

PLC Programming Issues

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Why Use PLCs with EPICS



- **PLCs can perform low level interlocks and logic needed to protect equipment**
- **If the IOC communicating with the PLC is offline for some reason (software update, reboot, etc.) the PLC may still allow the process to remain in operation.**
- **Inexpensive local operator interface available for PLCs**
- **Long term hardware and software support provided by vendors**
 - » **Can still purchase new modules for 15 year old PLCs**

Why Use PLCs with EPICS



- **PLC operation is stable.**
 - » Once the PLC operation is verified, updates are very infrequent.
- **Changes can be made on-line with no reboot.**
 - » Process can remain running while changes implemented.
 - » Easy to roll back to previous version if unexpected results.
- **PLCs may be used where high-speed (millisecond and faster) data acquisition and control is not required**
 - » Fast enough for utility type systems; HVAC, vacuum, cooling tower water, Cryogenic, etc.
- **EPICS drivers are available for several PLCs**

PanelView Local Control Screen



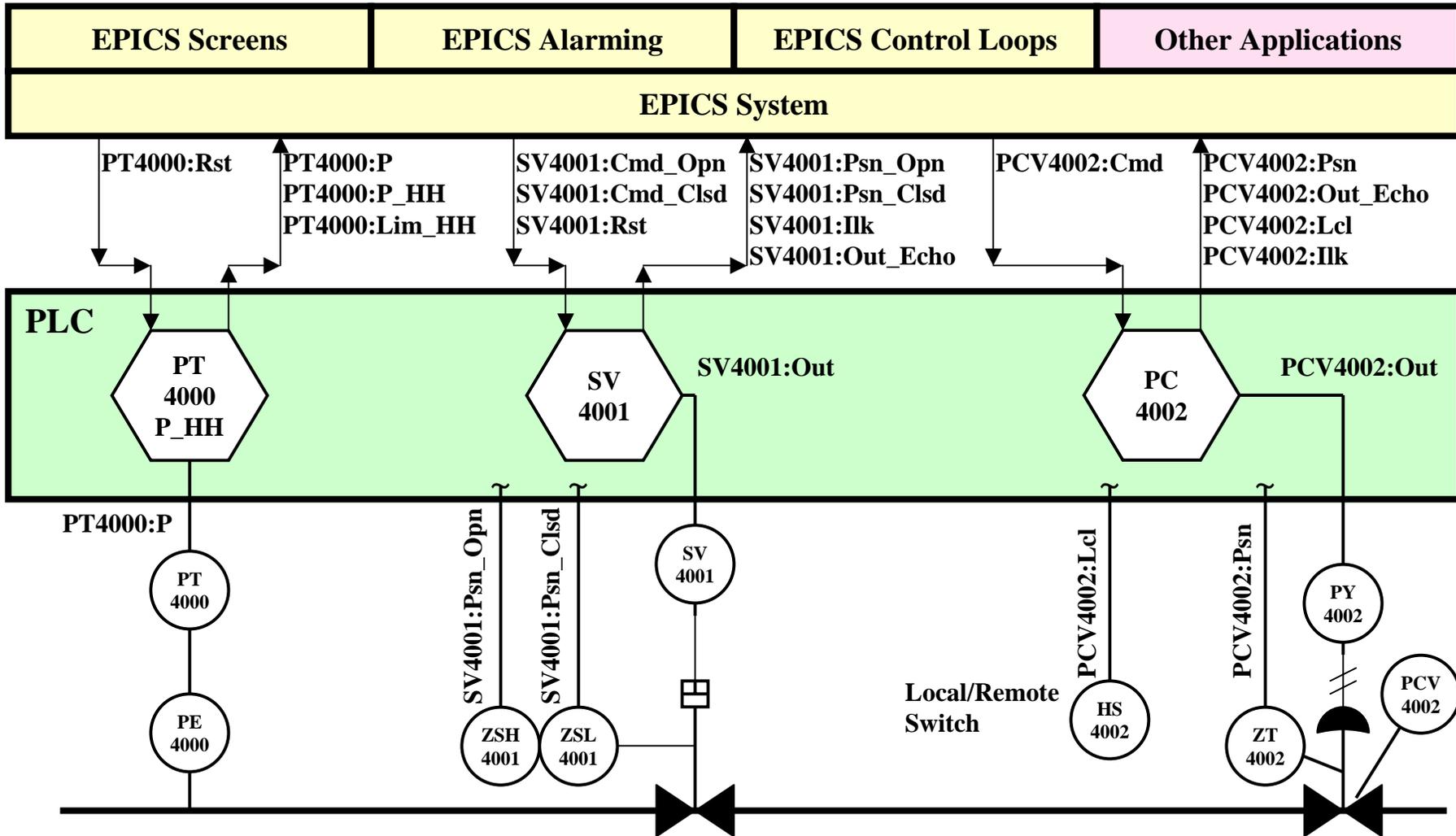
Key Switch **LOCAL**

GAS MANAGEMENT

VALVE	PV20205	PV20305	PV20611	PV20621	PV20601	PV20520
Process Variable	PT20103	PT20203	PT20331	PT20331	PT20331	TD3xxxx
PV Value	1.05	2.95	18.65	18.65	18.65	*****
Output to Valve	64.98	76.68	22.08	14.29	0.00	0.00
Desired Output	66.78	75.34	22.08	14.29	0.00	0.00
Select →	F3	F4	F5	F6	F7	F8
Mode	Remote	LOCAL	Remote	Remote	Remote	Remote
Select →	F11	F12	F13	F14	F15	F16

Navigation buttons: 7, 8, 9, 4, 5, 6, 1, 2, 3, ., 0, -, ←, ← (long), Prev, Next, F3-F8, F9-F16, <, ^, >, v

General Signals, PID loop closed in IOC



Contacts, Normally Open or Closed



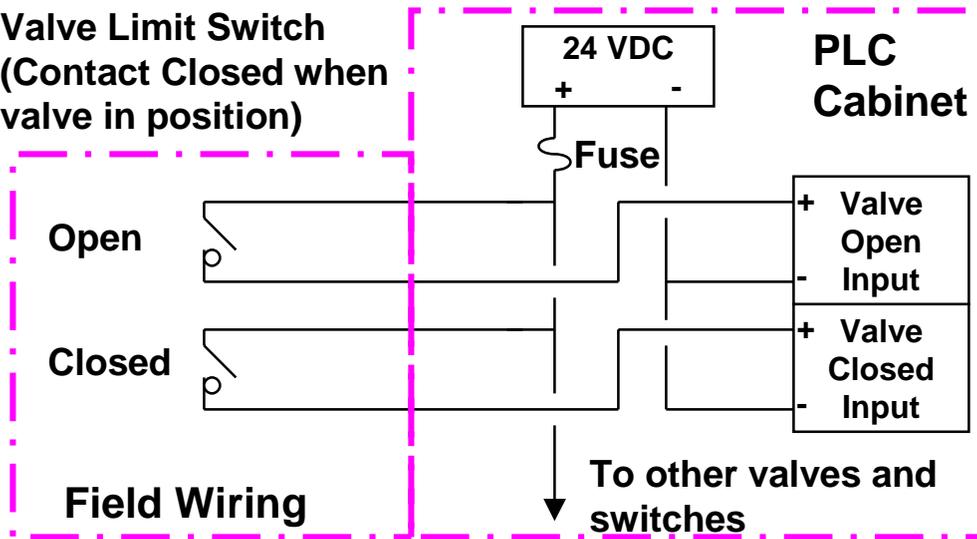
- All switches and contacts will be wired in a fail safe manner such that
 - A closed contact indicates a "good", "normal", or "known" condition
 - An open contact indicates an "alarm", "off normal", or "unknown" condition
- Position switches on solenoid valves
 - Positive indication of the valve position at each end of travel

Valve position switch wiring (1/2)



Normally Open Limit Switch

Valve Limit Switch
(Contact Closed when
valve in position)



PLC Input Bit
Open Closed

Meaning

0	0	Transition, fail if too long
0	1	Valve Closed
1	0	Valve Open
1	1	Fault

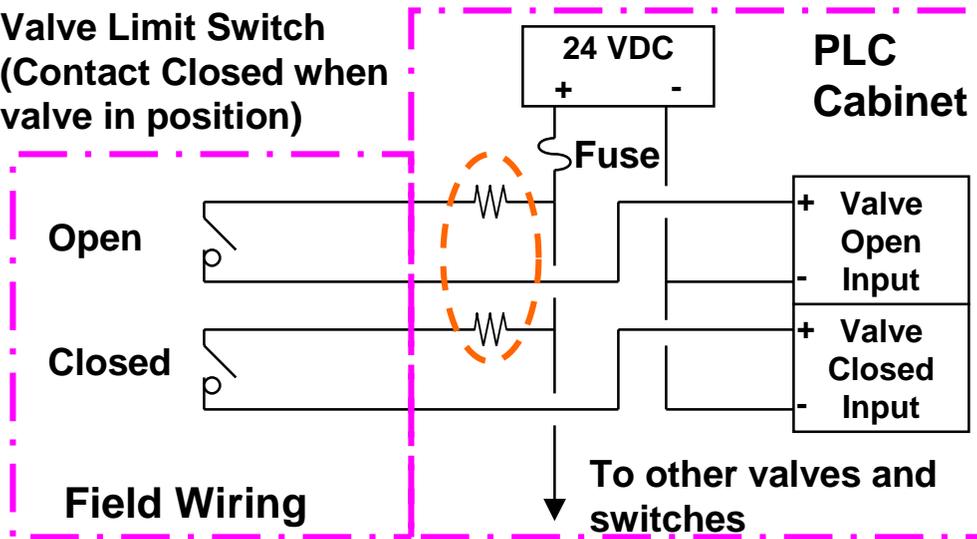
- **Advantage:** If a wire breaks, indication of that position is lost. If a valve in the beam path is open and the open wire breaks, the PLC will indicate that the valve is not open. The beam would be turned off. Fail Safe
- **Disadvantage:** If work is being performed on the valve and the +24 vdc is shorted to ground, indication of all other inputs powered by the same fuse will be lost.

Valve position switch wiring (2/2)



Normally Open Limit Switch

Valve Limit Switch
(Contact Closed when
valve in position)



PLC Input Bit
Open Closed

Meaning

0	0	Transition, fail if too long
0	1	Valve Closed
1	0	Valve Open
1	1	Fault

- **Advantage:** If a wire breaks, indication of that position is lost. If a valve in the beam path is open and the open wire breaks, the PLC will indicate that the valve is not open. The beam would be turned off. Fail Safe
- **Advantage:** If work is being performed on the valve and the +24 vdc is shorted to ground, indication for only that valve is affected.
- **Disadvantage:** Extra components to install and check. Added costs for installation

PLC General Operation



- **Some PLCs asynchronously read the inputs while processing interlock logic.**
 - » An input might change state part of the way through the program logic scan.
- **All PLC inputs should be scanned into input buffer arrays, analog and discrete, at the beginning of the each program scan so that any sequence dependent logic will operate on a time consistent set of inputs.**
- **Output modules should be configured to set the output to a known fail safe state in the event:**
 - » Communication to the PLC processor fails
 - » The PLC is not in the "Run" Mode
 - » The output module fails

EPICS to Allen-Bradley PLC Interface



- **The EPICS driver for communicating to ControlLogix PLCs over Ethernet will be used to transfer data between the PLCs and EPICS**
- **The most efficient method for data transfer is to use arrays in the PLC**
 - » **The transfer of one byte of data takes nearly as long as 512 bytes of data.**
 - » **Real or Integer (Int or DInt) arrays for analog I/O and control commands**
 - » **Boolean or Integer arrays for discrete I/O and control commands**

ControlNet Communication



- **Used to send and receive information from the concentrator PLC to remote PLCs**
- **Each node must have an unique address 1 to 99**
- **Data should be combined into arrays or user defined data types to minimize connections**
 - » **Use one user defined type tag for data from the remote PLC (producer) to the concentrator PLC (consumer)**
 - » **A second user defined type tag for data to the remote PLC (consumer) from the concentrator PLC (producer)**

EPICS and PLC watchdog signals



- A heart beat signal should be sent from the IOC to the PLC
- If the IOC heart beat signal stops
 - » The PLC will continue to process all interlocks
 - » The PLC will freeze the EPICS commands to all control devices
 - » The EPICS commands will remain frozen until the IOC heart beat is updated for at least 2 seconds
- The PLC will provide status information to the IOC
 - » PLC processor status
 - Mode: run, program, etc.
 - Major and minor fault data
 - Scan times
 - » I/O module status

Discrete Status Signals to/from EPICS



- For each type device, a group of bits should be reserved in the PLC array for transfer of process information to EPICS
- A standard format (bit order) should be developed for each type of device
- All EPICS command signals should be momentary
- Input, interlock, and status variables should be copied into the buffer array read by EPICS
- The elements in the EPICS buffer array should not be used in the PLC interlock logic since the elements could potentially be modified by EPICS

Analog Input Signals



- The ControlLogix analog I/O modules have the capability to convert signals to engineering units
- Thermocouple and RTD signals should be converted to engineering units by the T/C and RTD I/O modules.
 - » The converted values will be monitored by EPICS
- Linear analog input signals should be converted to engineering units by the analog input module. Example:
 - » A pressure transmitter with a 4 – 20 ma output that is calibrated such that 0 PSIG = 4 ma and 30 PSIG = 20 ma.
- Non-linear analog input signals should be converted to engineering units by the IOC

Analog Output Signals



- Use real values, not integer, for all analog signals
- Analog input and output module scaling
 - » Configure the current modules to scale the 4 to 20 ma signals so that 0.0 ma = -25.0% and 20.0 ma = 100.0 %. This allows the EPICS to send a slightly negative value if there is some drift in the operation of the control device.
 - » Configure the voltage modules to scale the 0 to 10 vdc signal to 0.0 to 100.0 %.
- This should make the EPICS scaling easier since all analog signal raw values will be a percent of full scale.

Alarms



- **All alarm generation should be done in EPICS**
 - » Alarm processor works well
 - » Limits readily available to the operator
 - » Limits are included with several record types
 - » Easy to add new alarms
- **Some PLC modules have the ability to check alarm limits and generate alarm status bits**
 - » Maintenance of limits is difficult
 - » Alarm limit data may be hidden from operator
 - » Additional PLC and EPICS work required to allow operator modification of limits
 - » Additional EPICS work required to handle the status bits
 - » Hard to add new alarms, reconfigure module
 - » Not recommended

Interlock Signals



- **These are signals like high pressure alarm, low temperature alarm, etc. that are used to indicate alarm conditions and/or to initiate an action performed by the PLC logic**
- **Alarm action limits and alarm status bits should be monitored by EPICS**
- **When an interlock input signal (analog or discrete) indicates an alarm condition, a bit in the PLC should be latched to indicate the alarm status**
- **EPICS will provide a reset command to reset the latched PLC bit**
 - » **If the alarm condition no longer exists, the PLC alarm latch bit will be reset**
 - » **If the alarm condition still exists, the EPICS reset command will have no affect on the PLC alarm latch bit**

Control Algorithms



- **PLCs include instructions for performing many control equations including standard PID instructions.**
- **In general, it is better to implement PID loops in EPICS**
 - » **Input and output signals may come from different IOCs**
 - » **Easy to substitute an alternate process variable if the primary process variable sensor fails**
 - » **Tuning coefficients more readily available to operator**
 - » **Update time adjustable by operator**
- **PIDs may be implemented in the PLC**
 - » **If communication delays between the IOC and PLC are too great for proper loop operation**
 - » **If all input and output signals needed for a PID loop are connected to a PLC**
 - » **If IOC reboot cannot be tolerated in the control loop**

Recommendations



- **Use PLCs where**
 - » High availability of interlock control is required
 - » Maintenance of control capability is required even during IOC reboot
 - » High speed data acquisition and control is not needed
 - » Complex control algorithms are not required
 - » Remote I/O is needed

- **Do not use PLCs**
 - » For I/O modules, VME is probably less expensive
 - » For alarm generation
 - » For high level sequences