Superconducting Undulators Development at European XFEL

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Outline

- SCU development plans at the EuXFEL
- SCU afterburner
- S-PRESSO
- Summary



Motivation for SCU at EuXFEL

EuXFEL is investing on the development of the technology for SCUs for its facility development program

SCU afterburner for SASE2 undulator beamline will

allow lasing above 30keV

- A future possible whole undulator beamline at the EuXFEL would allow to:
 - generate photon energies of ~100keV
 - enhance the tunability range from hard to soft X-rays at the same electron beam energy
 - keep the photon energies generated now in pulsed mode operation, if the linac would be upgraded to CW operation.
 - CW operation will be possible at 8 GeV, while now the maximum electron beam energy is 17.5 GeV

SCU development plans at the EuXFEL

- SCU afterburner
- S-PRESSO: Superconducting undulator PRE-SerieS mOdule to be produced before the five modules of the SCU afterburner
- Vertical and horizontal test stands for SCU at DESY-site
- Additional activities on SCUs
 - EuXFEL R&D project on Advanced SCU coils. In collaboration with Mechancal Engineering Group. Postdoc: V. Grattoni
 - LEAPS activity on pulsed wire method to determine the magnetic field profile of long structures (~2 m) with short periods (<20 mm). Postdoc: J. Baader</p>

slide courtesy: S. Casalbuoni

SCU afterburner



The cooling scheme of S-PRESSO and of the afterburner modules will be based on cryocoolers

SC phase shifter for the cold intersection

- Requirements for the phase shifter:
 - The phase shifter guarantees continuous tunability between the photon energy tanges offered by the possible energies at the EuXFEL with a phase integral of $PI = 1.5 \times 10^{-5} T^2 m^3$
 - The available intersection length for the phase shifter is $L_{int} = 1.1m$



- The magnetic length of the phase shifter should be minimized to have a compact magnetic structure
- The magnetic length is defined as the length of the interval in which the first field integral I_1 is above $4 \times 10^{-6} Tm$
- The conditions on the field integral are the following:
 - ► $I_1 < 4 \times 10^{-6} Tm$
 - $I_2 < 1 \times 10^{-4} Tm^2$





V. Grattoni et al., "Superconducting Phase shifter design for the afterburner at the European XFEL", SRI2021, submitted

slide courtesy: S. Casalbuoni

S-PRESSO

Aims of S-PRESSO are to test:

- the alignment of the two 2m long SCU coils in the 5m long cryostat
- the mechanical tolerances necessary for the FEL process
- the implementation of the module in the accelerator

S-PRESSO will be used to

- amplify the hardest radiation generated by the SASE2 PMUs
 - ▶ in this configuration we will check the performances of S-PRESSO
 - test harmonic schemes to generate larger photon energies

S-PRESSO parameters



V. Gratto



SUPERCONDUCTING UNDULATOR PRE-SERIES MODULE

Mechanical tolerances study for S-PRESSO

GENESIS simulations have shown that for $\sigma\left(\frac{\Delta K}{K}\right) = 1.5 \times 10^{-3}$, more than 95% of the mean power with respect to the ideal case can be reached.

FEL simulation done considering a whole SCU beamline

Mechanical tolerances required for S-PRESSO

Pole height	Winding vert. shift	Pole width	Coil width
±20 μm	±20 μm	±10 µm	±10 µm

with deviation from the average period length $\leq 20 \ \mu m$



Detailed study can be found in the backup slides

V. Grattoni et al., "An analytical study to determine the mechanical tolerances for the Afterburner Superconducting Undulators at EuXFEL", SRI2021, submitted

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Option for correction scheme

If the following mechanical tolerances cannot be satisifed

Pole	Winding	Pole	Coil
height	vert. shift	width	width
±20 µm	±20 μm	±10 µm	±10 μm



- Shimming with a wire of 0.25mm diameter is considered as correction scheme.
- Several correction coils powered by a maximum of 10 power supplies with max current of 10 A might be applied

Shimming the coils with a current of 10 A enables a correction up to $\frac{\Delta K}{K} \le 1.6 \times 10^{-2}$



Alignment for S-PRESSO

The allowed misalignment between the two 2 m long coils should be: measurable

keep the error budget contribution negligible: $\sigma\left(\frac{\Delta K}{K}\right) \ll 1.5 \times 10^{-3}$ for each set of SCU coils



slide courtesy: S. Casalbuoni

Vertical and horizontal test stands for SCU at DESY-site



Test SCU coils up to 2m long in liquid or superfluid helium

B. Marchetti et al., "Liquid Helium vertical test-stand for 2m long superconducting undulator coils", SRI2021, submitted

Additional activities on SCUs

EuXFEL R&D project on Advanced SCU coils



Winding machine







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V. Grattoni, SLAC, 22.04.22

Thank you for the attention

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Backup slides

Impact of mechanical deviations on the field

- A shorter undulator (15 periods) is considered to characterize the effect on the magnetic field from different mechanical errors (signatures) with FEMM
- Each parameter of the coil has been varied while keeping the other ones constant and equal to the design value. This procedure allows to find the sensitivity of the K value to the precision of each varied parameter.
- The signature ΔB is defined as follows:

$$\Delta B = \tilde{B} - B_0$$

where B_0 is the ideal field and \tilde{B} is the field with a mechanical error.



Signatures from FEMM simulations

Error on one pole of the undulator, width +30µm 2 2 B-field with error B-field with error signature $\times 10^2$ signature $\times 10^2$ 1.5 1.5 1 0.5 0.5 B field [T] B field [T] 0 0 -0.5 -0.5 -1 -1 -1.5 -1.5 -2 -2 -0.2 -0.15 -0.1 -0.05 0.05 0.15 0.2 -0.2 -0.15 -0.1 -0.05 0.05 0.15 0.2 0 0.1 0 0.1 z [m] z [m]

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Signatures from FEMM simulations

Error on one pole of the undulator, height +50µm



Error on the groove width, and also on the pole width shows a sinusoidal signature

Error on the winding package

- is the dervative of a Gaussian function when it is a vertical shift
- is a Gaussian function when it is a horizontal shift
- Error on the pole height is described by a Gaussian function

Correspondent Mechanical Tolerances

The amplitude of the signature is **linearly related** with the error size for small error amounts

- \rightarrow to find the linear relation, a pair of error sizes are simulated for each error type.
- \rightarrow each amplitude can be related with the max. $\frac{\Delta K}{\kappa}$
 - → all the values of the magnetic field positive and negative peaks B_{peak} and the position of the peaks are stored
 - \rightarrow from the difference of the position of consecutive peaks, we get the half period length $\frac{\lambda_u}{2}$
 - → We can finally get $\frac{K}{2} = 93.4 \cdot |B_{peak}| \cdot \frac{\lambda_u}{2}$ and $\Delta K/2$ is calculated between the difference of the max. $\frac{K}{2}$ of the field with and without the error

Correspondent Mechanical Tolerances

Genesis simulations show that a $\sigma\left(\frac{\Delta K}{K}\right) \le 1.5 \times 10^{-3}$ should be kept in order to preserve high quality FEL lasing

The error size for each error type that we can tolerate are shown in the plot



Montecarlo Simulation

The tolerances used for S-PRESSO are:

Pole	Winding	Pole	Coil
height	vert. shift	width	width
±20 μm	±20 μm	±10 µm	±10 μm

Additionally: deviation from the average period length $\leq 20 \ \mu m$

We apply the four errors at each half period length

Montecarlo Simulation

- The total signature that should be added to the ideal field to get the real field is generated as shown in the video
- The error amount is generated using an uniform distribution (worst case) in +/- the range of the tolerance
- For the Montecarlo simulation, we generate50 different fields.



Correspondent errors to the deviation assumed in the GENESIS simulation

Errors have a **uniform distribution** (worst case) in +/the values range in the table below

م ا	$\left(\Delta K\right)$	_	1 0	\mathbf{v}	10-3
0	K /	_	1.0	^	10

Mechanical error	Range [µm]
Pole width	10
Groove width	10
Winding vertical deviation (dcentercoil)	20
Pole height	20

Tolerances are tighter for the period length $\lambda_u = 15 \ mm$, while S-PRESSO period is $\lambda_u = 18 \ mm$



Option for correction scheme

If the following mechanical tolerances cannot be satisifed

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height vert. shift		width	width
±20 μm	±20 μm	±10 µm	±10 μm

- Shimming with a wire of 0.25mm diameter is considered as correction scheme.
- Several correction coils powered by a maximum of 10 power supplies with max current of 10 A might be applied

Shimming the coils with a current of 10 A enables a correction up to $\frac{\Delta K}{K} \le 1.6 \times 10^{-2}$



Conclusions

Genesis simulations confirm that for $\sigma\left(\frac{\Delta K}{K}\right) = 1.5 \times 10^{-3}$, more than 95% of the mean power with respect to the ideal case can be reached.

The tolerances specified for S-PRESSO are:

Pole	Winding	Pole	Coil
height	vert. shift	width	width
±20 μm	±20 μm	±10 µm	±10 μm



The Montecarlo study shows that we can achieve a $\sigma\left(\frac{\Delta K}{K}\right) = 1.8 \times 10^{-3}$ considering a period length $\lambda_u = 15 \ mm$

If it is not possible to satisfy the mechanical tolerances, shimming the coils with a current of 10 A enables a correction up to $\frac{\Delta K}{K} = 1.6 \times 10^{-2}$