L_{\text{eff}} \rangle$	3.32638±0.00004	m
$\langle L_{2\pi} \rangle$	0.097168±0.000004	m
I1X (Cell Range Total)	-2.44	μTm
I2X (Cell Range Total)	-33.68	μTm^2
I1Y (Cell Range Total)	-14.99	μTm
I2Y (Cell Range Total)	-5.14	μTm^2
PI (Cell Range Total)	26,451.0	T^2mm^3
Phase Shake	1.93	degXray
Cell Phase Advance (over 4.012667 m)	48,597.3 (135×360-2.7)	degXray
Undulator Entrance Phase	2160.7 (12×180+0.7)±0.1	degXray
Undulator Exit Phase	2156.7 (12×180-3.3)±0.1	degXray
Undulator Phase Imbalance: Entrance - Exit	4.0±0.2	degXray
Cell Entrance min. Phase Shifter Correction	359.3	degXray
Cell Exit min. Phase Shifter Correction	3.3	degXray

Undulator Encoder Settings: Data Listing D

MATLAB function "EvaluateUndulatorField" on	08/17/2019 16:35	
D. ENCODER SETTINGS		
Upstream Gap Encoder Offset	-41.3275	mm
Downstream Gap Encoder Offset	-41.7658	mm
Upstream Wall Encoder Offset	91.37850	mm
Downstream Wall Encoder Offset	89.99560	mm
Upstream Aisle Encoder Offset	89.99780	mm
Downstream Aisle Encoder Offset	91.03740	mm

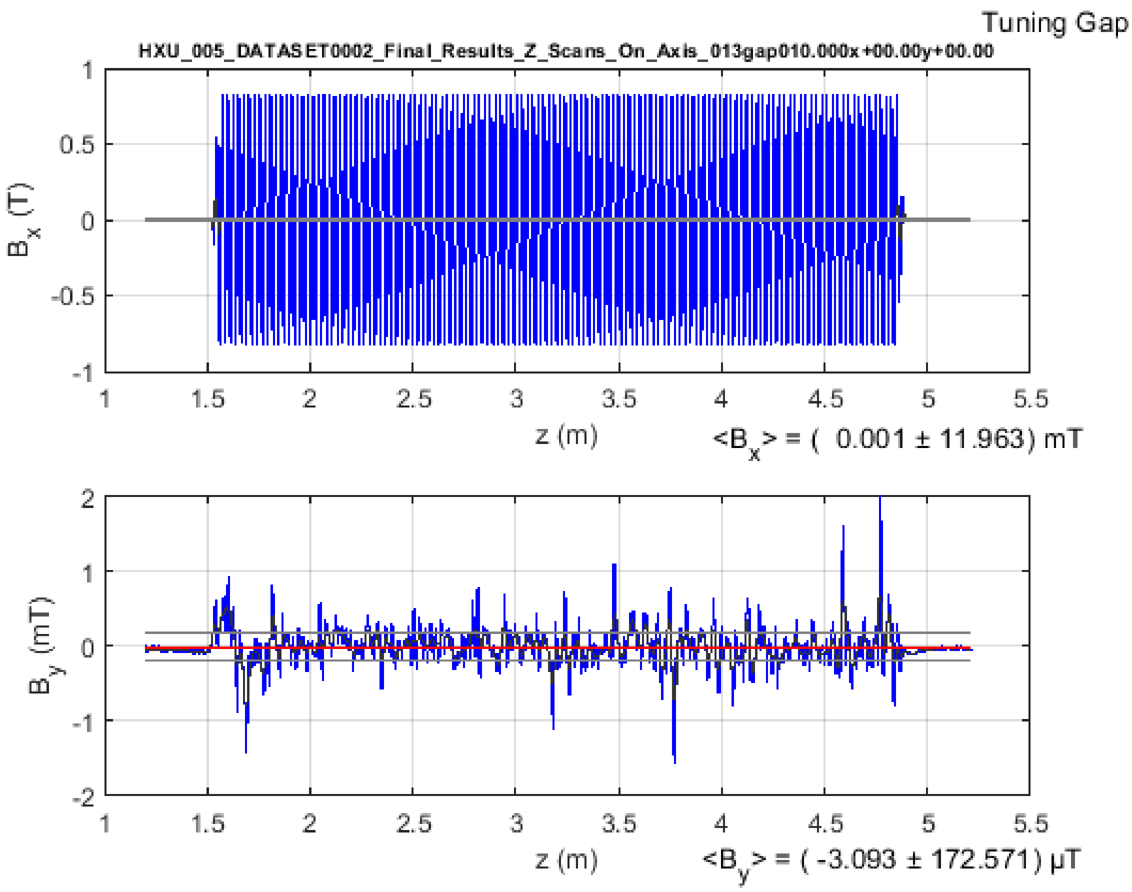
Undulator Capacitive Sensor Values: Data Listing E

E. CAPACITIVE SENSOR VALUES

Module	Pole	Capacitive Sensor Gap	Upstream Encoder	Downstream Encoder	
Ref	—	46.4776	29.4994	29.4998	mm
Ref	—	46.4776	29.4994	29.4998	mm
1	20	46.5436	46.4999	46.4999	mm
1	20	46.5436	46.4999	46.4999	mm
1	60	46.5431	46.4999	46.4999	mm
1	60	46.5431	46.4999	46.4999	mm
1	20	46.5436	46.4999	46.4999	mm
1	20	46.5436	46.4999	46.4999	mm
1	60	46.5431	46.4999	46.4999	mm
1	60	46.5431	46.4999	46.4999	mm
1	20	46.5436	46.4999	46.4999	mm
1	20	46.5436	46.4999	46.4999	mm
1	60	46.5431	46.4999	46.4999	mm
1	60	46.5431	46.4999	46.4999	mm
Ref	—	46.4776	29.4994	29.4998	mm
Ref	—	46.4776	29.4994	29.4998	mm

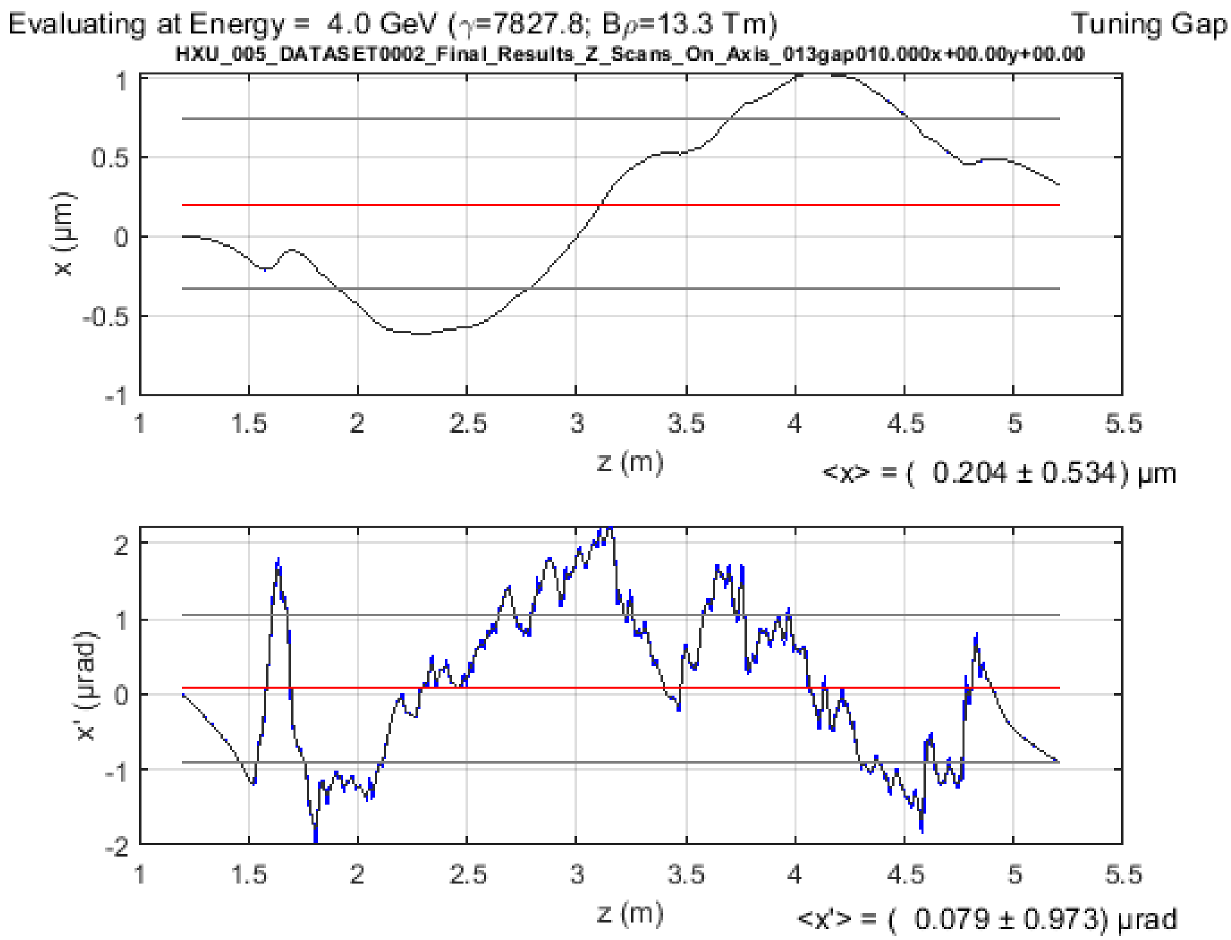
The following figures show result of the field analysis at the tuning gap.

Evaluation of Hall Probe at Tuning Gap: B_x & B_y Plot



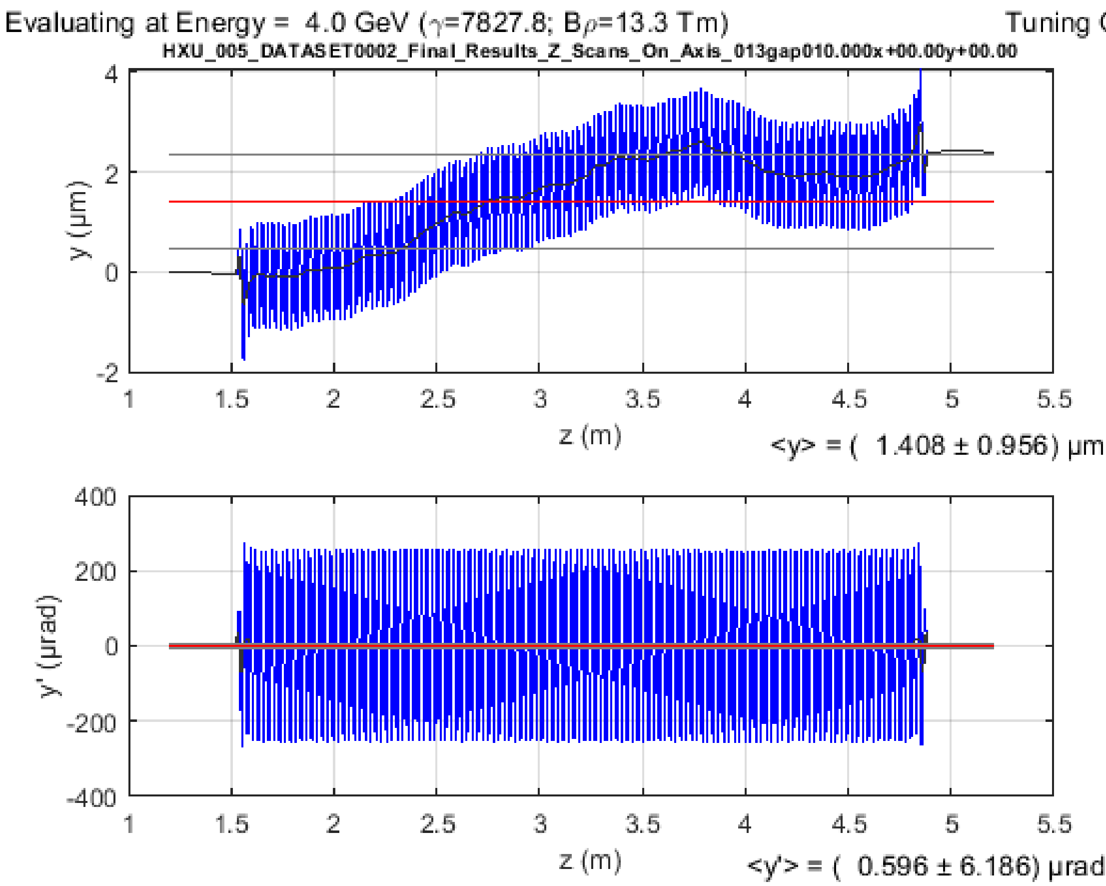
The figures show the x (upper) and y (lower) field components along the undulator tuning axis for the tuning gap. A running wiggler-period-average function is plotted in black (not very well visible in the lower figure). The horizontal lines indicate the mean (center red line) and the rms deviations from the mean (two black lines above and below the average) of that wiggler-period-average function. The corresponding mean and rms values are also printed on the right hand side underneath each figure. [Documentary Information]

Evaluation of Hall Probe at Tuning Gap: x & x' Plot



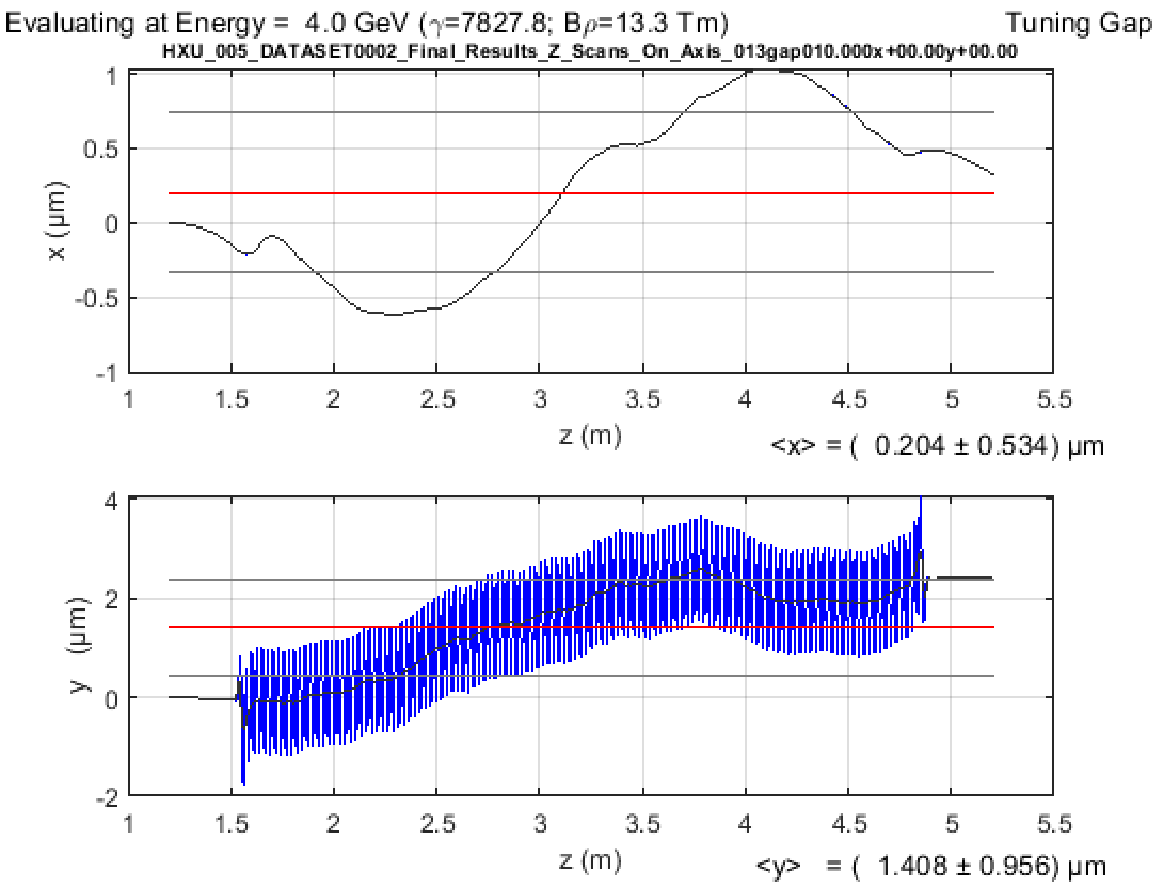
The figures show the x (upper) and x' (lower) electron beam trajectories along the undulator tuning axis for the tuning gap based on the measured magnetic field components and estimated for an electron beam energy of 4.0 GeV. A running wiggler-period-average function is plotted in black (difficult to see in the lower figure). The horizontal lines indicate the mean (center red line) and the rms deviations from the mean (two black lines above and below the average) of that wiggler-period-average function. The corresponding mean and rms values are also printed on the right hand side underneath each figure. [Documentary Information]

Evaluation of Hall Probe Scans at Tuning Gap: y & y' Plot



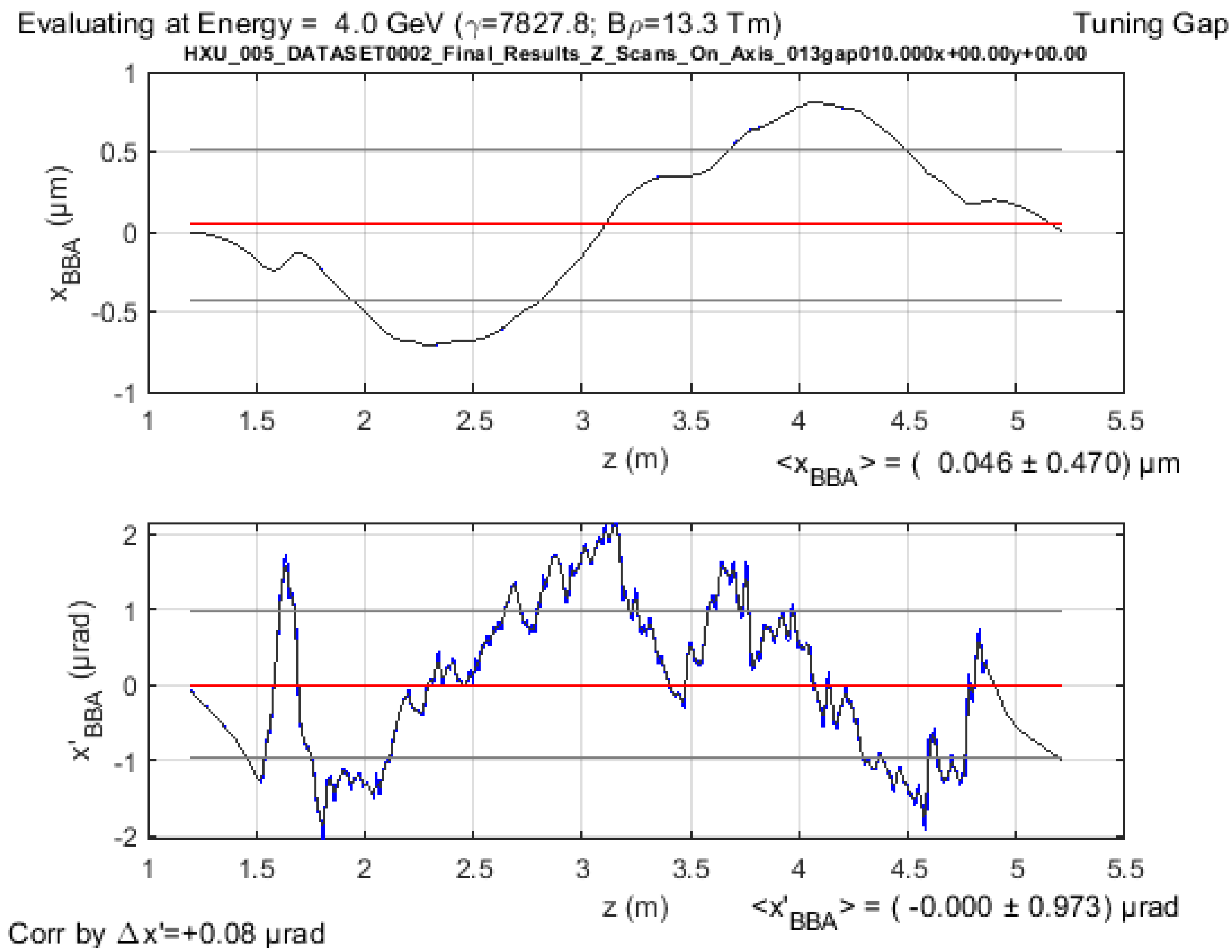
The figures show the y (upper) and y' (lower) electron beam trajectories along the undulator tuning axis for the tuning gap based on the measured magnetic field components and estimated for an electron beam energy of 4.0 GeV. A running wiggler-period-average function is plotted in black (difficult to see). The horizontal lines indicate the mean (center red line) and the rms deviations from the mean (two black lines above and below the average) of that wiggler-period-average function. The corresponding mean and rms values are also printed on the right hand side underneath each figure. [Documentary Information]

Evaluation of Hall Probe Scans at Tuning Gap: x & y Plot



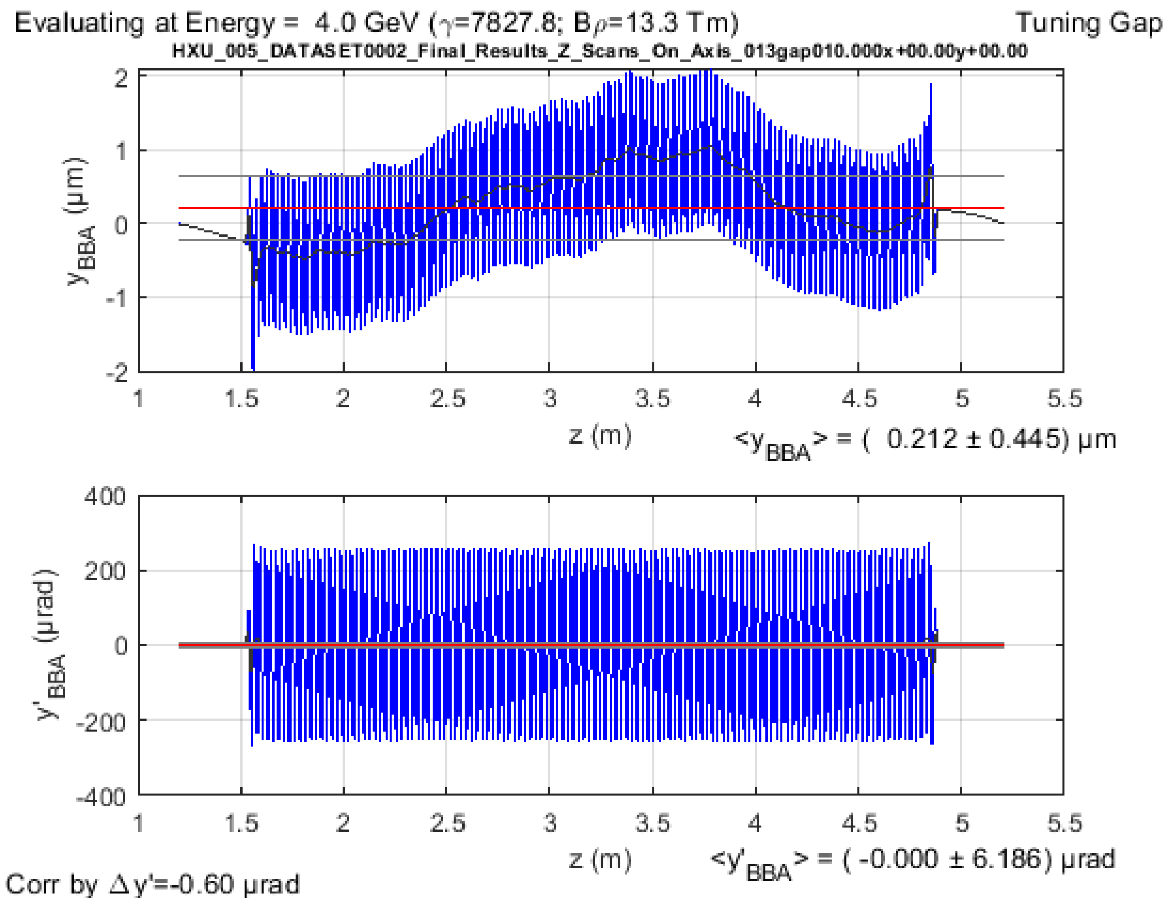
The figures show the x (upper) and y (lower) electron beam trajectories along the undulator tuning axis for the tuning gap based on the measured magnetic field components and estimated for an electron beam energy of 4.0 GeV. A running wiggler-period-average function is plotted in black (identical with the trajectory in the lower figure). The horizontal lines indicate the mean (center red line) and the rms deviations from the mean (two black lines above and below the average) of that wiggler-period-average function. The corresponding mean and rms values are also printed on the right hand side underneath each figure. [Documentary Information]

Evaluation of Hall Probe plus BBA Correction at Tuning Gap: x & x' Plot



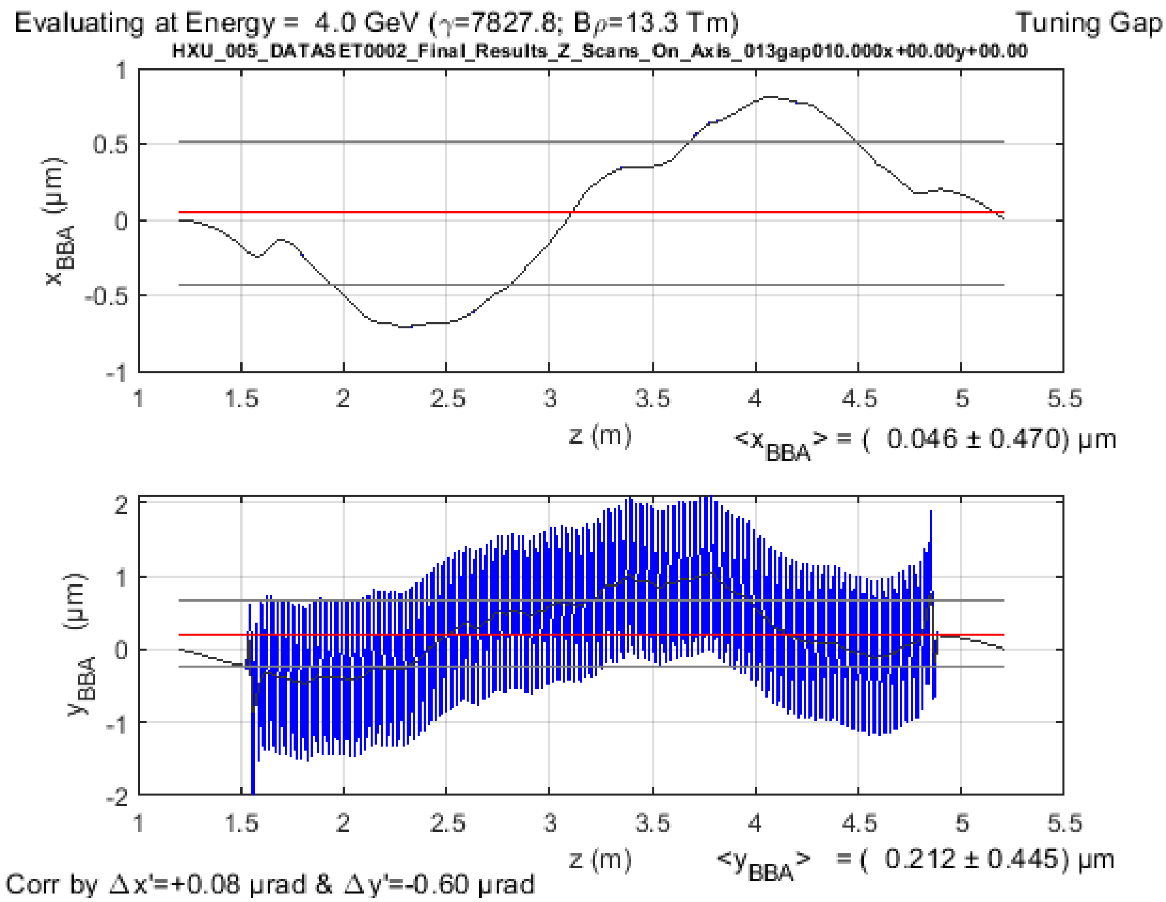
The figures show the x (upper) and x' (lower) electron beam trajectories along the undulator tuning axis for the tuning gap based on the measured magnetic field components after BBA correction (to zero the amplitudes at the cell boundaries) and estimated for an electron beam energy of 4.0 GeV. A running wiggler-period-average function is plotted in black (difficult to see in the lower figure). The horizontal lines indicate the mean (center red line) and the rms deviations from the mean (two black lines above and below the average) of that wiggler-period-average function. The corresponding mean and rms values are also printed on the right hand side underneath each figure. The amount of BBA correction applied is printed underneath the lower left corner of the lower figure. [Documentary Information]

Evaluation of Hall Probe plus BBA Correction at Tuning Gap: y & y' Plot



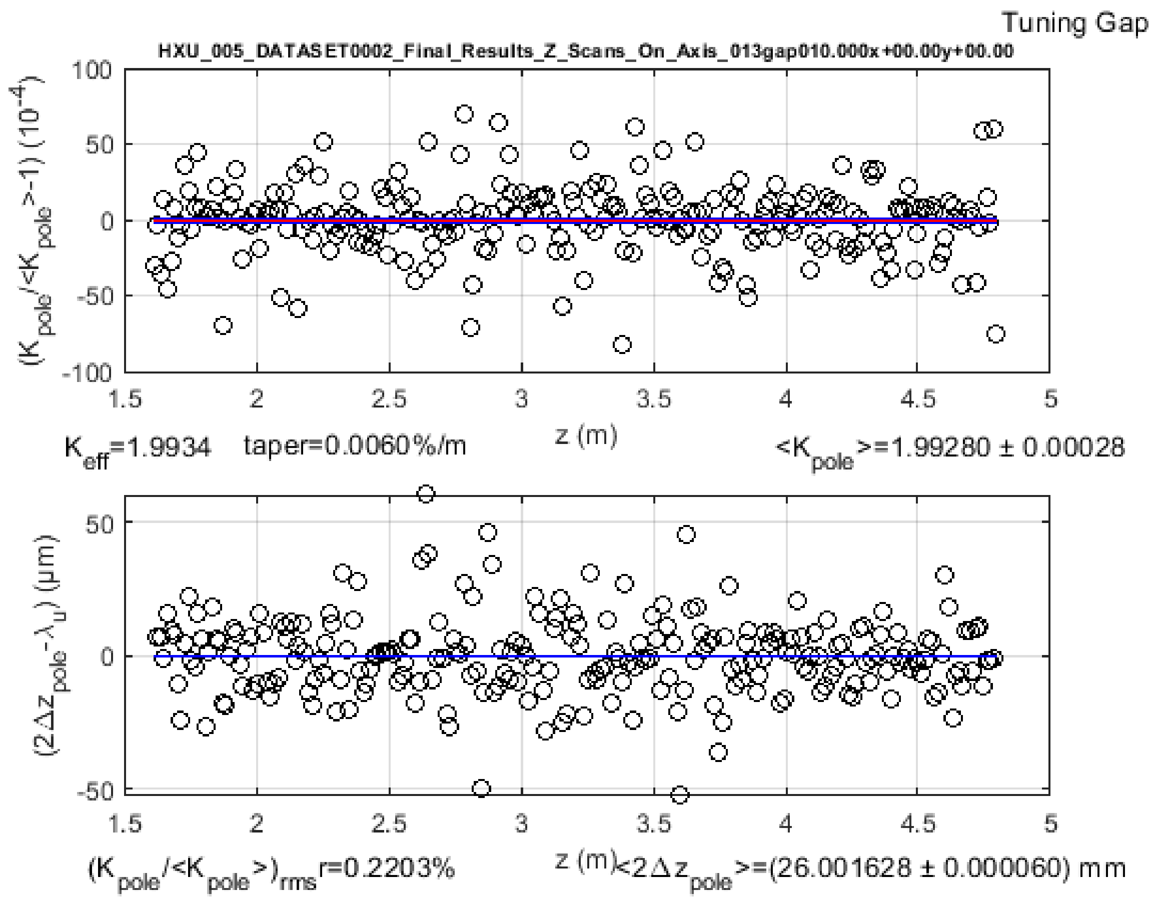
The figures show the y (upper) and y' (lower) electron beam trajectories along the undulator tuning axis for the tuning gap based on the measured magnetic field components after BBA correction (to zero the amplitudes at the cell boundaries) and estimated for an electron beam energy of 4.0 GeV. A running wiggler-period-average function is plotted in black (identical with the trajectories). The horizontal lines indicate the mean (center red line) and the rms deviations from the mean (two black lines above and below the average) of that wiggler-period-average function. The corresponding mean and rms values are also printed on the right hand side underneath each figure. The amount of BBA correction applied is printed underneath the lower left corner of the lower figure. [Documentary Information]

Evaluation of Hall Probe plus BBA Correction at Tuning Gap: x & y Plot



The figures show the x (upper) and y (lower) electron beam trajectories along the undulator tuning axis for the tuning gap based on the measured magnetic field components after BBA correction (to zero the amplitudes at the cell boundaries) and estimated for an electron beam energy of 4.0 GeV. A running wiggler-period-average function is plotted in black (identical with the trajectory in the lower figure). The horizontal lines indicate the mean (center red line) and the rms deviations from the mean (two black lines above and below the average) of that wiggler-period-average function. The corresponding mean and rms values are also printed on the right hand side underneath each figure. The amount of BBA correction applied is printed underneath the lower left corner of the lower figure. [Documentary Information]

Evaluation of Hall Probe at Tuning Gap: K and λ_u Plot



The figures show the per-pole undulator strength K_{pole} (upper) and the deviation of the pole width from the expected value of $\lambda_u/2$ (lower) for the 246 core undulator poles for the tuning gap. The horizontal lines indicate the mean (center red line) and the rms deviations from the mean (two black lines above and below the average). The corresponding mean and rms values are also printed on the right hand side underneath each figure. [Documentary Information]

For description of K calculation see next page.

K calculation description for previous page:

The undulator parameter, K_{pole}, in the upper figure, is calculated for each of the core poles based on the scanned vertical field values $B_y(z)$ as well as an interpolation of the upstream, $z_{(0-dn,pole)}$, and downstream, $z_{(0-up,pole)}$, field zero crossing locations using the following formula:

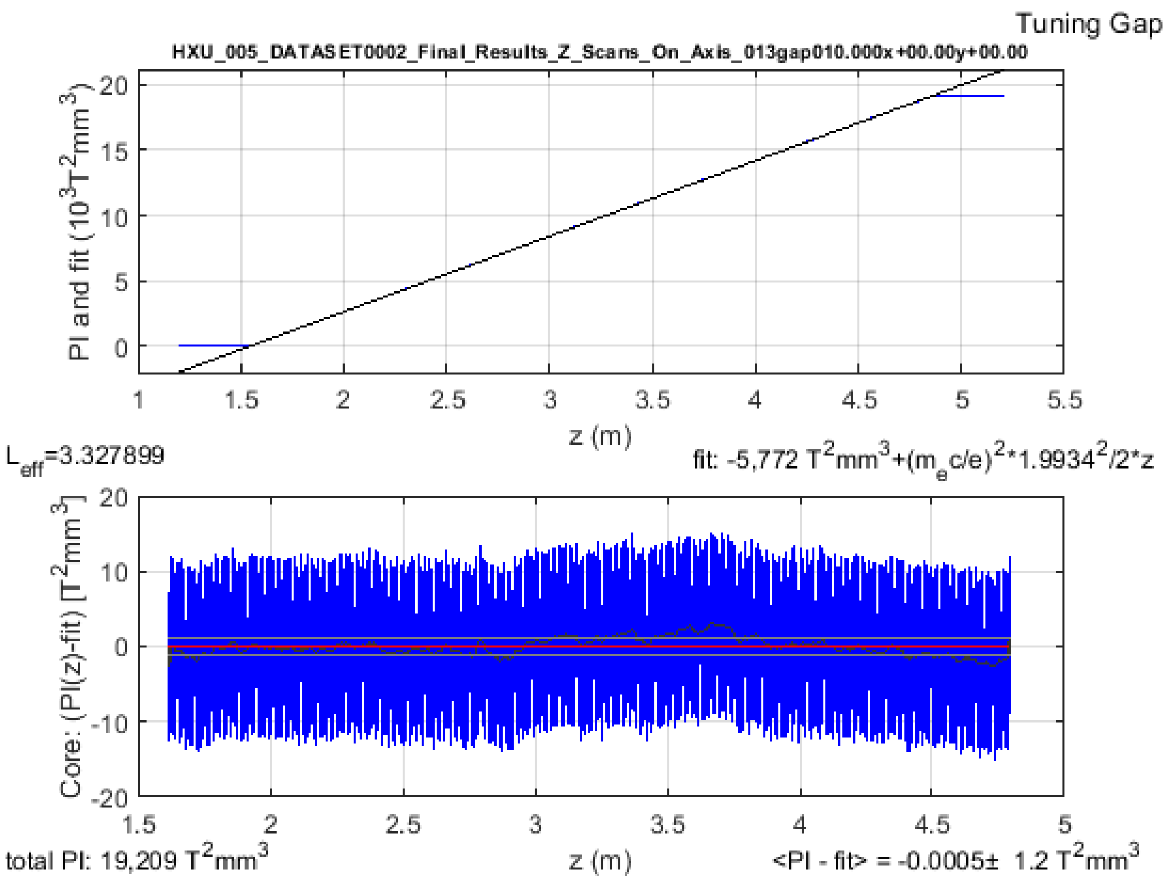
$$K_{pole}(z_{pole}) = \frac{\Delta z_{pole}}{2\pi}\frac{e}{m_e c}\sqrt{\frac{2}{\Delta z_{pole}}\int_{z_{0-up,pole}}^{z_{0-dn,pole}} B_y^2(\hat{z})\,d\hat{z}}$$

The term $\frac{e}{m_e c}$ uses the electron mass, m_e, the speed of light, c, and the electron's electric charge, e. The variable Δz_{pole} stands for

$$\Delta z_{pole} = z_{0-dn,pole} - z_{0-up,pole}$$

$$z_{pole} \approx \frac{1}{2}(z_{0-dn,pole} + z_{0-up,pole})$$

Evaluation of Hall Probe Scans for Tuning Gap: Phase Integral Plot



A description of the figure is given on the next page:

Figure description for previous page:

The upper figure shows the phase integral of an electron calculated from the measured on-axis magnetic field components for the tuning gap:

$$PI(z) = \int_0^z BL_{x1}^2(\hat{z})\,d\hat{z} + \int_0^z BL_{y1}^2(\hat{z})\,d\hat{z}$$

with

$$BL_{x1,y1}(z) = \int_0^z B_{x,y}(\hat{z})\,d\hat{z} - \frac{1}{L}\int_0^L \left\{ \int_0^{\tilde{z}} B_{x,y}(\hat{z})\,d\hat{z} \right\} d\tilde{z}.$$

The function

$$\overline{PI}(z) = \overline{PI}(0) + z\left(\frac{mc}{e}\right)^2 \frac{1}{2}K_{\text{eff}}^2,$$

fitted to the measured phase integral $PI(z)$ (along the undulator core) with fit coefficients $\left(\frac{mc}{e}\right)^2 \frac{1}{2}K_{\text{eff}}^2$ and can be seen as a straight black line in the upper plot. The values of the fit coefficients are printed at the right hand side underneath the upper figure. On the lower left of the upper figure the effective undulator length is printed, which is obtained as the distance over the undulator core, where the blue and black lines in the plot are on top of each other: $L_{\text{eff}} = PI(z_{max}) / \left(\frac{d\overline{PI}(z)}{dz}\right)$.

The lower figure shows the residuals between the phase integral and the fit function over the core part of the undulator magnet. A running wiggler-period-averaged function is plotted in black. The horizontal lines indicate the mean (center red line) and the rms deviations from the mean (two blue lines above and below the mean) of that wiggler-period-averaged function. The corresponding mean and rms values are also printed on the right hand side underneath the figure. On the lower left of the plot, the total phase integral accumulated along the undulator magnet, is shown, i.e., $PI(z_{max})$, the right-hand side value of the blue line in the upper plot.

The wiggler period averaged phase, $\langle\Phi\rangle_{\lambda_u}(z)$ can be calculated from $PI(z)$ via

$$\langle\Phi\rangle_{\lambda_u}(z) = \frac{2\pi}{L_{2\pi}}\left(\frac{e}{mc}\right)^2 \int_{z-\frac{\lambda_u}{2}}^{z+\frac{\lambda_u}{2}} \left(PI(\hat{z}) - \overline{PI}(\hat{z})\right) d\overline{z},$$

integrated over the undulator core.

Here $L_{2\pi} = \lambda_u\left(1 + \frac{1}{2}K_{eff}^2\right)$ (see next figure) is the free space distance over which a phase slippage of 2π occurs. The phase shake, $\langle\Delta\phi\rangle_{rms}$, which will be discussed later in this document, is calculated as

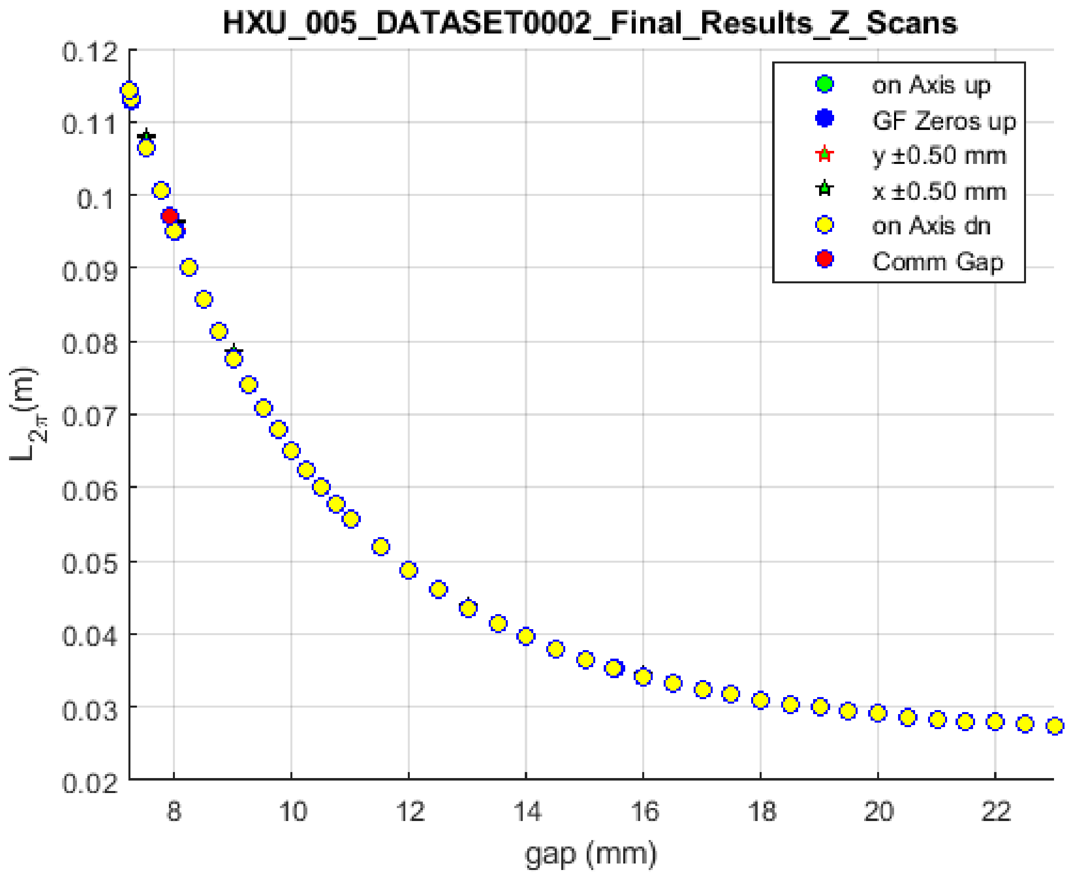
$$\langle\Delta\phi\rangle_{rms} = \left(\Delta\langle\Phi\rangle_{\lambda_u}\right)_{rms} = \left(\langle\Phi\rangle_{\lambda_u}(z) - \langle\langle\Phi\rangle_{\lambda_u}(z)\rangle\right)_{rms}$$

The cell phase $\phi(z)$ is calculated over the entire cell length (not just the undulator core)

$$\phi(z) = \frac{360\text{ degXray}}{L_{2\pi}}\left(z - z_{center} + \left(\frac{e}{mc}\right)^2 PI(z)\right).$$

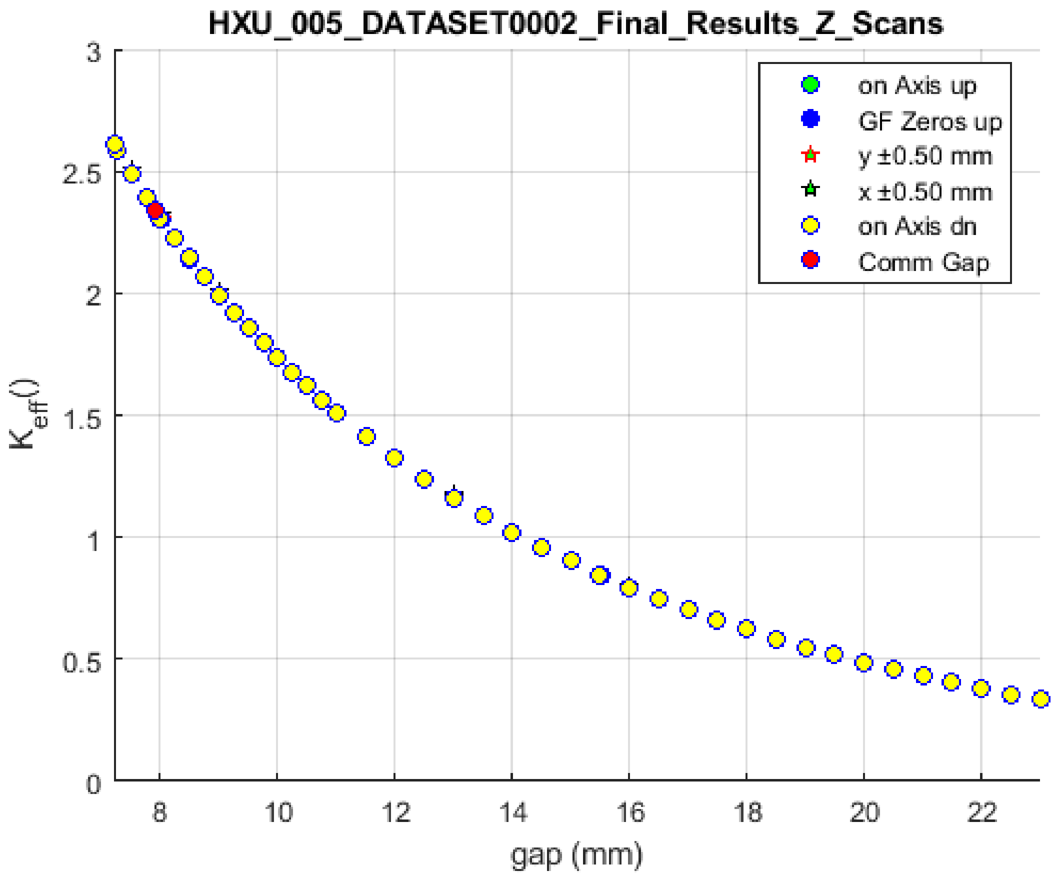
The following figures show the results of the gap dependent analysis.

Evaluation of Hall Scans: $L_{2\pi}$ vs gap



The figure shows the free space distance over which a 2π slippage occurs between the radiation field and the electron bunch (see explanation above) as a function of undulator gap over the operational gap range. Note: the free space travel distance required to accumulate 2π slippage gets shorter towards larger gap values, which correspond to shorter undulator wavelengths. [Documentary Information]

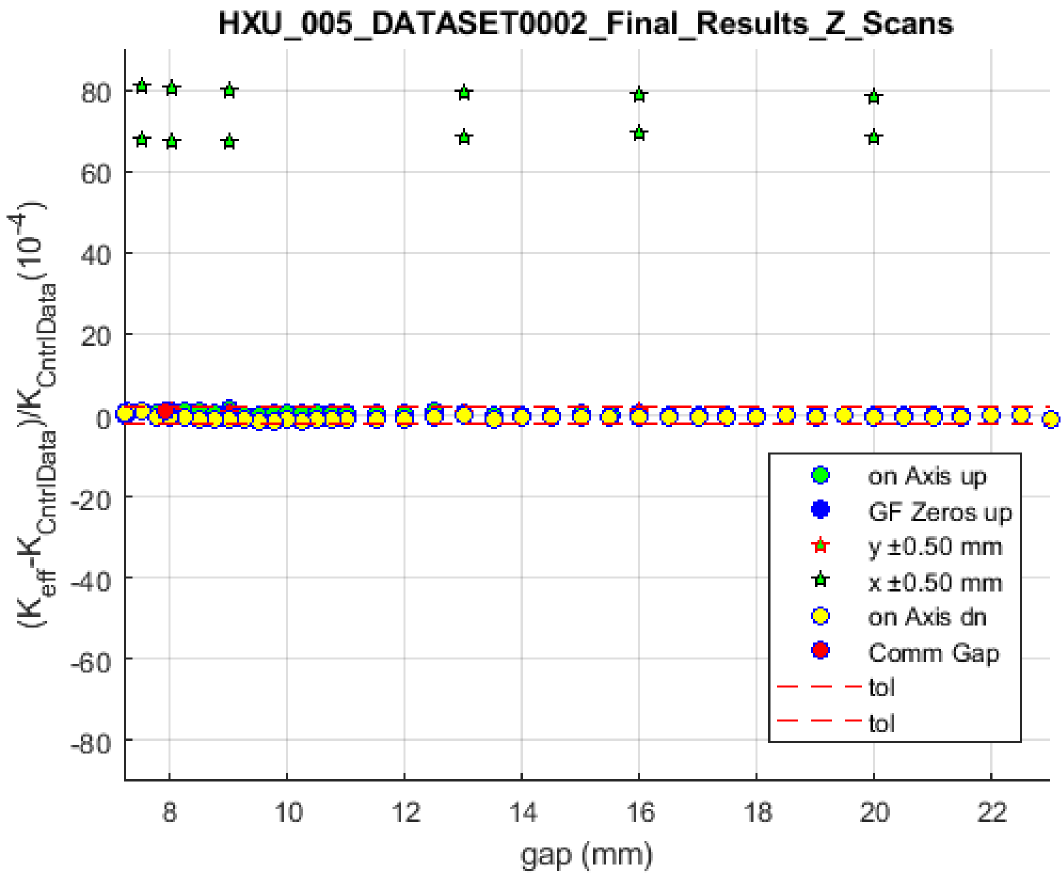
Evaluation of Hall Scans: K_{eff} vs gap



The figure shows undulator strength K_{eff} as a function of gap over the 7.2 mm—20 mm operational range. The legend shows a number of different cases that will be explained later in this document because their effect cannot be observed in this full scale plot. Note: The gap values are derived from the readings of the two gap encoders installed on the HXU. In that sense these are nominal gap numbers that will be close but not identical to each of the individual pole separations measured across the undulator gap.

The continuous conversion between the two axes (i.e. K_{eff}(gap) and gap(K_{eff})) will be done during operations based on the list of reference data points stored in file `hxu_005_k_vs_gap_spline.dat` in the Controls Data folder on the V: drive (see final section of this document for file information). From that list K_{eff}(gap) and gap(K_{eff}) can be calculated via cubic spline fits or equivalent. [Documentary Information]

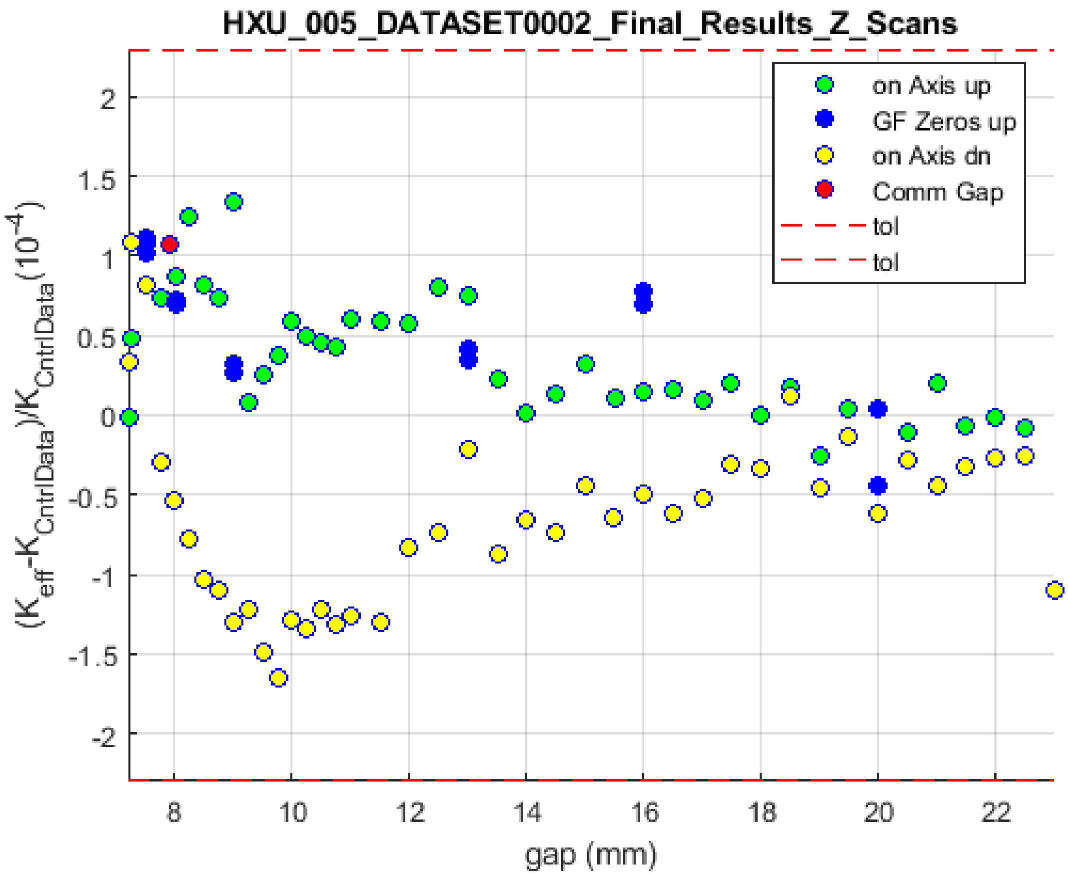
Evaluation of Hall Scans: $K_{\text{eff}} - K_{\text{control}}$ vs gap



The figure shows the relative difference between the measured undulator strength Keff and a cubic spline fit to the list of reference data points stored in file `hxu_005_k_vs_gap_spline.dat` in the Controls Data folder on the V: drive as a function of gap over the 7.2 mm—20 mm operational range.

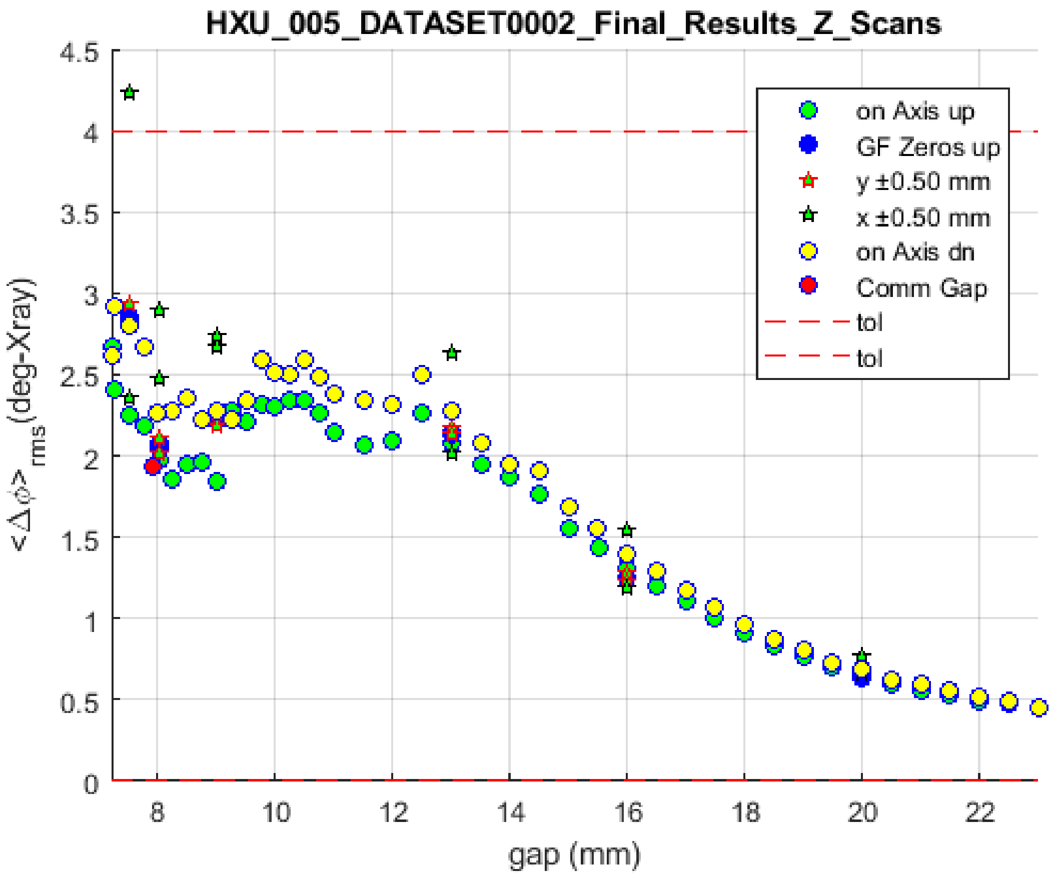
The legend explains the different cases that are shown in the plot: The green filled circles are data acquired on axis as the gap was changed from close to open. The yellow filled circles are data acquired on axis as the gap was changed from open to close. The horizontal red dashed lines show the tolerance limits. Note: The undulator K_{eff} value shows a hysteresis, i.e., for a given gap, the value depends on the direction of gap motion to reach that gap. While this is not a desirable feature, its effect stays within the given tolerance and will be acceptable. The other symbols shown indicate off-axis measurements that are added for interest only. The tolerance limits apply for on-axis readings, only.

Evaluation of Hall Scans: $(K_{\text{eff}} - K_{\text{CntrlData}}) / K_{\text{CntrlData}}$ vs gap



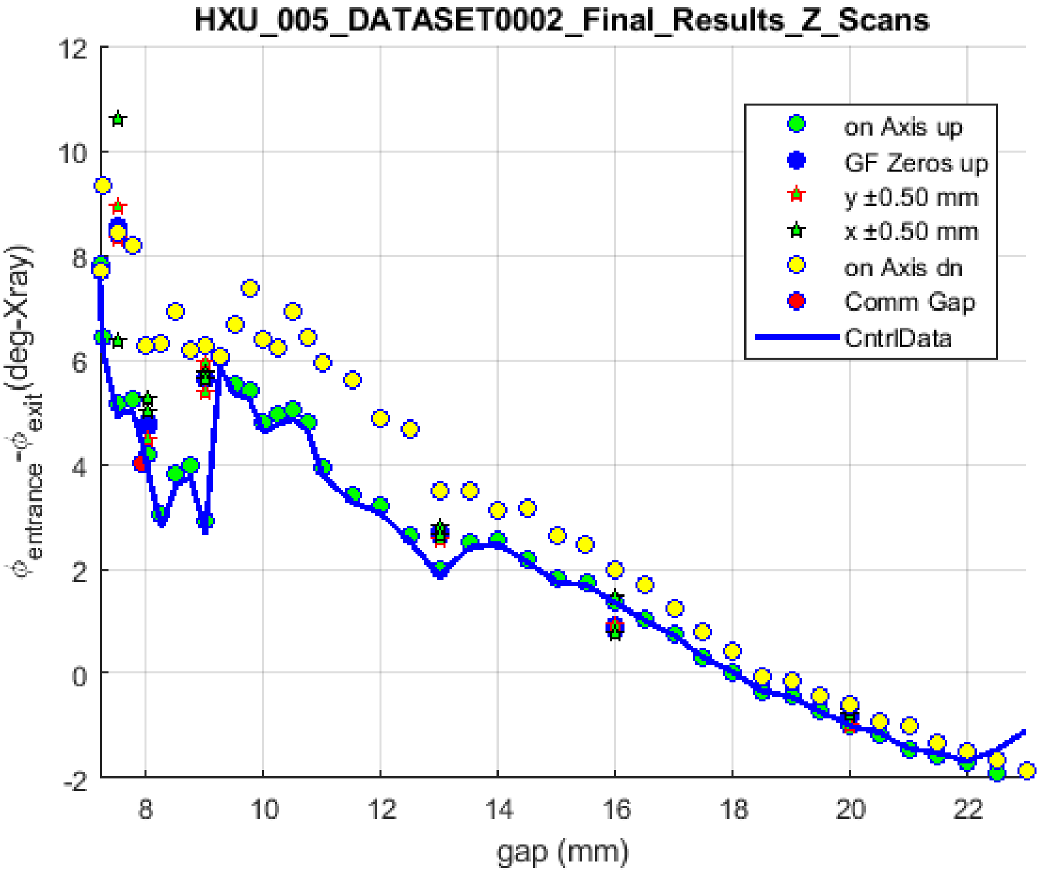
The figure shows some of the data shown in the previous figure but with a larger vertical scale that just captures the tolerance range. The off-axis measurements are not shown.

Evaluation of Hall Scans: Phase Shake vs gap



The figure shows the phase shake, $\langle\Delta\phi\rangle_{rms}$, (see above) as a function of operational gap. The vertical axis extends over the entire tolerance range. The values show a slight hysteresis (show explanation above) but are well within tolerance.

Evaluation of Hall Probe: Entrance to Exit Phase Error Balance vs. gap



The figure shows a (negligible) imbalance of the entrance (cell boundary start to undulator core) to the exit (undulator core to cell boundary end) phase slippage for the undulator. In addition to the signals described above, the blue curve is a spline fit to the difference of the data in files

"`..._phase_match_enter_vs_gap_spline.dat`"
"`..._phase_match_exit_vs_gap_spline.dat`".

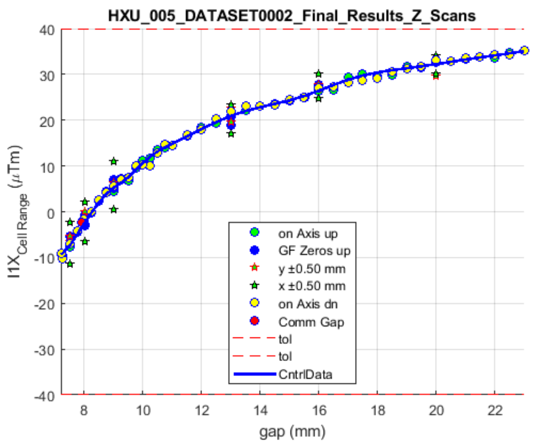
The small change in phase difference between opening and closing measurements shows the effect of gap hysteresis. The explanation for the legend items can be found on previous pages above. The entrance and exit phase slippage is calculated as

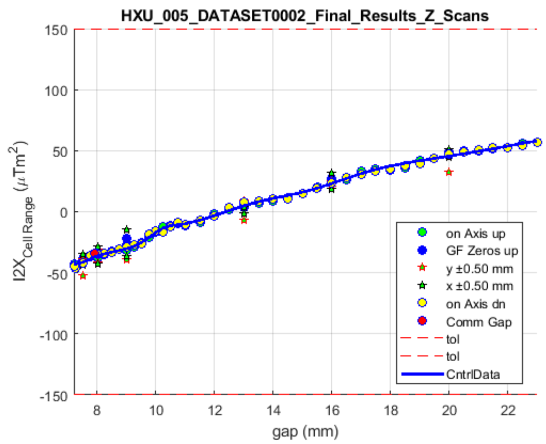
$$\phi_{\text{entrance}} = -\phi\left(z_{\text{Cell-Start}}\right) + \frac{1}{n+1}\sum_{j=1}^{n+1}\left(\phi\left(zB0,j\right) - \pi\left(j-1\right)\right).$$

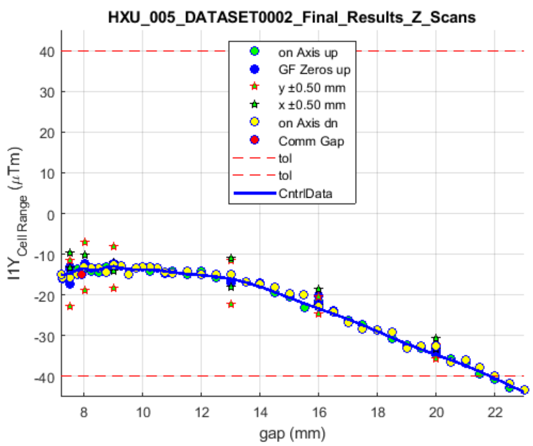
$$\phi_{\text{exit}} = -\phi\left(z_{\text{Cell-End}}\right) - \frac{1}{n+1}\sum_{j=1}^{n+1}\left(\phi\left(zB0,j\right) + \pi\left(n+1-j\right)\right).$$

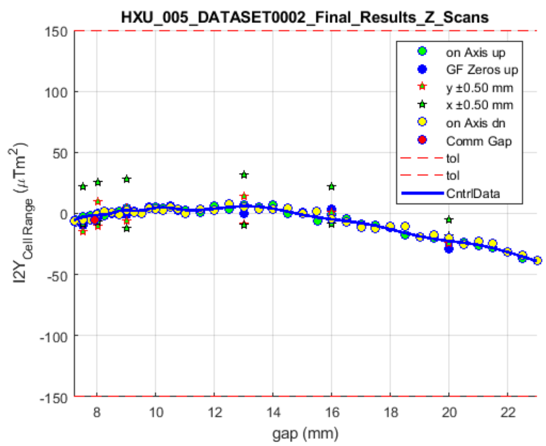
Here, $z_{(B0,j)}$ is the z location of the zero crossing of $B_y(z)$ in front of the j^{th} core B_y peak. $z_{(B0,(n+1))}$ is the z location of the field zero of $B_y(z)$ after the last core B_y peak.

Evaluation of Hall Probe: Field Integrals vs. gap







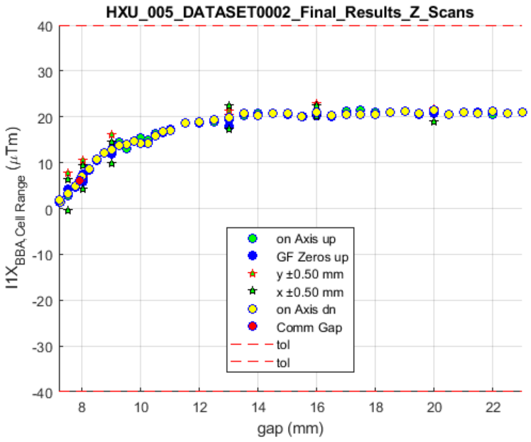


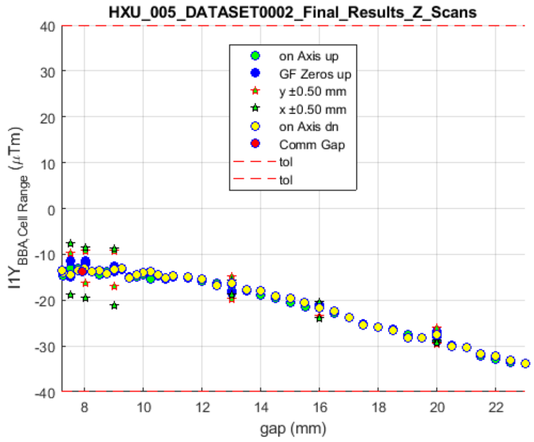
The figures show the field integrals (I1X, I2X, I1Y, I2Y) as functions of the operational gap. The proximity of the green and yellow circles shows that the field integrals are not sensitive to the hysteresis in K as seen on a previous page. The blue curves are spline fits to the data in files

"...i1xvsgap_spline.dat",
"...i2xvsgap_spline.dat",
"...i1yvsgap_spline.dat",
"...i2yvsgap_spline.dat",

and demonstrate how the controls representations of the field integrals relates to the actual measurements (see final section of this document for file information).

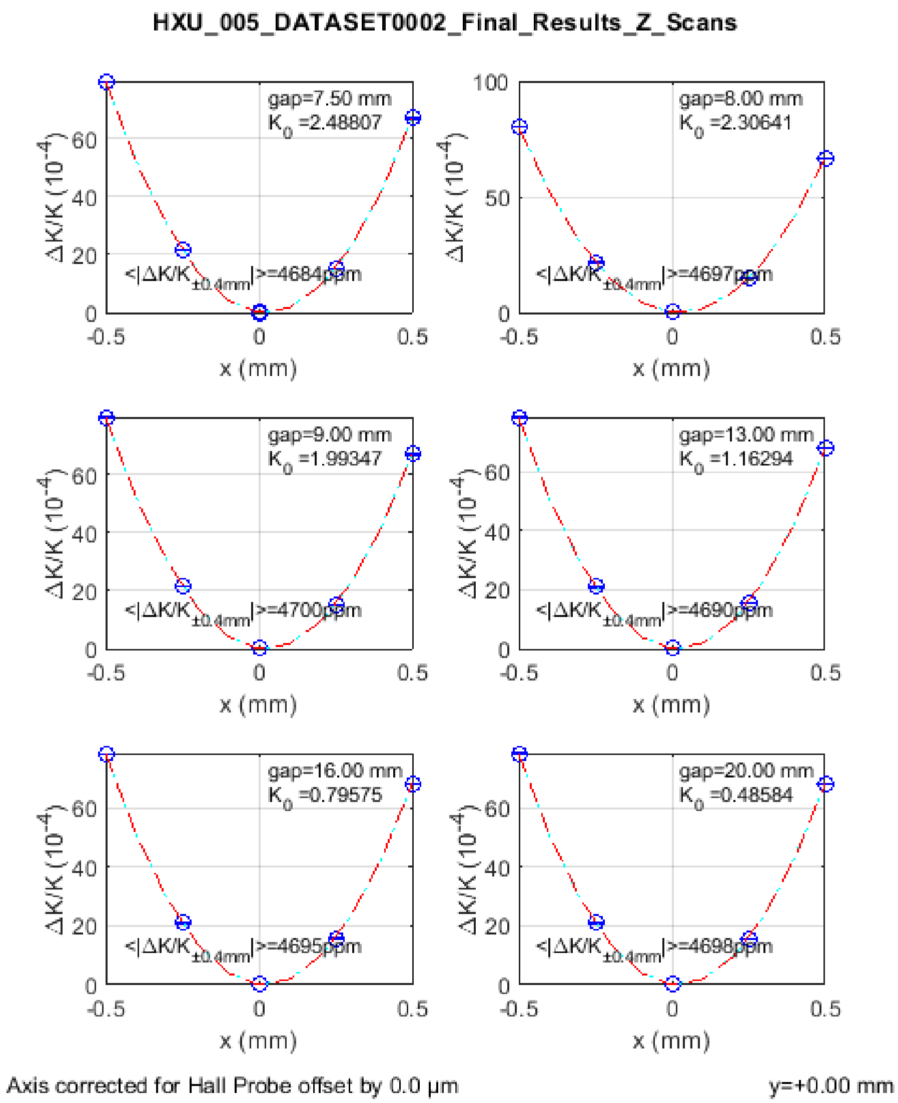
Evaluation of Hall Probe: BBA Field Integrals





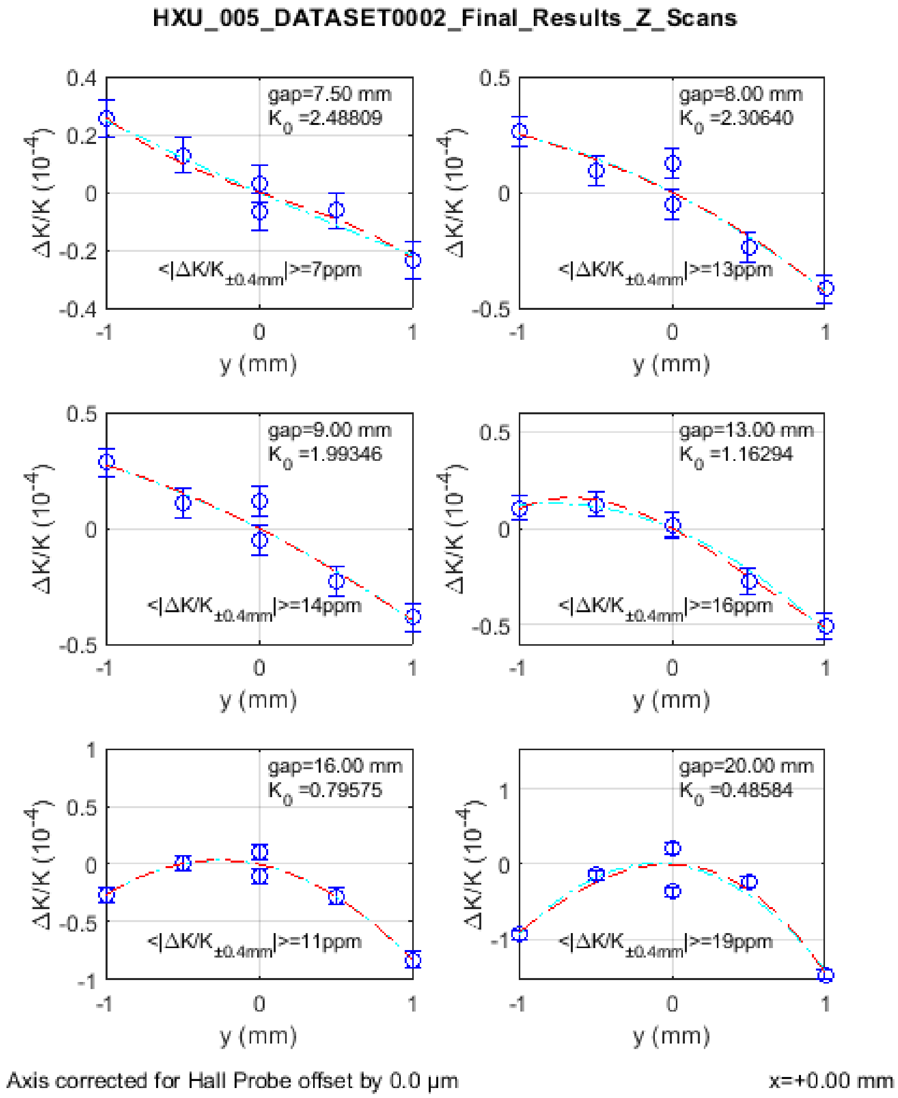
The figure shows the first integrals after a BBA equivalent correction was applied. The values stay within tolerance over the operational range.

Evaluation of Hall Scans: K vs. x dependence



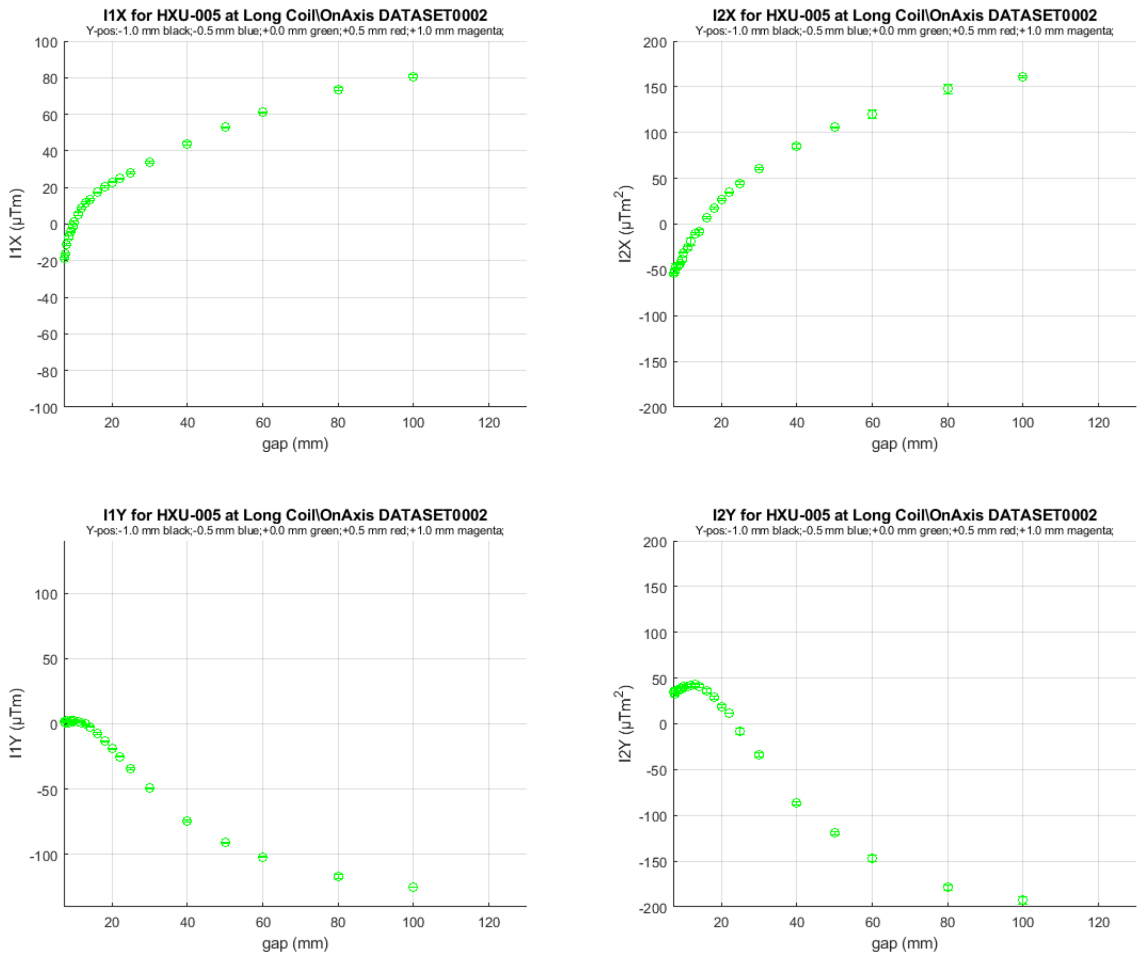
The figure shows the deviation of the relative undulator strength, K, from the off-axis value, K_0, as function of x at a number of operational gaps. The deviations follow closely the expected functional form $(\cosh\,(k_u y) - 1)$.

Evaluation of Hall Scans: K vs. y dependence



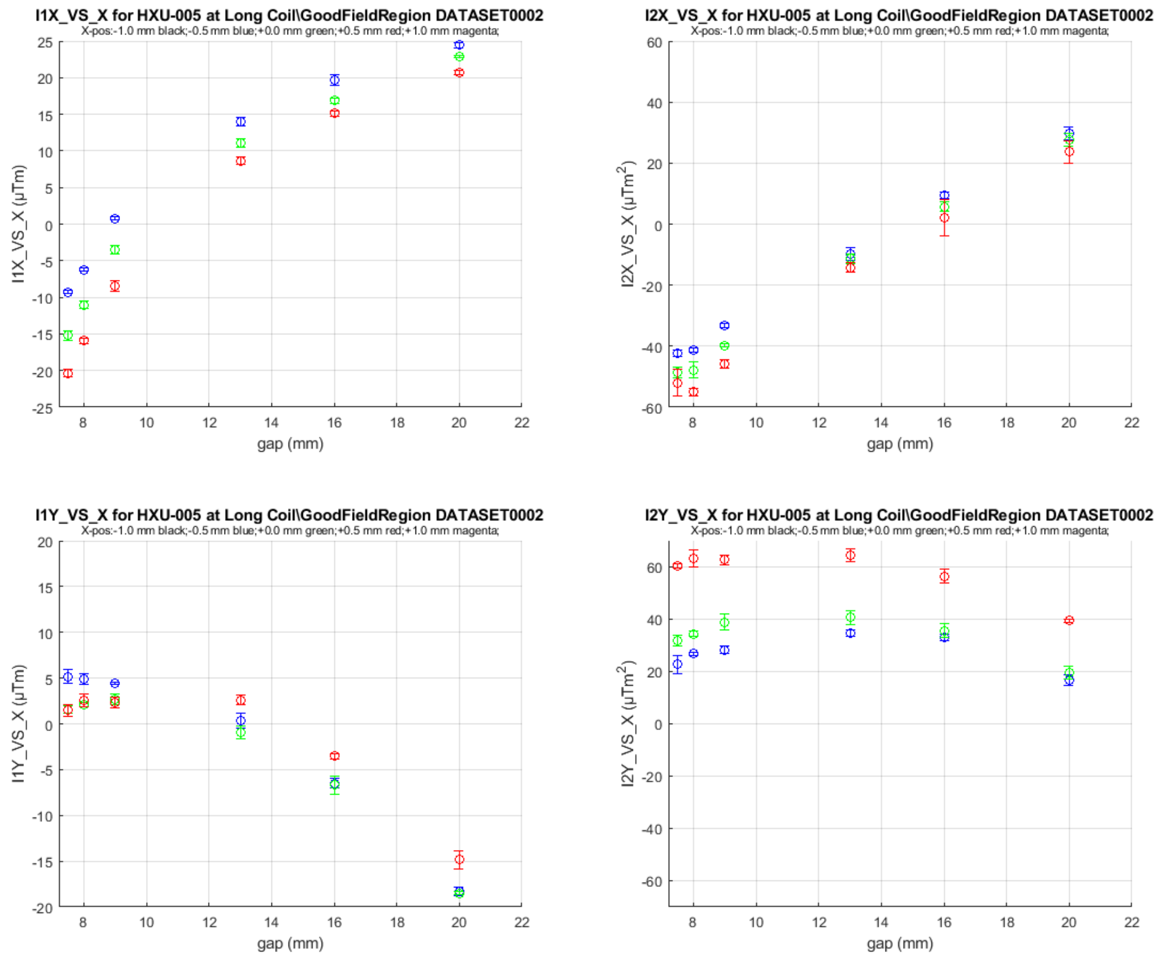
The figure shows the deviation of the relative undulator strength, K, value from the on-axis value, K_0, as function of y at a number of operational gaps. The average deviation at $z = 0.4$ mm is well below the tolerance of 160 ppm in all cases.

Long Coil Measurement of the On-Axis Field Integrals



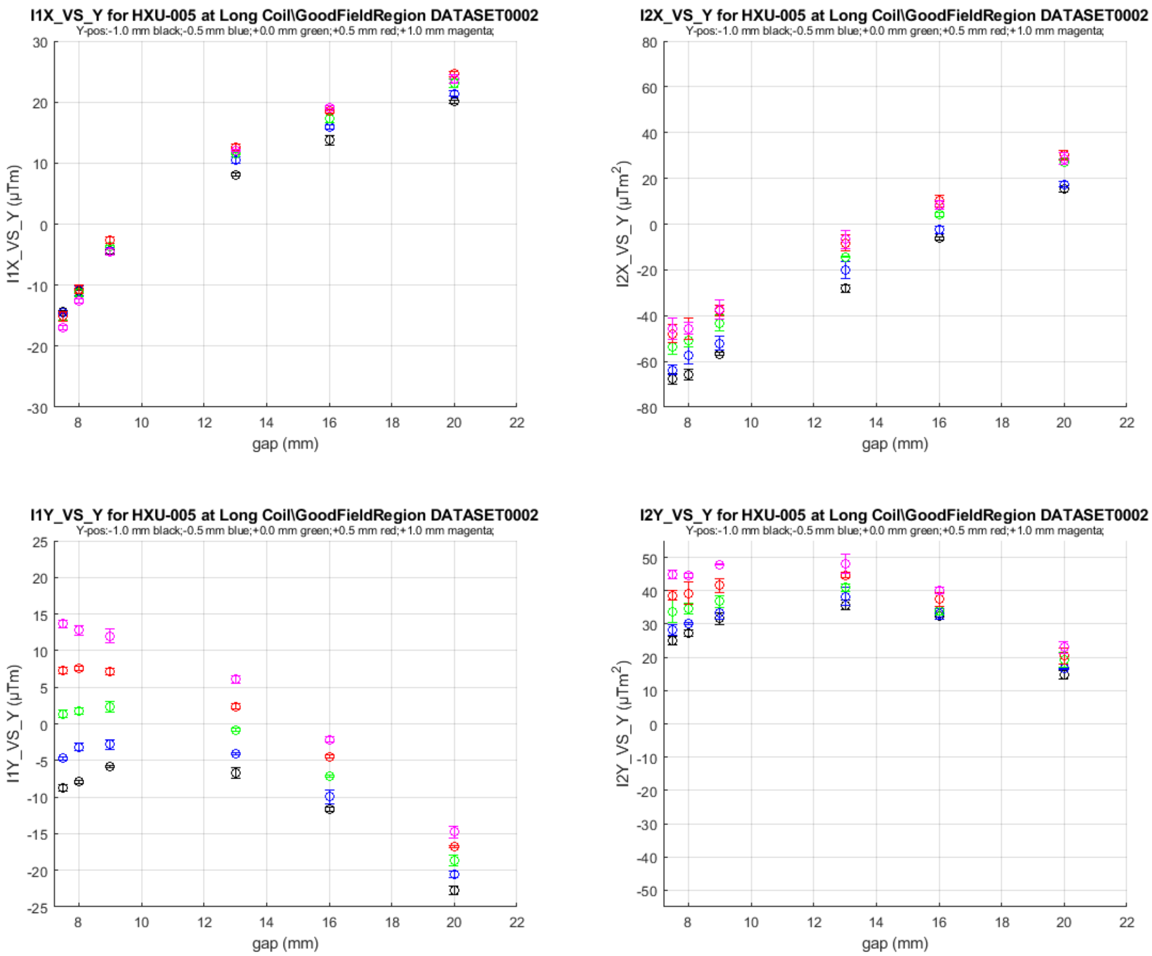
The figure shows the field integrals obtained from long coil measurements on-axis. The vertical axes extend over the tolerance range. All integrals are in tolerance.

Long Coil Measurement of the Horizontally Off-Axis Field Integrals



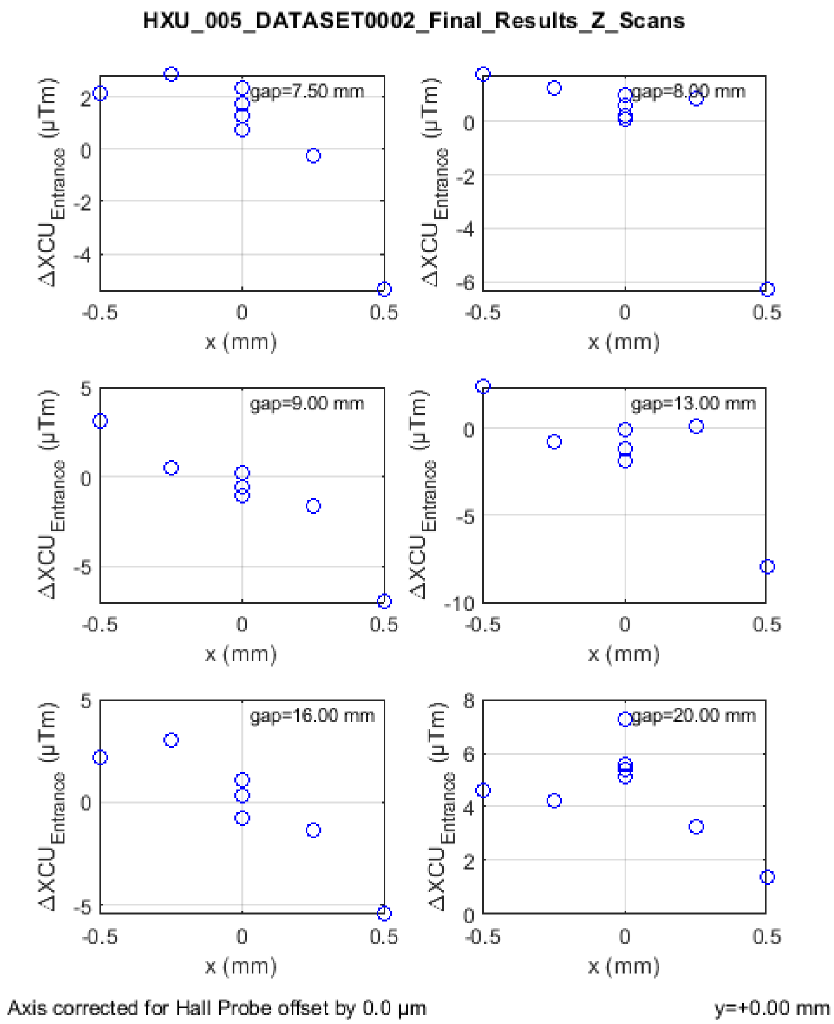
The figure shows the integrals obtained from long coil measurements off axis in the vertical plane using colors to indicate offset distance (black: -1.0 mm, blue: -0.5 mm, green: on-axis; red: +0.5 mm, magenta: +1.0 mm). The vertical axes extend of the tolerance range. All integrals are in tolerance.

Long Coil Measurement of the Vertically Off-Axis Field Integrals



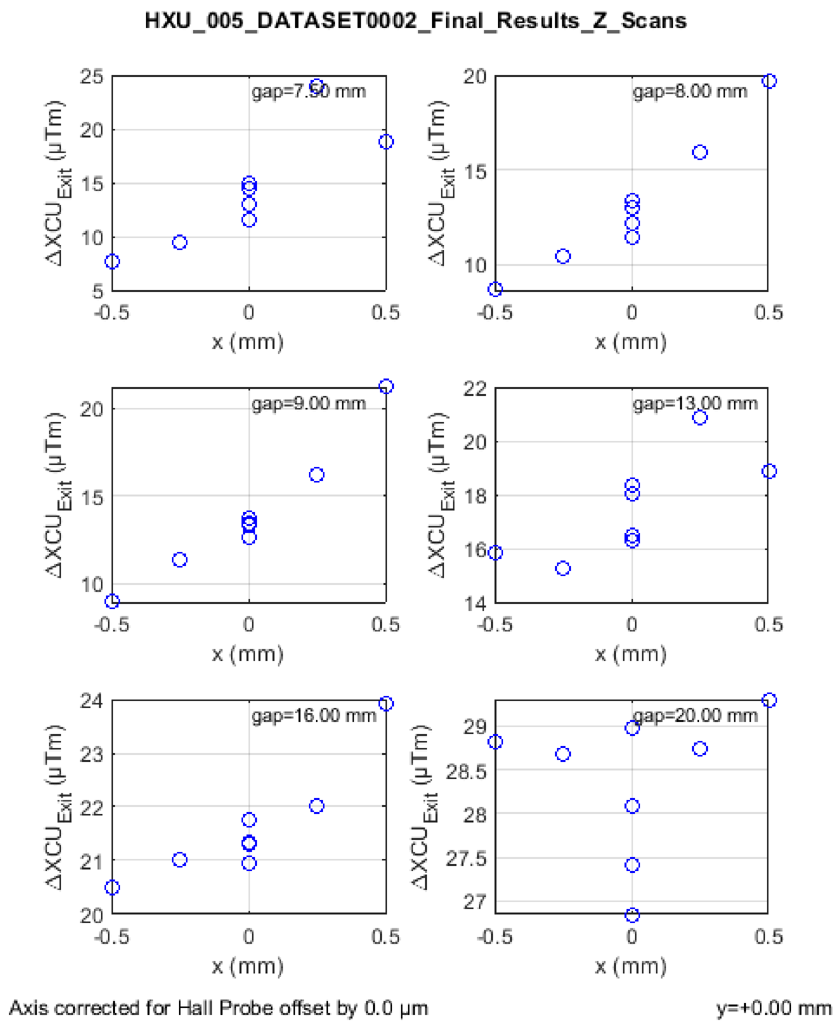
The figure shows the field integrals obtained from long coil measurements off axis in the horizontal plane using colors to indicate offset distance (black: -1.0 mm, blue: -0.5 mm, green: on-axis; red: +0.5 mm, magenta: +1.0 mm). The vertical axes extend over the tolerance range. All integrals are in tolerance.

Estimated Upstream Horizontal Corrector Strength Requirement vs. x



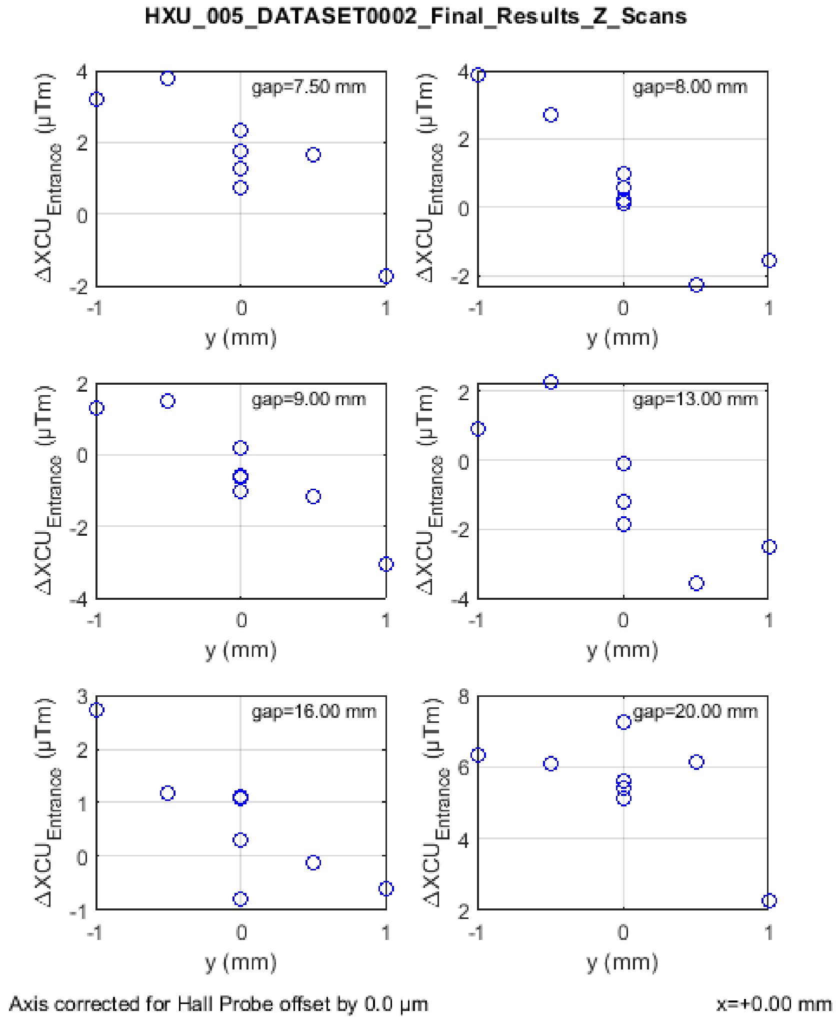
The figure shows the required strength of the upstream horizontal corrector to remove the second vertical undulator field integral at the downstream BPM for a number of operational undulator gaps. The analysis was done at a number of off-axis locations in the x-z plane. All values are small and well below the maximum correction capabilities of greater than 550 μTm of the actual correctors.

Estimated Downstream Horizontal Corrector Strength Requirement vs. x



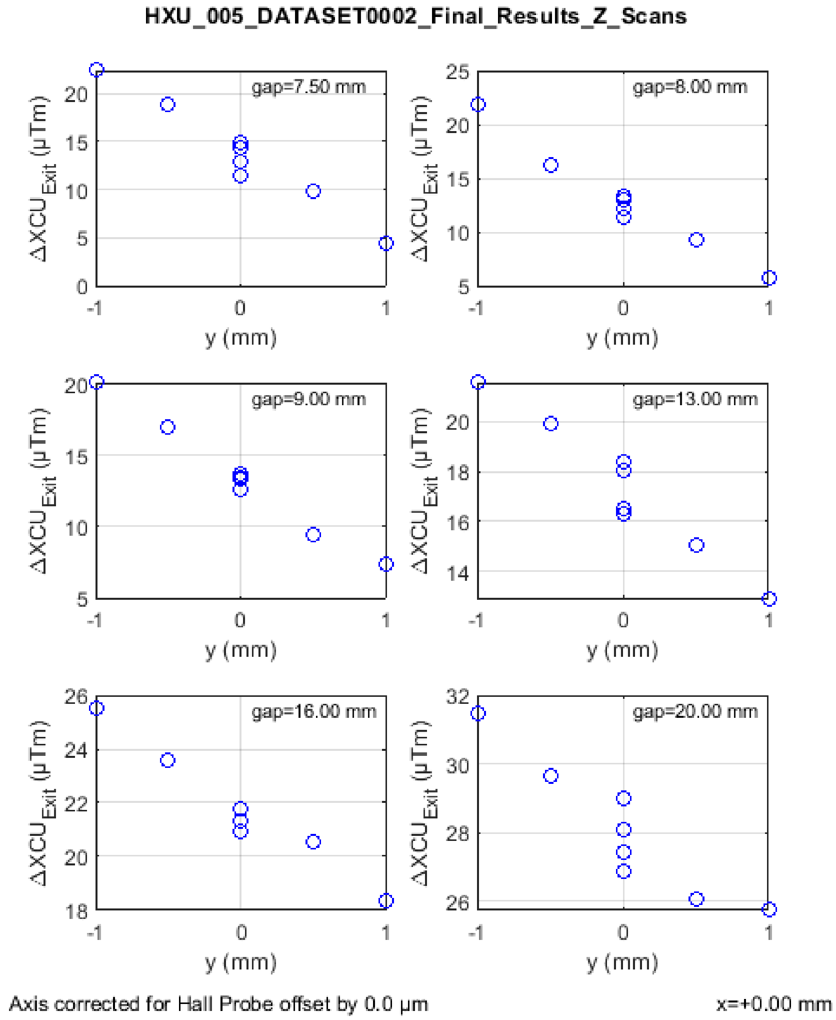
The figure shows the required strength of the downstream horizontal corrector to remove the first vertical undulator field integral and upstream corrector field integral at the downstream BPM for a number of operational undulator gaps. The analysis was done at a number of off-axis locations in the x-z plane. All values are small and well below the maximum correction capabilities of greater than 550 μTm of the actual correctors.

Estimated Upstream Horizontal Corrector Strength Requirement vs. y



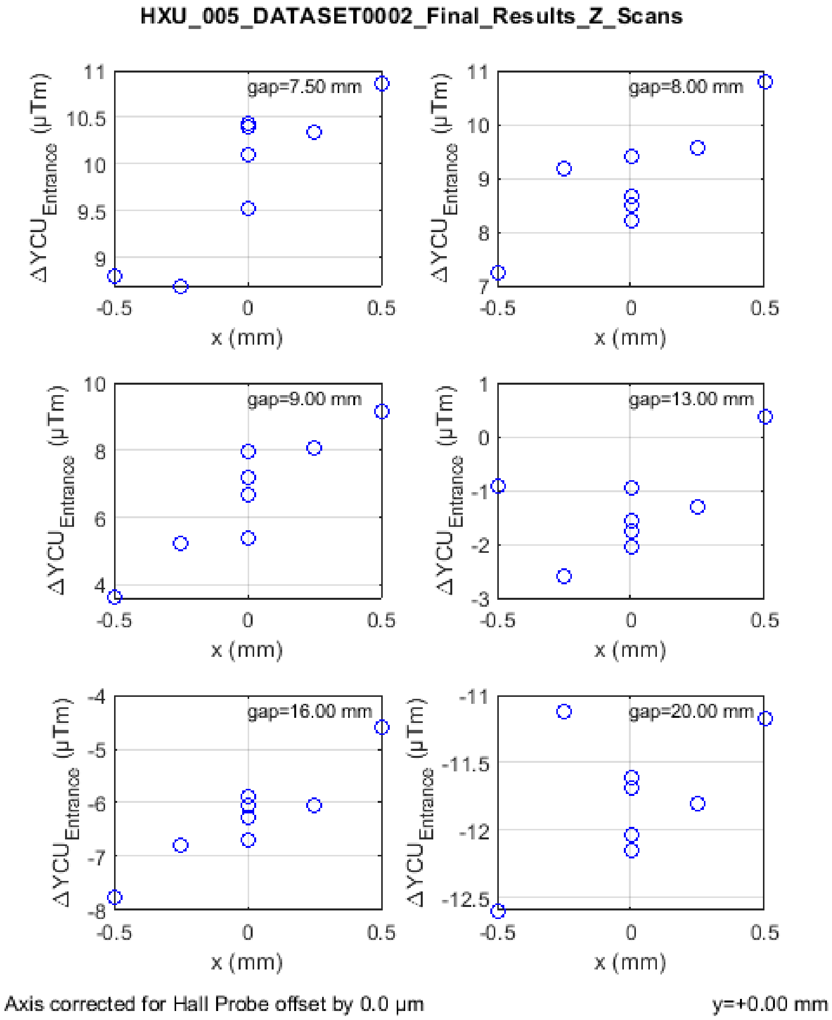
The figure shows the required strength of the upstream horizontal corrector to remove the second vertical undulator field integrals at the downstream BPM for a number of operational undulator gaps. The analysis was done at a number of off-axis locations in the y-z plane. All values are small and well below the maximum correction capabilities of greater than 550 μTm of the actual correctors.

Estimated Downstream Horizontal Corrector Strength Requirement vs. y



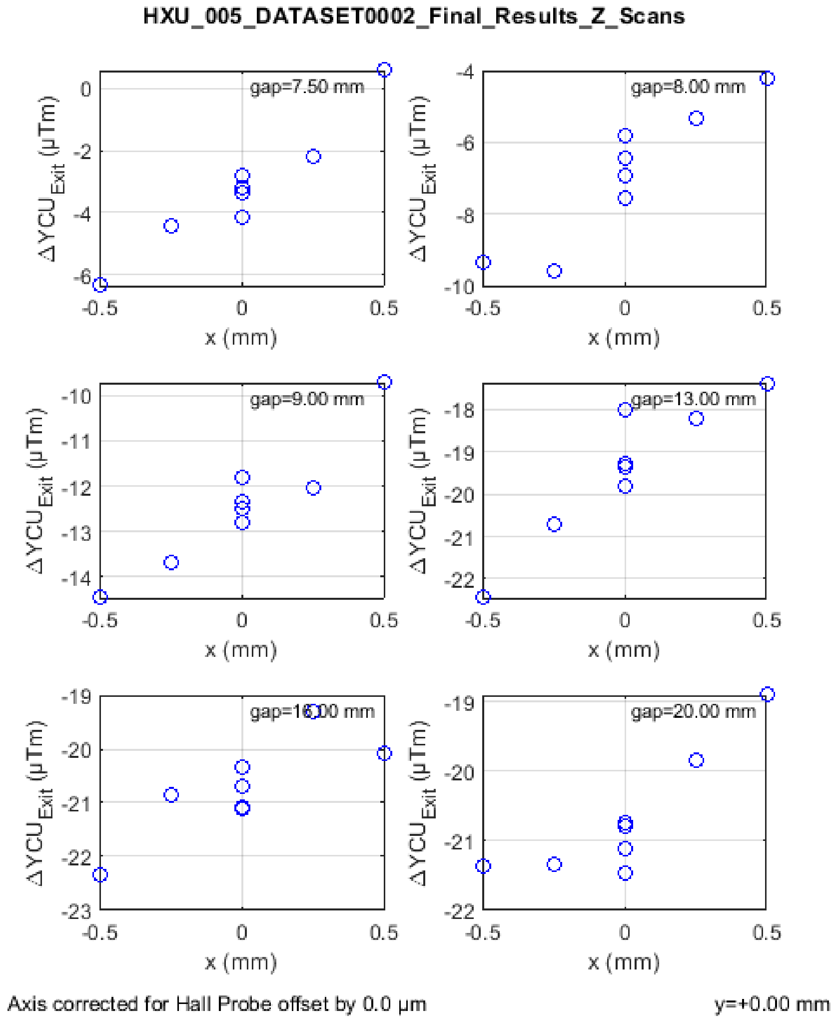
The figure shows the required strength of the upstream horizontal corrector to remove the first vertical undulator and upstream corrector field integrals at the downstream BPM for a number of operational undulator gaps. The analysis was done at a number of off-axis locations in the y-z plane. All values are small and well below the maximum correction amplitude of greater than 550 μTm capabilities of the actual correctors.

Estimated Upstream Vertical Corrector Strength Requirement vs. x



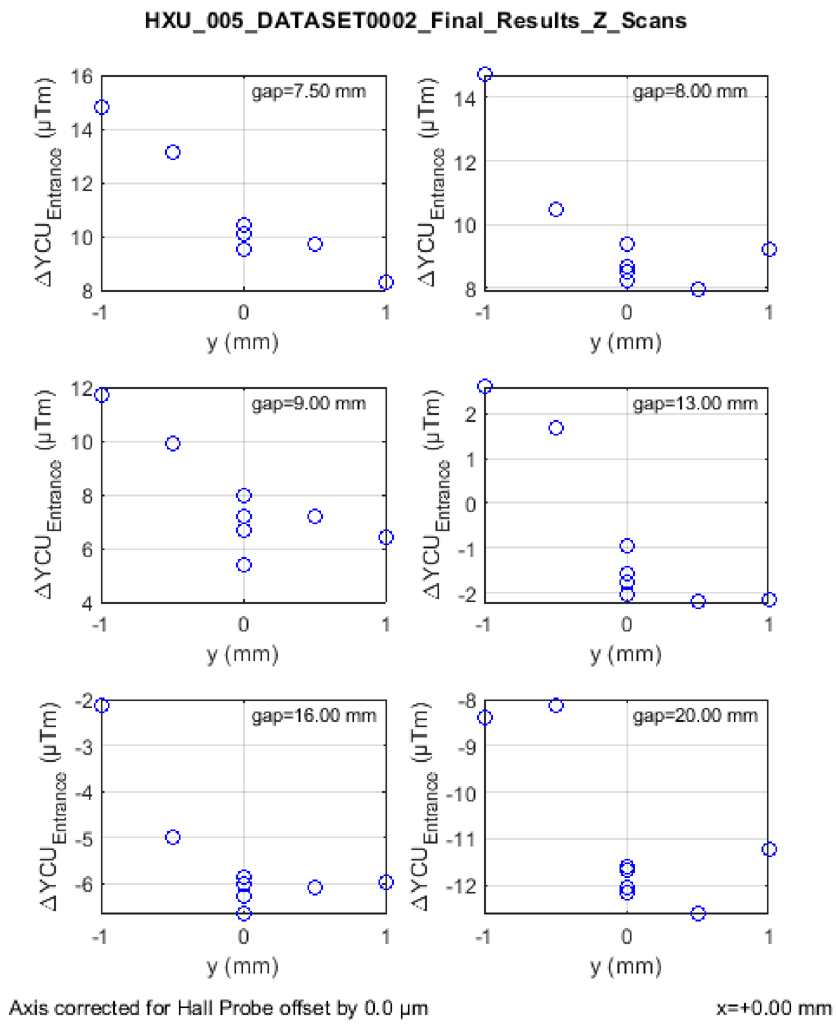
The figure shows the required strength of the upstream horizontal corrector to remove the second horizontal undulator field integral at the downstream BPM for a number of operational undulator gaps. The analysis was done at a number of off-axis locations in the x-z plane. All values are small and well below the maximum correction capabilities of greater than 550 μTm of the actual correctors.

Estimated Downstream Vertical Corrector Strength Requirement vs. x



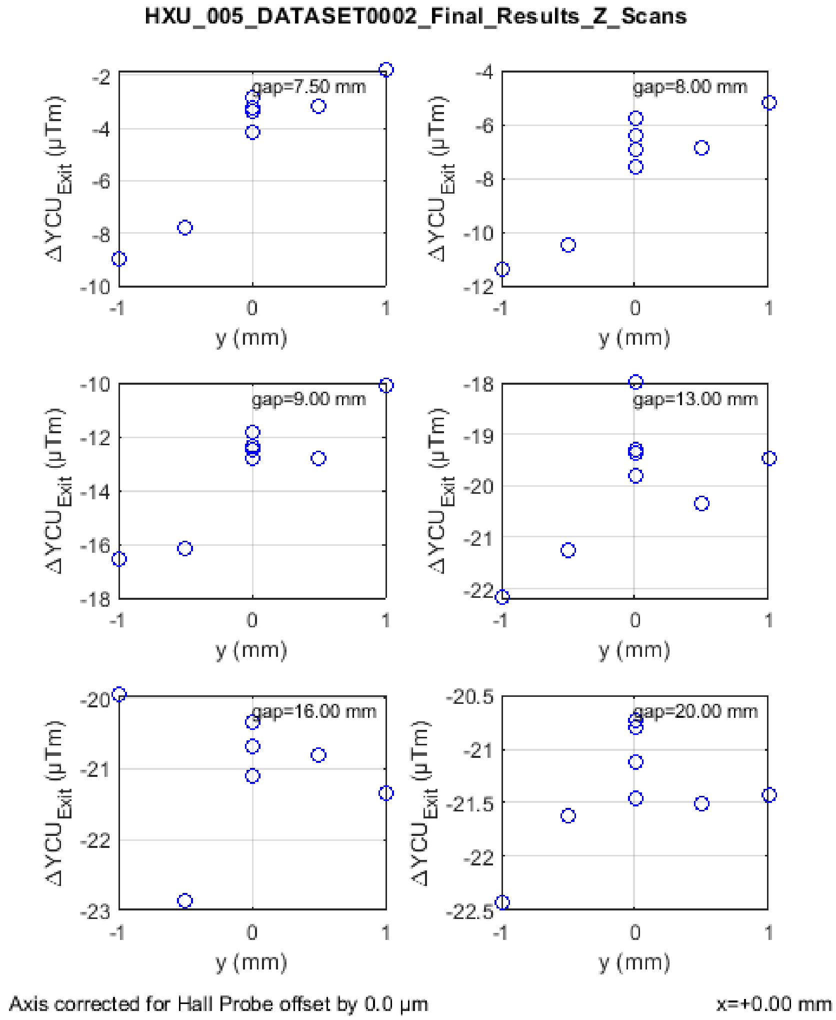
The figure shows the required strength of the downstream vertical corrector to remove the first horizontal undulator field integral and upstream corrector field integral at the downstream BPM for a number of operational undulator gaps. The analysis was done at a number of off-axis locations in the x-z plane. All values are small and well below the maximum correction capabilities of greater than 550 μTm of the actual correctors.

Estimated Upstream Vertical Corrector Strength Requirement vs. y



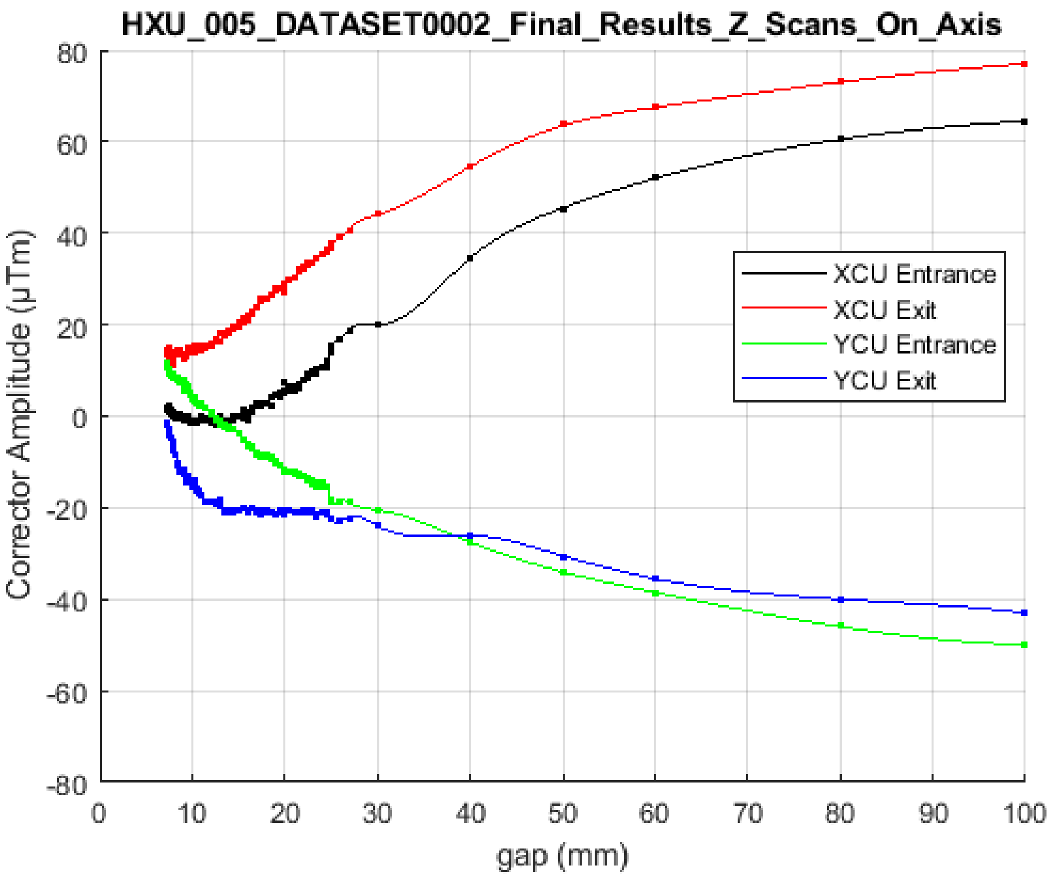
The figure shows the required strength of the upstream vertical corrector to remove the second horizontal undulator field integral at the downstream BPM for a number of operational undulator gaps. The analysis was done at a number of off-axis locations in the y-z plane. All values are small and well below the maximum correction capabilities of greater than 550 μTm of the actual correctors.

Estimated Downstream Vertical Corrector Strength Requirement vs. y



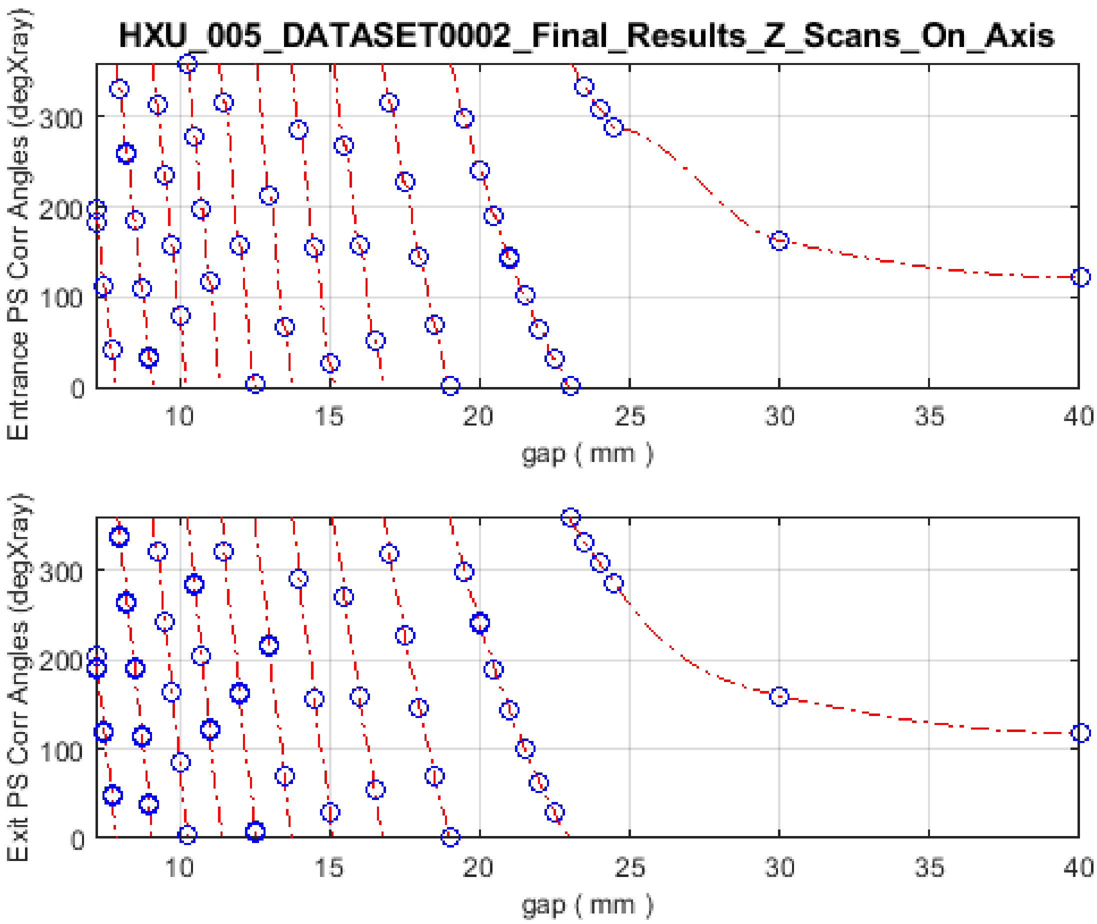
The figure shows the required strength of the downstream vertical corrector to remove the first horizontal undulator field integral and the upstream corrector field integral at the downstream BPM for a number of operational undulator gaps. The analysis was done at a number of off-axis locations in the y-z plane. All values are small and well below the maximum correction capabilities of greater than 550 μTm of the actual correctors.

Estimated Corrector Strengths Requirement vs. gap



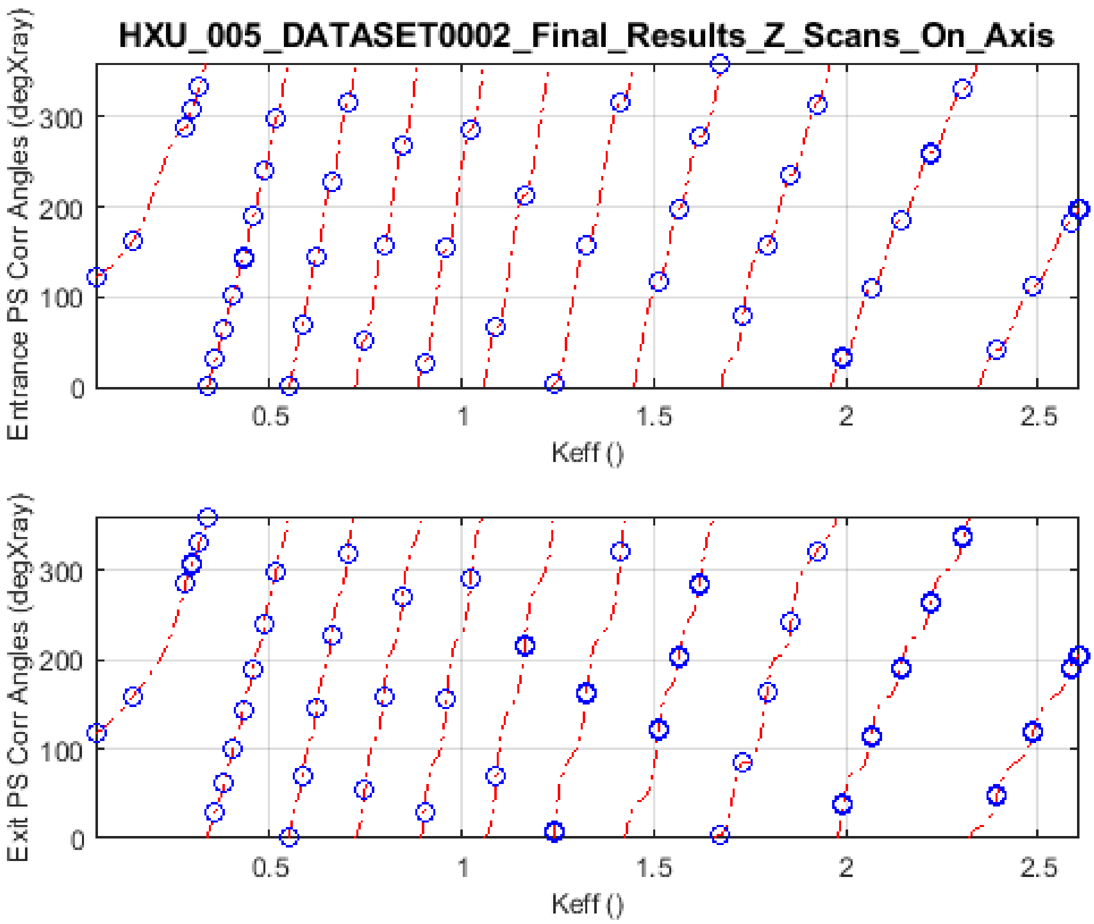
The figure shows as a function of undulator gap the required strengths of the upstream and downstream horizontal and vertical correctors to remove the effect of undulator field integrals at the downstream BPM over the entire available gap range. All values are small and well below the maximum correction capabilities of greater than 550 μTm of the actual correctors.

Estimated Phase Shifter Angle Change Requirement vs. gap



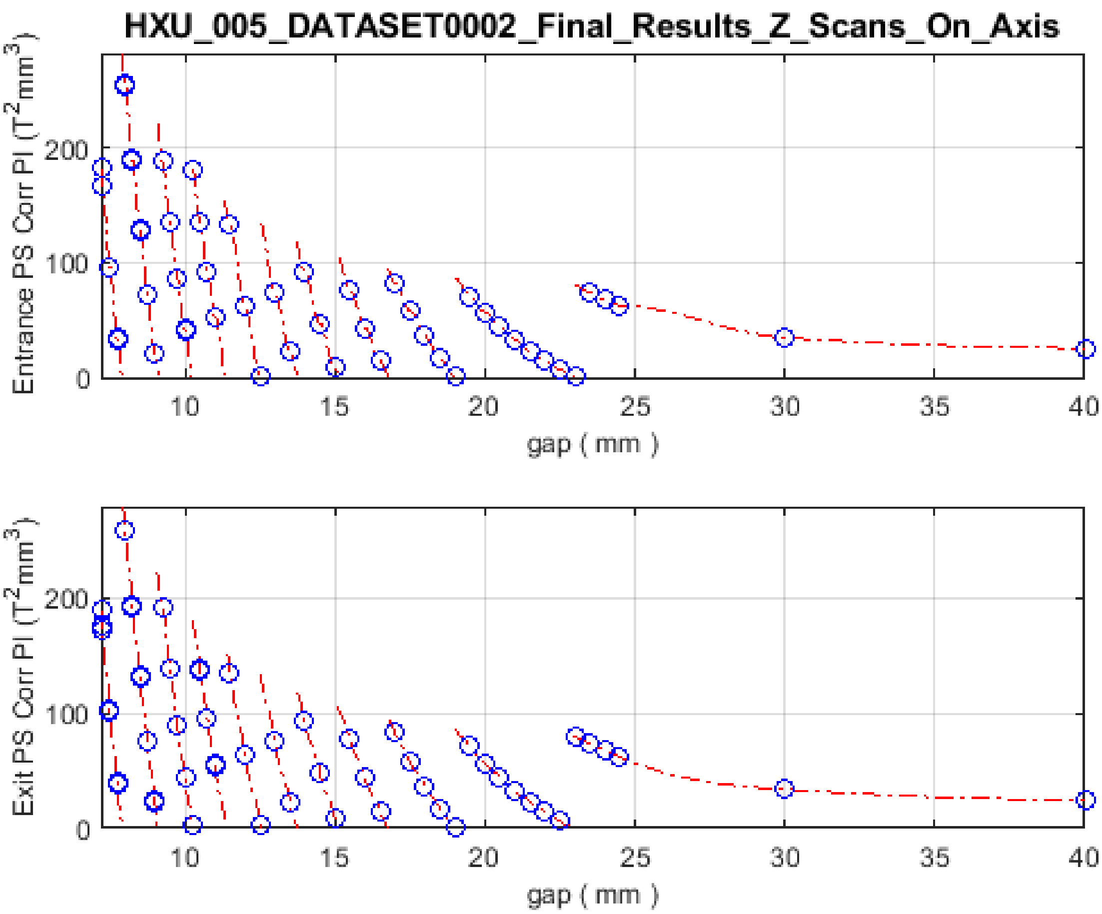
The top and bottom figures show as a function of undulator gap the required correction angles to be added to the upstream and downstream phase shifters, respectively. The red lines indicate the minimum required phase shifter phase angle increases, which are in the 0 to 360 degXray phase shift range. The blue circles indicate MMF measurements.

Estimated Phase Shifter Angle Change Requirement vs. K_{eff}



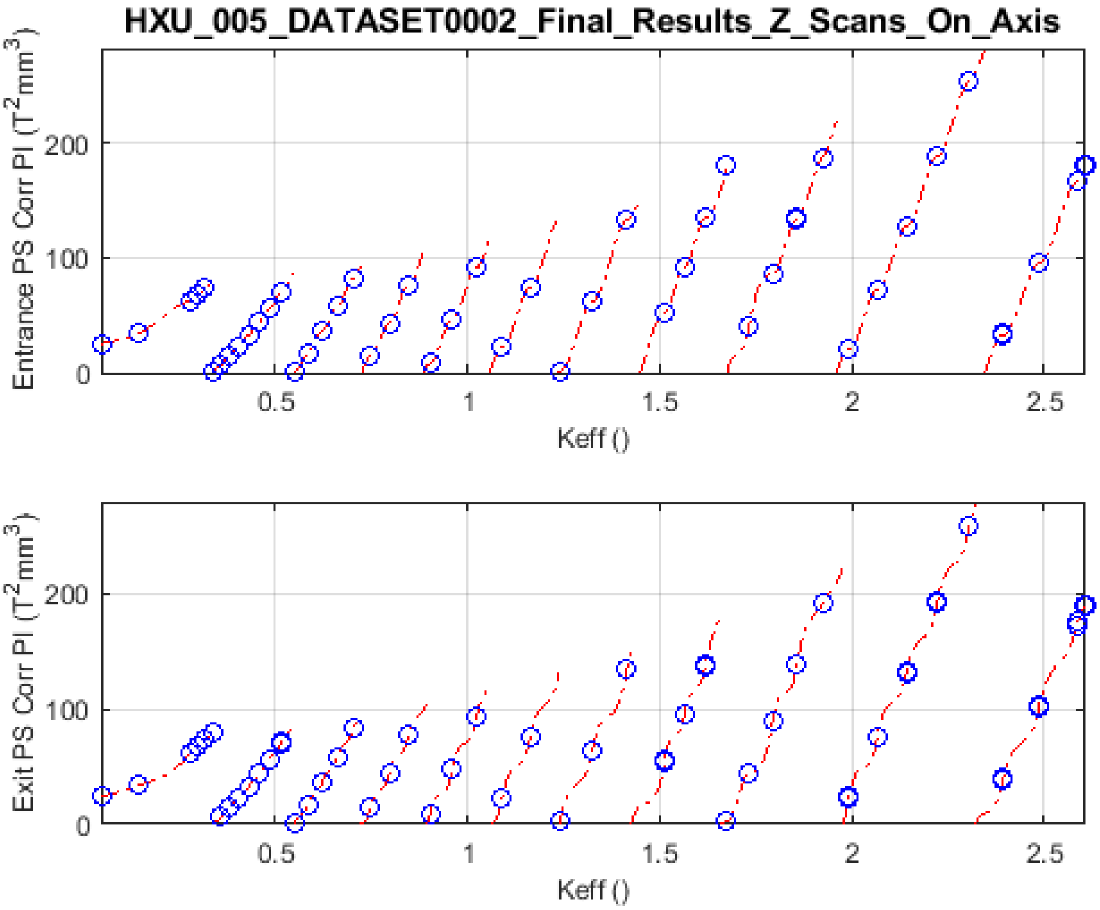
The top and bottom figures as a function of undulator parameter Keff the required correction angles to be added to the upstream and downstream phase shifters, respectively. The red lines indicate the minimum required phase shifter phase angle increases, which are in the 0 to 360 degXray phase shift range. The blue circles indicate MMF measurements.

Estimated Phase Shifter Phase Integral Change Requirement vs. gap



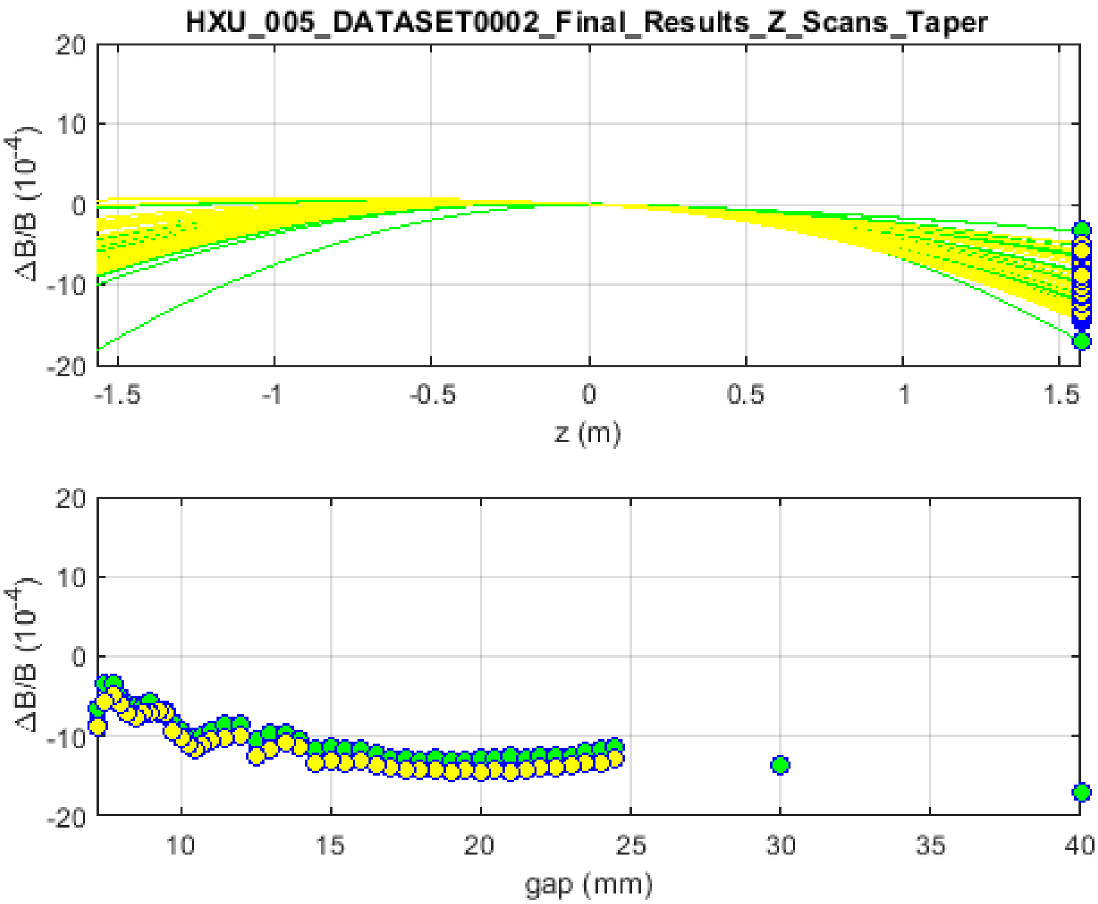
The top and bottom figures show as a function of undulator gap the required correction phase integral (PI) values to be added to the upstream and downstream phase shifters, respectively. The red lines indicate the minimum required phase shifter phase angle increases, which are in the 0 to 360 degXray phase shift range. The blue circles indicate MMF measurements.

Estimated Phase Shifter Phase Integral Change Requirement vs. K_{eff}



The top and bottom figures show as a function of undulator parameter Keff the required correction phase integral (PI) values to be added to the upstream and downstream phase shifters, respectively. The red lines indicate the minimum required phase shifter phase angle increases, which are in the 0 to 360 degXray phase shift range. The blue circles indicate MMF measurements.

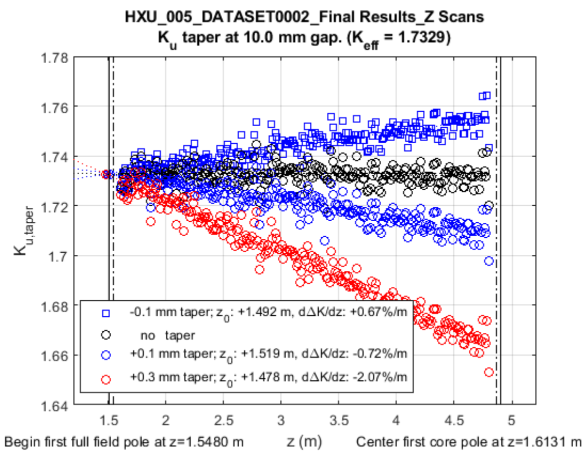
Zero Taper Fit vs. gap

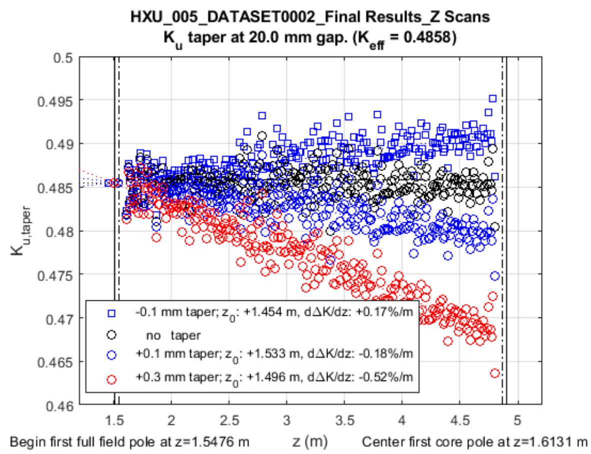


The top figure shows quadratic fits to the absolute values K_u for each core pole for different gaps when the device is set to zero taper. Green curves indicate that the gap was approached from smaller gaps, while yellow curves indicate approach from larger gaps. The fitted K_u value of the last pole is marked with a solid circle with the same color coding. The bottom shows the same solid circles as in the upper plot but this time plotted against the corresponding undulator gap encoder values. The figures show that the undulator has a small quadratic taper that varies with gap. This could explain the phase shake dependence on gap as shown in an earlier figure.

Gap Tapering—Tapered K_u Values

The SXU devices support a gap taper, which is controlled by the taper PV, which holds the difference between the upstream and downstream gap encoder readings measured in micro-meter. The taper can be varied over the ±300 μm-range.

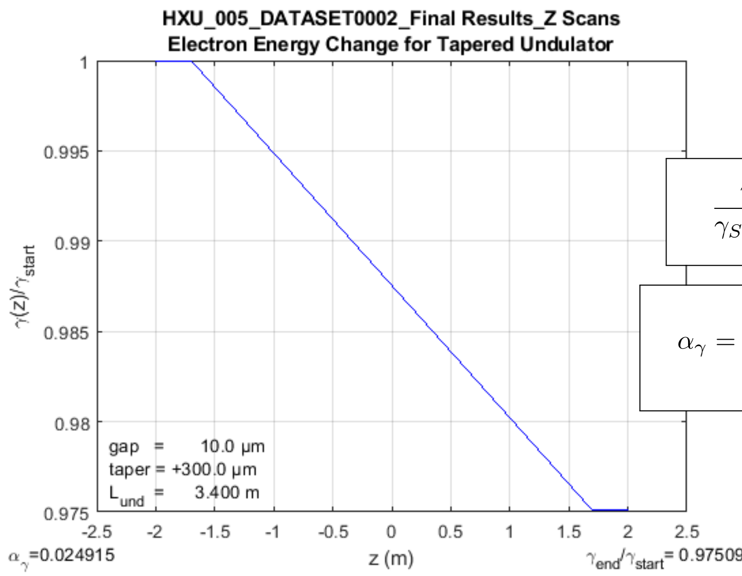




The figure shows K_u, taper for the 246 core poles based on Hall probe measurements versus z location for 4 different taper amplitudes (-100 μm, 0 μm, +100 μm, +300 μm) and 2 different gaps (8 mm, 22 mm). The vertical dashed lines indicate the beginning of the first and the end of the last full field pole. The solid vertical lines indicate the longitudinal limits of strongback. The crosses on the left hand side of the undulator segment border surrounded by the K_u, taper symbol for the representative taper amplitude indicate the intersections between linear fits (indicated by dotted lines in the representative color) and the K_u values untapered case with each of the tapered cases. The horizontal dash-dotted line next to the figure center (hard to see) indicated the level of K_{eff} of the untapered undulator.
The taper operation for this segment is functional.

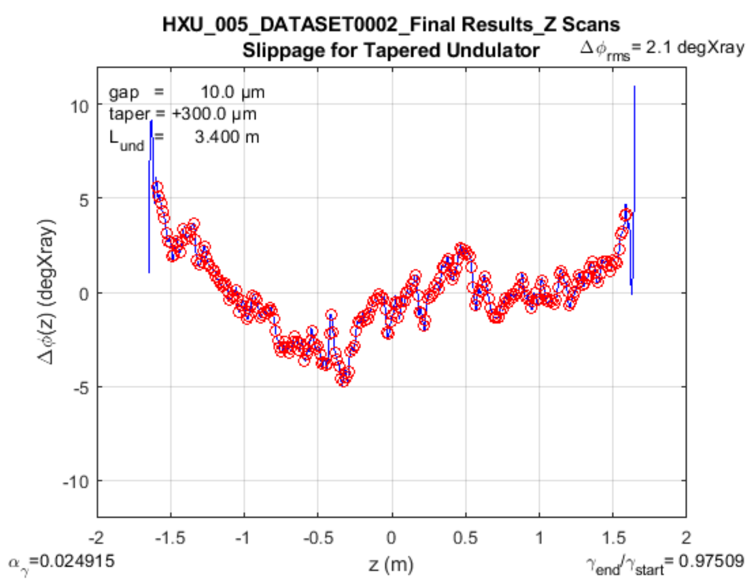
Gap Tapering—Tapered K_u Values

Generally, gap tapering will cause significant increases in the phase shake within the undulator segment. If however during high gain FEL operation the electrons loose significant amounts of energy, a matching gap taper can reduce the total phase shake to stay within the original parallel gap phase shake tolerance for constant energy.



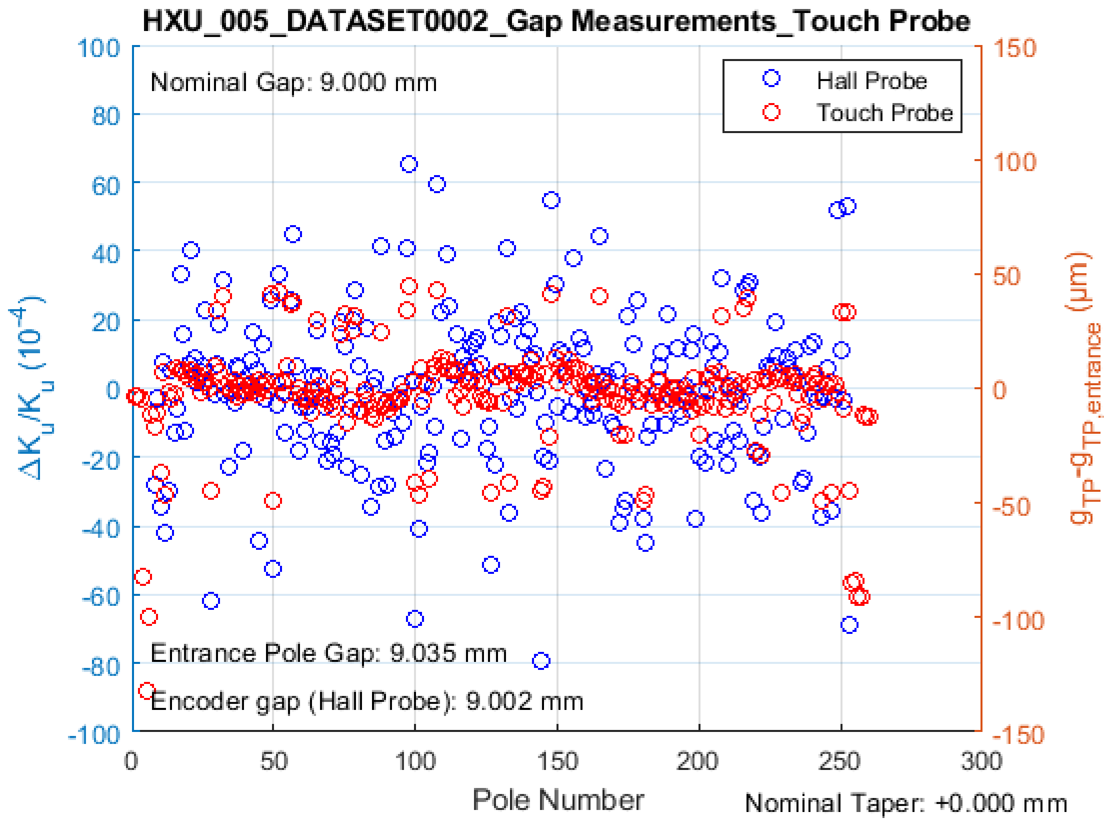
$$\frac{\gamma}{\gamma_{Start}} = 1 - \alpha_\gamma \frac{z}{L_{und}}$$

$$\alpha_\gamma = -\frac{1}{\frac{2}{K_0^2}+1}\frac{L_{und}}{K_0}\frac{dK}{dz}$$



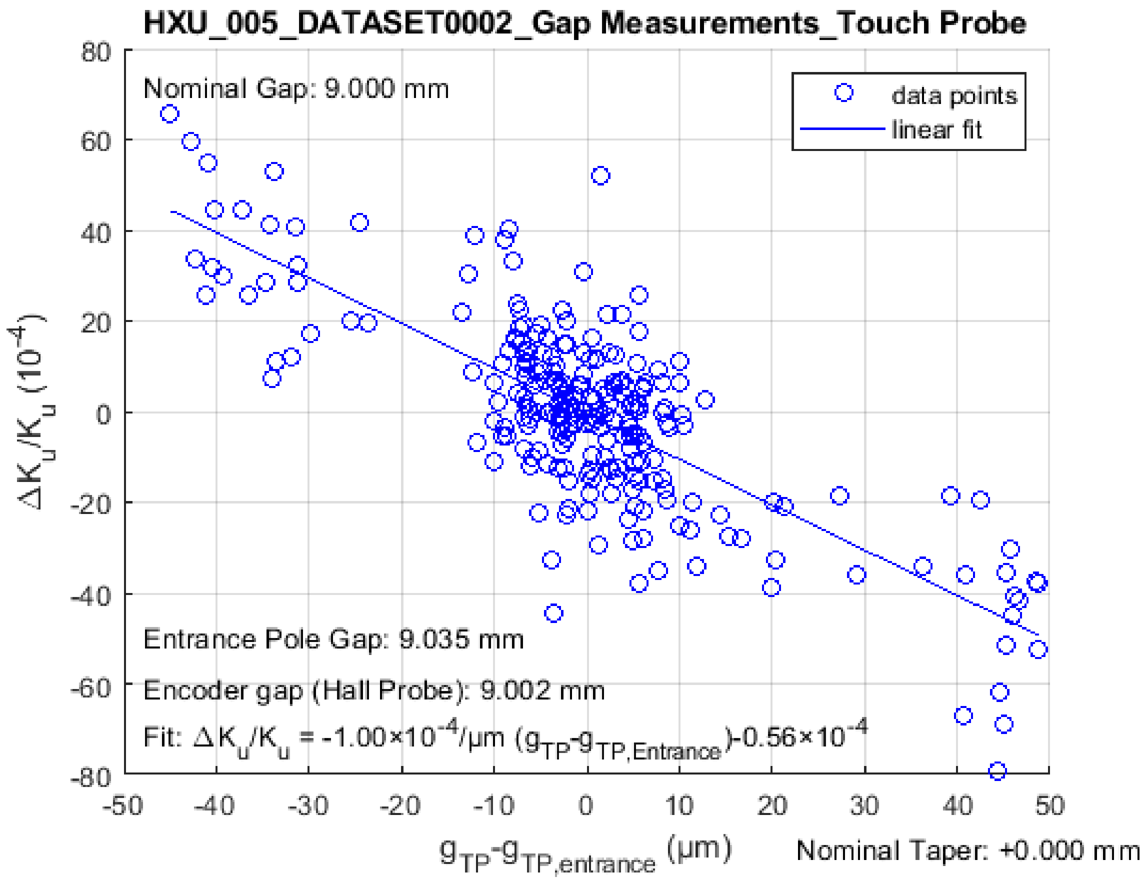
The upper figure shows a simplified linear energy loss function (Lorentz factor γ/γ_{Start}) optimized for the 0.3 mm gap taper at an 10 mm nominal gap. The lower figure shows the phase error along the undulator segment for the same parameters.

Touch Probe (TP) Analysis — Per pole gap vs. per pole K (untapered)



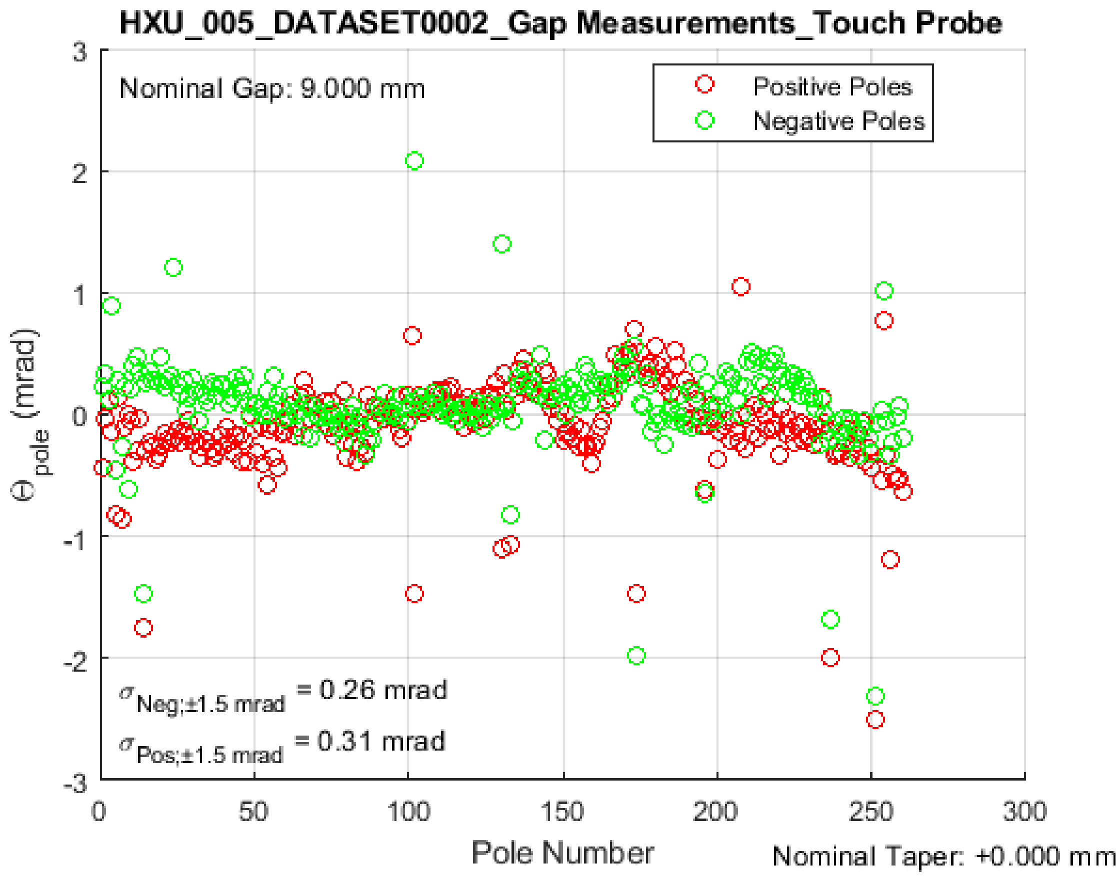
The figure shows $\Delta K/K$ (blue, left axis) (for the 246 core poles) as well as mechanical gap heights ($\langle g_{TP}\rangle - g_{TP}$) (red, right axis) (for all 260 poles) based on touch probe measurements versus pole number. The large amplitude outliers are the result of tuning.

Touch Probe (TP) Analysis — K vs. per pole gap (untapered)



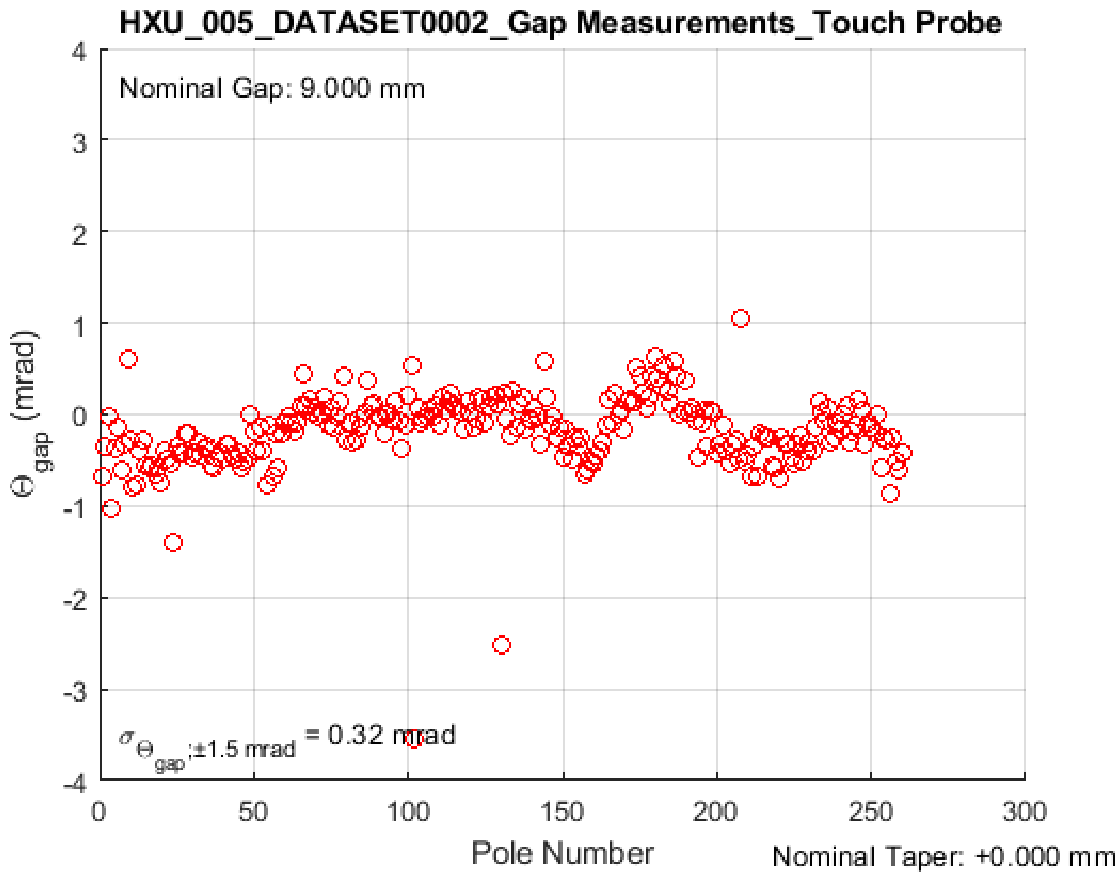
The figure shows the correlation between the $\Delta K_u/K_u$ for each pole from Hall probe measurements for the tuning gap and the deviation of the pole gap measured by the touch probe relative to its average (for the 246 core poles). The average gap measured with the touch probe and the one measured with the gap encoder are shown in the lower left corner of the figure. Also shown is the fit function.

Touch Probe (TP) Analysis — Pole Cant Angles (untapered)



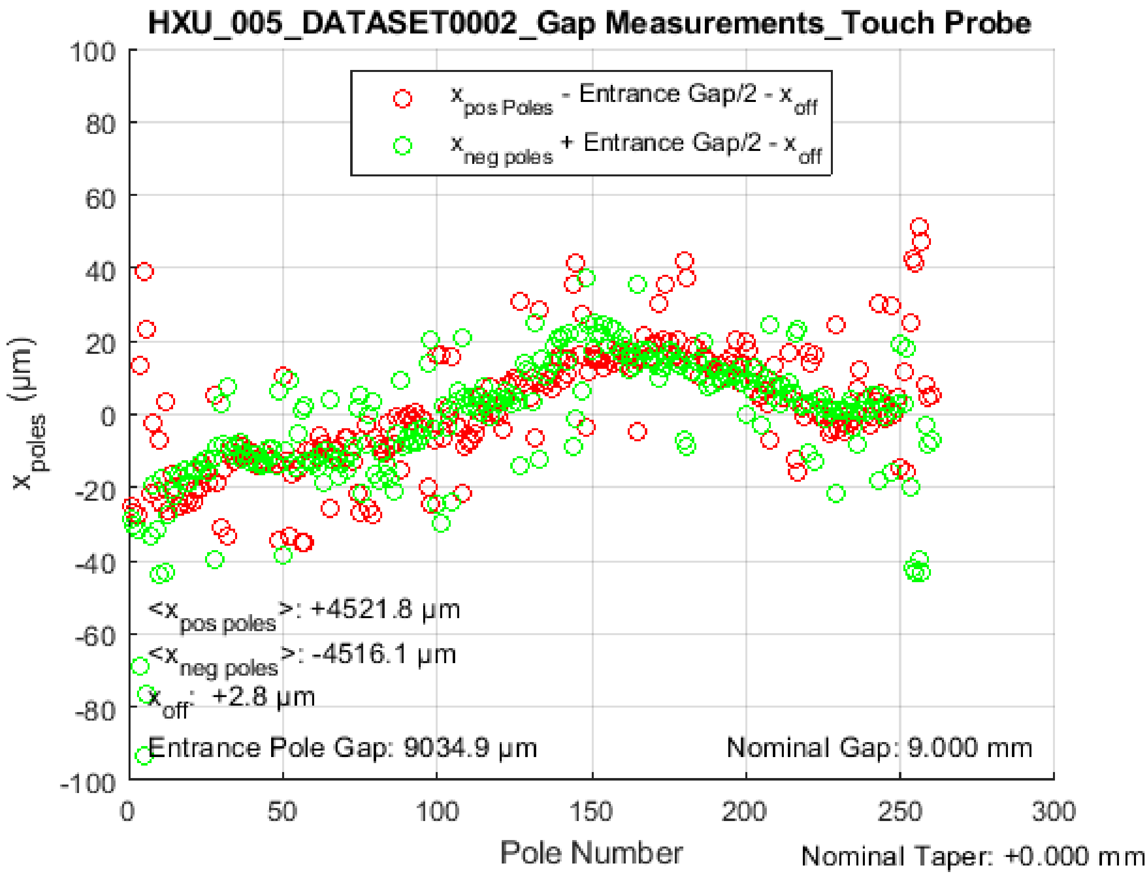
The figure shows the cant angles of each pole (top red, bottom green) relative to the horizontal plane defined by the Kugler bench at the Tuning Gap for all 260 poles, measured by the touch probe. The rms width of each distribution within a ±1.5 mrad band is shown in the lower left corner of the figure.

Touch Probe (TP) Analysis — Gap Cant Angles (untapered)



The figure shows the cant angles between the top and bottom part of each pole at the Tuning Gap for all 260 poles, measured by the touch probe. The rms width of each distribution within a ±1.5 mrad band is shown in the lower left corner of the figure.

Touch Probe (TP) Analysis — Pole Heights (untapered)



The figure shows the relative vertial positions of the center of each pole (top red, bottom green) relative to the horizontal plane define by the Kugler bench at the Tuning Gap for all 260 poles, measured by the touch probe.

Measurement Results are stored:

At V-Drive:

☒ V:\MET\MagServe\MagData\LCLS-II\Undulator\

☐ ______________________________

In Folder

☒ HXU-005\DATASET0002\MagServe\Final Results\

☐ ______________________________

Confirmation of File Locations:

The following tables list all required data files documenting the tuning results. An existence check was done and the result is indicated next to each filename as "exists" or "missing".

Sub folder: Z Scans\Good Field Region exists

001gap007.500x-00.50y+00.00\zscan.dat	exists
002gap007.500x-00.25y+00.00\zscan.dat	exists
003gap007.500x+00.00y+00.00\zscan.dat	exists
004gap007.500x+00.25y+00.00\zscan.dat	exists
005gap007.500x+00.50y+00.00\zscan.dat	exists
006gap007.500x+00.00y-01.00\zscan.dat	exists
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Sub folder: Z Scans\On Axis `exists`

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031gap018.000x+00.00y+00.00\zscan.dat	exists
032gap018.500x+00.00y+00.00\zscan.dat	exists
033gap019.000x+00.00y+00.00\zscan.dat	exists
034gap019.500x+00.00y+00.00\zscan.dat	exists
035gap020.000x+00.00y+00.00\zscan.dat	exists
036gap020.500x+00.00y+00.00\zscan.dat	exists
037gap021.000x+00.00y+00.00\zscan.dat	exists
038gap021.500x+00.00y+00.00\zscan.dat	exists
039gap022.000x+00.00y+00.00\zscan.dat	exists
041gap023.000x+00.00y+00.00\zscan.dat	exists
043gap024.000x+00.00y+00.00\zscan.dat	exists
045gap025.000x+00.00y+00.00\zscan.dat	exists
046gap026.000x+00.00y+00.00\zscan.dat	exists
047gap027.000x+00.00y+00.00\zscan.dat	exists
048gap030.000x+00.00y+00.00\zscan.dat	exists
049gap040.000x+00.00y+00.00\zscan.dat	exists
050gap050.000x+00.00y+00.00\zscan.dat	exists
051gap060.000x+00.00y+00.00\zscan.dat	exists
052gap080.000x+00.00y+00.00\zscan.dat	exists
053gap100.000x+00.00y+00.00\zscan.dat	exists

Sub folder: Z Scans\Commissioning Gap exists

001gap007.904x+00.00y+00.00\zscan.dat	exists

Sub folder: Z Scans\Gap with taper exists

005gap010.000taper-0.100x+00.00y+00.00\zscan.dat	exists
007gap010.000taper+0.000x+00.00y+00.00\zscan.dat	exists
001gap010.000taper+0.100x+00.00y+00.00\zscan.dat	exists
003gap010.000taper+0.300x+00.00y+00.00\zscan.dat	exists
006gap020.000taper-0.100x+00.00y+00.00\zscan.dat	exists
008gap020.000taper+0.000x+00.00y+00.00\zscan.dat	exists
002gap020.000taper+0.100x+00.00y+00.00\zscan.dat	exists
004gap020.000taper+0.300x+00.00y+00.00\zscan.dat	exists

Sub folder: Long Coil exists

Sub folder: Long Coil\Good Field Region exists

integrals_summary.txt	exists
011gap007.500x-00.50y+00.00_i1X_integrals.txt	exists
012gap007.500x-00.25y+00.00_i1X_integrals.txt	exists
013gap007.500x+00.00y+00.00_i1X_integrals.txt	exists
014gap007.500x+00.25y+00.00_i1X_integrals.txt	exists
015gap007.500x+00.50y+00.00_i1X_integrals.txt	exists
031gap007.500x+00.00y-01.00_i1X_integrals.txt	exists
032gap007.500x+00.00y-00.50_i1X_integrals.txt	exists
013gap007.500x+00.00y+00.00_i1X_integrals.txt	exists
034gap007.500x+00.00y+00.50_i1X_integrals.txt	exists
035gap007.500x+00.00y+01.00_i1X_integrals.txt	exists
051gap008.000x-00.50y+00.00_i1X_integrals.txt	exists
052gap008.000x-00.25y+00.00_i1X_integrals.txt	exists
053gap008.000x+00.00y+00.00_i1X_integrals.txt	exists
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071gap008.000x+00.00y-01.00_i1X_integrals.txt	exists
072gap008.000x+00.00y-00.50_i1X_integrals.txt	exists
053gap008.000x+00.00y+00.00_i1X_integrals.txt	exists
074gap008.000x+00.00y+00.50_i1X_integrals.txt	exists
075gap008.000x+00.00y+01.00_i1X_integrals.txt	exists
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092gap009.000x-00.25y+00.00_i1X_integrals.txt	exists
093gap009.000x+00.00y+00.00_i1X_integrals.txt	exists
094gap009.000x+00.25y+00.00_i1X_integrals.txt	exists
095gap009.000x+00.50y+00.00_i1X_integrals.txt	exists
111gap009.000x+00.00y-01.00_i1X_integrals.txt	exists
112gap009.000x+00.00y-00.50_i1X_integrals.txt	exists
093gap009.000x+00.00y+00.00_i1X_integrals.txt	exists
114gap009.000x+00.00y+00.50_i1X_integrals.txt	exists
115gap009.000x+00.00y+01.00_i1X_integrals.txt	exists
131gap013.000x-00.50y+00.00_i1X_integrals.txt	exists
132gap013.000x-00.25y+00.00_i1X_integrals.txt	exists

133gap013.000x+00.00y+00.00_i1X_integrals.txt	exists
134gap013.000x+00.25y+00.00_i1X_integrals.txt	exists
135gap013.000x+00.50y+00.00_i1X_integrals.txt	exists
151gap013.000x+00.00y-01.00_i1X_integrals.txt	exists
152gap013.000x+00.00y-00.50_i1X_integrals.txt	exists
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171gap016.000x-00.50y+00.00_i1X_integrals.txt	exists
172gap016.000x-00.25y+00.00_i1X_integrals.txt	exists
173gap016.000x+00.00y+00.00_i1X_integrals.txt	exists
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175gap016.000x+00.50y+00.00_i1X_integrals.txt	exists
191gap016.000x+00.00y-01.00_i1X_integrals.txt	exists
192gap016.000x+00.00y-00.50_i1X_integrals.txt	exists
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252gap050.000x-00.25y+00.00_i1X_integrals.txt	exists
253gap050.000x+00.00y+00.00_i1X_integrals.txt	exists
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167gap016.000x-00.25y+00.00_i2Y_integrals.txt	exists
168gap016.000x+00.00y+00.00_i2Y_integrals.txt	exists
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187gap016.000x+00.00y-00.50_i2Y_integrals.txt	exists
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190gap016.000x+00.00y+01.00_i2Y_integrals.txt	exists
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247gap050.000x-00.25y+00.00_i2Y_integrals.txt	exists
248gap050.000x+00.00y+00.00_i2Y_integrals.txt	exists
249gap050.000x+00.25y+00.00_i2Y_integrals.txt	exists
250gap050.000x+00.50y+00.00_i2Y_integrals.txt	exists
266gap050.000x+00.00y-01.00_i2Y_integrals.txt	exists
267gap050.000x+00.00y-00.50_i2Y_integrals.txt	exists
248gap050.000x+00.00y+00.00_i2Y_integrals.txt	exists
269gap050.000x+00.00y+00.50_i2Y_integrals.txt	exists
270gap050.000x+00.00y+01.00_i2Y_integrals.txt	exists
286gap100.000x-00.50y+00.00_i2Y_integrals.txt	exists
287gap100.000x-00.25y+00.00_i2Y_integrals.txt	exists
288gap100.000x+00.00y+00.00_i2Y_integrals.txt	exists
289gap100.000x+00.25y+00.00_i2Y_integrals.txt	exists
290gap100.000x+00.50y+00.00_i2Y_integrals.txt	exists
306gap100.000x+00.00y-01.00_i2Y_integrals.txt	exists
307gap100.000x+00.00y-00.50_i2Y_integrals.txt	exists
288gap100.000x+00.00y+00.00_i2Y_integrals.txt	exists
309gap100.000x+00.00y+00.50_i2Y_integrals.txt	exists
310gap100.000x+00.00y+01.00_i2Y_integrals.txt	exists

Sub folder: Long Coil\On Axis `exists`

integrals_summary.txt	exists

003gap007.200x+00.00y+00.00_i1X_integrals.txt	exists
004gap007.200x+00.00y+00.00_i2X_integrals.txt	exists
001gap007.200x+00.00y+00.00_i1Y_integrals.txt	exists
002gap007.200x+00.00y+00.00_i2Y_integrals.txt	exists
007gap007.500x+00.00y+00.00_i1X_integrals.txt	exists
008gap007.500x+00.00y+00.00_i2X_integrals.txt	exists
005gap007.500x+00.00y+00.00_i1Y_integrals.txt	exists
006gap007.500x+00.00y+00.00_i2Y_integrals.txt	exists
011gap008.000x+00.00y+00.00_i1X_integrals.txt	exists
012gap008.000x+00.00y+00.00_i2X_integrals.txt	exists
009gap008.000x+00.00y+00.00_i1Y_integrals.txt	exists
010gap008.000x+00.00y+00.00_i2Y_integrals.txt	exists
015gap008.500x+00.00y+00.00_i1X_integrals.txt	exists
016gap008.500x+00.00y+00.00_i2X_integrals.txt	exists
013gap008.500x+00.00y+00.00_i1Y_integrals.txt	exists
014gap008.500x+00.00y+00.00_i2Y_integrals.txt	exists
019gap009.000x+00.00y+00.00_i1X_integrals.txt	exists
020gap009.000x+00.00y+00.00_i2X_integrals.txt	exists
017gap009.000x+00.00y+00.00_i1Y_integrals.txt	exists
018gap009.000x+00.00y+00.00_i2Y_integrals.txt	exists
027gap010.000x+00.00y+00.00_i1X_integrals.txt	exists
028gap010.000x+00.00y+00.00_i2X_integrals.txt	exists
025gap010.000x+00.00y+00.00_i1Y_integrals.txt	exists
026gap010.000x+00.00y+00.00_i2Y_integrals.txt	exists
035gap012.000x+00.00y+00.00_i1X_integrals.txt	exists
036gap012.000x+00.00y+00.00_i2X_integrals.txt	exists
033gap012.000x+00.00y+00.00_i1Y_integrals.txt	exists
034gap012.000x+00.00y+00.00_i2Y_integrals.txt	exists
043gap014.000x+00.00y+00.00_i1X_integrals.txt	exists
044gap014.000x+00.00y+00.00_i2X_integrals.txt	exists
041gap014.000x+00.00y+00.00_i1Y_integrals.txt	exists
042gap014.000x+00.00y+00.00_i2Y_integrals.txt	exists
047gap016.000x+00.00y+00.00_i1X_integrals.txt	exists
048gap016.000x+00.00y+00.00_i2X_integrals.txt	exists
045gap016.000x+00.00y+00.00_i1Y_integrals.txt	exists
046gap016.000x+00.00y+00.00_i2Y_integrals.txt	exists

051gap018.000x+00.00y+00.00_i1X_integrals.txt	exists
052gap018.000x+00.00y+00.00_i2X_integrals.txt	exists
049gap018.000x+00.00y+00.00_i1Y_integrals.txt	exists
050gap018.000x+00.00y+00.00_i2Y_integrals.txt	exists
055gap020.000x+00.00y+00.00_i1X_integrals.txt	exists
056gap020.000x+00.00y+00.00_i2X_integrals.txt	exists
053gap020.000x+00.00y+00.00_i1Y_integrals.txt	exists
054gap020.000x+00.00y+00.00_i2Y_integrals.txt	exists
059gap022.000x+00.00y+00.00_i1X_integrals.txt	exists
060gap022.000x+00.00y+00.00_i2X_integrals.txt	exists
057gap022.000x+00.00y+00.00_i1Y_integrals.txt	exists
058gap022.000x+00.00y+00.00_i2Y_integrals.txt	exists
063gap025.000x+00.00y+00.00_i1X_integrals.txt	exists
064gap025.000x+00.00y+00.00_i2X_integrals.txt	exists
061gap025.000x+00.00y+00.00_i1Y_integrals.txt	exists
062gap025.000x+00.00y+00.00_i2Y_integrals.txt	exists
067gap030.000x+00.00y+00.00_i1X_integrals.txt	exists
068gap030.000x+00.00y+00.00_i2X_integrals.txt	exists
065gap030.000x+00.00y+00.00_i1Y_integrals.txt	exists
066gap030.000x+00.00y+00.00_i2Y_integrals.txt	exists
071gap040.000x+00.00y+00.00_i1X_integrals.txt	exists
072gap040.000x+00.00y+00.00_i2X_integrals.txt	exists
069gap040.000x+00.00y+00.00_i1Y_integrals.txt	exists
070gap040.000x+00.00y+00.00_i2Y_integrals.txt	exists
075gap050.000x+00.00y+00.00_i1X_integrals.txt	exists
076gap050.000x+00.00y+00.00_i2X_integrals.txt	exists
073gap050.000x+00.00y+00.00_i1Y_integrals.txt	exists
074gap050.000x+00.00y+00.00_i2Y_integrals.txt	exists
079gap060.000x+00.00y+00.00_i1X_integrals.txt	exists
080gap060.000x+00.00y+00.00_i2X_integrals.txt	exists
077gap060.000x+00.00y+00.00_i1Y_integrals.txt	exists
078gap060.000x+00.00y+00.00_i2Y_integrals.txt	exists
083gap080.000x+00.00y+00.00_i1X_integrals.txt	exists
084gap080.000x+00.00y+00.00_i2X_integrals.txt	exists
081gap080.000x+00.00y+00.00_i1Y_integrals.txt	exists
082gap080.000x+00.00y+00.00_i2Y_integrals.txt	exists

087gap100.000x+00.00y+00.00_i1X_integrals.txt	exists
088gap100.000x+00.00y+00.00_i2X_integrals.txt	exists
085gap100.000x+00.00y+00.00_i1Y_integrals.txt	exists
086gap100.000x+00.00y+00.00_i2Y_integrals.txt	exists

Sub folder: Fiducialization exists

HXU_005 Fiducial Report.pdf	exists

Sub folder: Gap Measurements exists

Sub folder: Gap Measurements\Touch Probe exists

002gap008.000taper-0.100.pdf	exists
002gap008.000taper-0.100.txt	exists
001gap009.000taper+0.000.pdf	exists
001gap009.000taper+0.000.txt	exists
003gap008.000taper+0.100.pdf	exists
003gap008.000taper+0.100.txt	exists
004gap008.000taper+0.300.pdf	exists
004gap008.000taper+0.300.txt	exists

Sub folder: Capacitive Sensors exists

gap_dat_ru1.dat	exists

Sub folder: Controls Data exists

hxu_005_parameters.txt	exists
hxu_005_k_vs_gap_spline.dat	exists
hxu_005_phase_match_enter_vs_gap_spline.dat	exists
hxu_005_phase_match_exit_vs_gap_spline.dat	exists
hxu_005_i1xvsgap_spline.dat	exists
hxu_005_i1yvsgap_spline.dat	exists
hxu_005_i2xvsgap_spline.dat	exists
hxu_005_i2yvsgap_spline.dat	exists

Summary of findings

Finding	Solution

Approval and Assignment by Heinz-Dieter Nuhn

Data Storage Checked:	Y	
Magnet Accepted:	Y	
Assigned Location:	HXU-005	

Heinz-Dieter Nuhn	Heinz-Dieter Nuhn	August 17, 2019
(Signature)	(Name)	(Date)