**SLAC Magnetic Measurement Plan and Traveler for 100A Unipolar**

**LCLS-II Quadrupoles of Type 2Q4W (SA-344-112-08)**

This traveler is intended to cover mechanical fiducialization and magnetic measurements of the 2Q4W quadrupole magnets needed for LCLS-II bypass line in Li28. There are a total of 2 of these magnets needed in that area. The configuration for these magnets are, SA-344-112-08. The table below gives the MAD names, polarities, and installation directions of the 100 A unipolar 2Q4W quadrupoles (the order in the beam line is QBP35 first and then QBP28).

|  |  |  |  |  |  |
| --- | --- | --- | --- | --- | --- |
| **MAD Name** | **Eng. Name** | **Drawing#** | **Barcode** | **Polarity** | **Bus bars** |
| QBP35 | 2Q4W | SA-344-112-08 | 4238 | QD | upstream |
| QBP28 | 2Q4W | SA-344-112-08 | 4237 | QF | upstream |

**Receiving:**

The following information is to be noted upon receipt of the magnets by the SLAC MM group:

|  |  |
| --- | --- |
| Received by (MMG initials): | SDA |
| Date received (dd-mm-yyyy): | 3/8/2019 |
| SLAC barcode number: | 4237 |
| Vendor serial number on the magnet: | 38 |

**Preparation:**

A beam direction arrow, with text “beam direction”, is to be applied to the top and/or connector side of the magnet with a sticker supplied by LCLS-II (F.-J. Decker will determine the direction).

|  |  |
| --- | --- |
| Beam-direction arrow in place (initials): | SDA |

**Fiducialization:**

Fiducialization may be done before or after magnetic measurements. The magnet is to be fiducialized by the CMM group. This will require the installation of removable tooling balls, location of the geometric axis of the poles of the magnet, and location of tooling balls with respect to the center of this geometric axis when the poles are aligned precisely horizontal.

|  |  |
| --- | --- |
| CMM technician (initials): | KC |

URL of on-line CMM fiducialization data (please modify or correct if necessary):

|  |
| --- |
|  http://www-group.slac.stanford.edu/met/MagMeas/MAGDATA/LCLS-II/Fiducial%20Reports/4237\_Fiducial\_Report.pdf |

**Magnetic Measurements:**

Enter URL of on-line magnetic measurements data (please modify or correct if necessary):

|  |
| --- |
| http://www-group.slac.stanford.edu/met/MagMeas/MAGDATA/LCLS-II/Quad/4237 |

1. Determine the connection polarity (with main supply outputting positive current) which produces a “positive” field polarity and “negative” field polarity as shown below:

 

**Figure 1**. Polarity convention for magnets having “positive” (left) and “negative” (right) polarities.

1. Mark the polarity near the magnet leads with clear “+” and “” labels as shown above.

|  |  |
| --- | --- |
| Magnet polarity chosen from Fig. 1 is (P or N): | P |

1. Connect the magnet to the LCW supply. The total magnet flow should be 0.8 gpm. Record the ΔP and flow below.

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| --- | --- |
| Record total flow rate and pressure. | 0.8 gpm @ 112 psi |

1. Connect the magnet terminals in the correct polarity as established above, to a unipolar power supply with maximum current *I* ≥ 100 A.
2. Run the magnet up to 100 A for ~30 minutes to warm it up (record temperature).

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| --- | --- |
| LCW delta T (°C) | 1.0 °C |
| Ambient temperature (°C): | 16.4 °C |
| Final magnet steel temperature (°C): | 25.6 °C |

1. Standardize the magnet, starting from zero to 100 A and back to zero, through three full cycles, finally ending at zero, with a flat-top pause time (at both 0 and 100 A) of 10 seconds. Use a three liner ramp rate of 20 A/sec, if possible, and record the ramp rate used.

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| Standardization complete (initials): | SDA |
| Ramp rate used (A/sec): | 20 A/sec |

1. If the power supply can be run as low as 4 A with <10-mA (0.5%) rms current regulation, then measure ∫*Gdl* from 0 to 100 A following the current range step sizes given in the table below.

|  |  |  |
| --- | --- | --- |
| **Current Range** | **Step Size Up** | **Step Size Down** |
| 0 to 20 A | 4-A | 4-A |
| 20 to 80 A | 10-A | 20-A |
| 80 to 100 A | 5-A | 10-A |

|  |  |
| --- | --- |
| Filename & run number of ∫*Gdl* up & down data: | Strdat.ru1, strplt.ru1 |

1. For all magnets, with rotating coil, measure the magnet harmonics at 20, 50, 100 A current setting. Multipole values should be given as a percentage of the quadrupole moment evaluated at the probe radius.

|  |  |
| --- | --- |
| Filename & run number of harmonic data: | Hardat.ru1, harplt.ru1 |
| Probe radius used for harmonics (cm): | 1.95965 |
| Rotating Coil Designation (Name) | 48BC1.6 |

1. Confirm the pole-tip field using a Hall probe at an excitation current of 100 A.

|  |  |
| --- | --- |
| Hall probe pole-tip field at 10 A (mean of 4 poles): | 0.286 +/- 0.01 T @ 99.9750 A |

1. For one magnet only, perform a final thermal test. Run the current up to 100 A. Measure the magnet temperature after it stabilizes (2-4 hours?). Record the temperature below.

|  |  |
| --- | --- |
| LCW delta T (°C) | 1.3 oC |
| Ambient temperature (°C): | 18.7 oC |
| Final magnet steel temperature (°C): | 27.2 oC |

1. Measure the inductance and resistance of the magnet:

|  |  |
| --- | --- |
| Inductance of coil (mH): | 2.208 mH |
| Resistance of coil (Ohms): | 0.06609 Ohm |
| Magnet temperature in degrees C | 26.3 oC |

1. Upon completion of tests, email URL of on-line data to Mark Woodley. Mark Woodley will determine if the magnet is accepted. Upon acceptance of magnet, analysis data will be placed in on-line data folder.

|  |  |
| --- | --- |
| Magnet accepted and Analysis file(s) put into on-line data folder (initials): | SDA |
| Assigned beamline location (MAD-deck name): | **QBP28** |