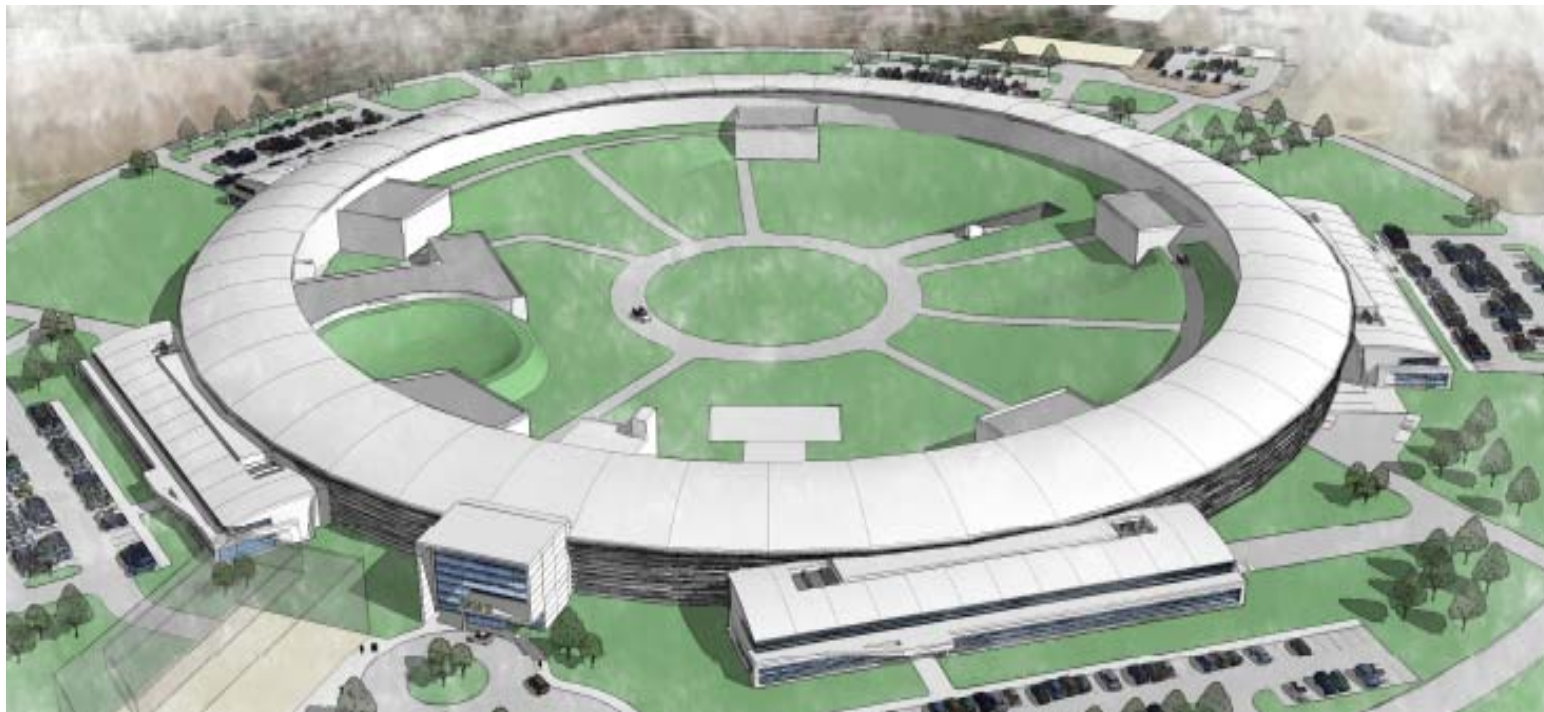


# Vibrating Wire R&D for Alignment of Multipole Magnets in NSLS-II



10<sup>th</sup> International Workshop on Accelerator Alignment  
February 11-15, 2008, Tsukuba, Japan

Animesh Jain for the NSLS-II magnet team

# Collaborators

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# Introduction

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- For optimum performance, the magnetic axes of quadrupoles and sextupoles in NSLS-II should be aligned to better than  $\pm 30$  microns.
- Optical survey accuracy (~50 microns) is inadequate to achieve the required tolerance.
- It is difficult, and expensive, to maintain the required machining and assembly tolerances in a long support structure (~5 m) holding several magnets.
- It is desirable to achieve the required alignment using direct magnetic measurements in a string of magnets.

# Magnet Alignment R&D

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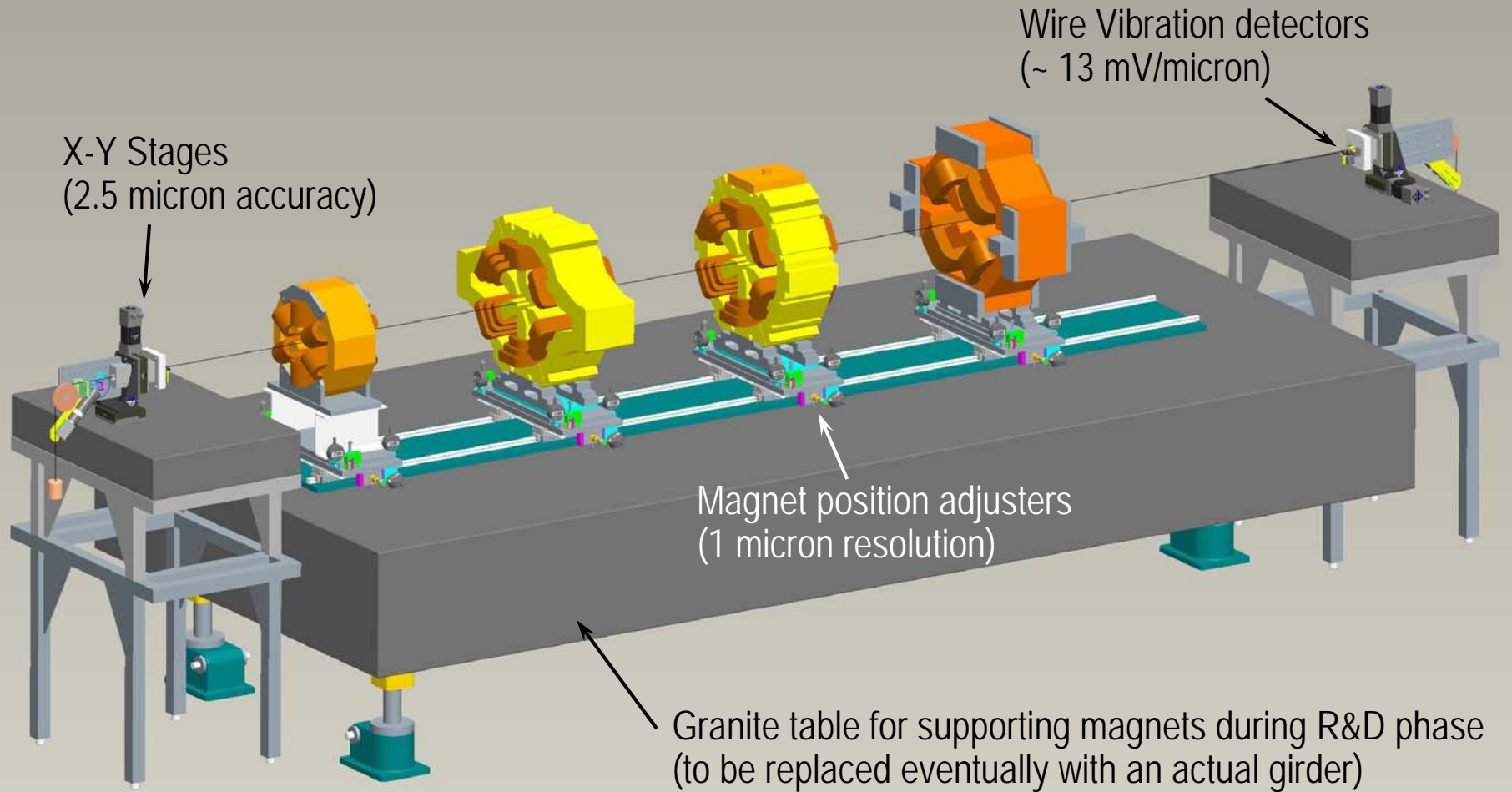
- Several magnets, including multipoles and corrector dipoles, will be installed on a girder ~5-6 m long.
- Based on the accuracy required, and the overall length of the girders, the vibrating wire technique developed at Cornell was deemed most appropriate for this task.
- An R&D program was initiated to develop the technique at BNL and demonstrate the required accuracy.
- Preliminary work was carried out using a temporary setup with help from Cornell and staff from NSLS.
- A new R&D setup was designed and is now operational.

# The Vibrating Wire Technique: Basics

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- In this technique, an AC current is passed through a wire stretched axially in the magnet.
- Any transverse field at the wire location exerts a periodic force on the wire, thus exciting vibrations.
- The vibrations are enhanced if the driving frequency is close to one of the resonant frequencies, giving high sensitivity.
- The vibration amplitudes are studied as a function of wire position to determine the transverse field profile, from which the magnetic axis can be derived.
- Vibration amplitudes measured at many resonant modes can also give the axial distribution of field along the wire.

# Vibrating Wire R&D Setup at BNL



Unique feature: Vibration sensors are installed on both ends, giving two simultaneous measurements

# Vibrating Wire R&D Setup: Wire Ends & Sensors

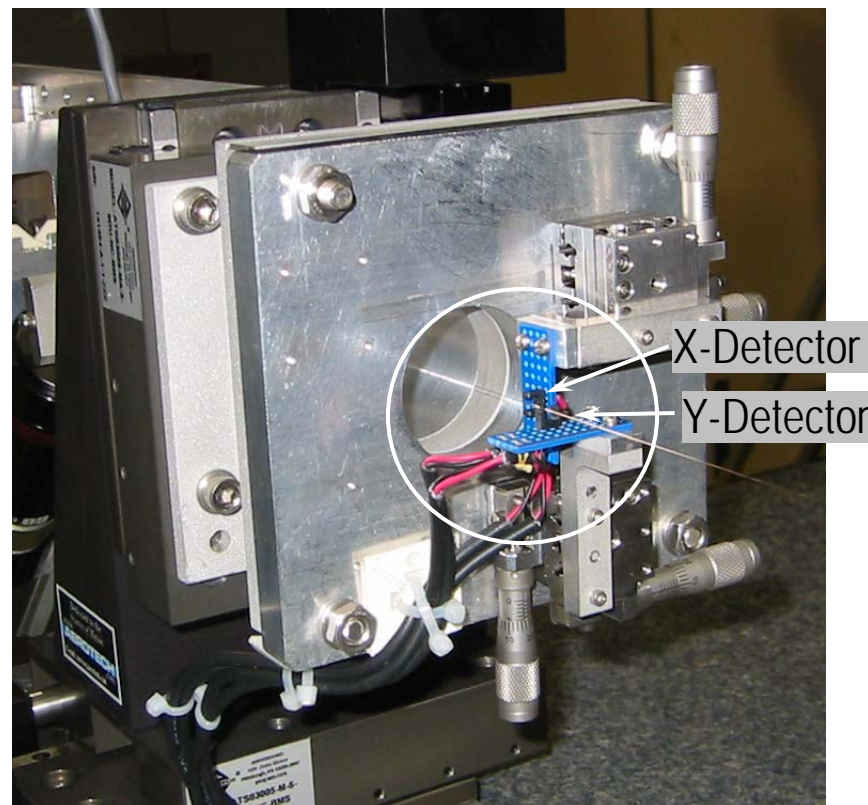
Fiducial nests (earlier version)



Wire Ends Details

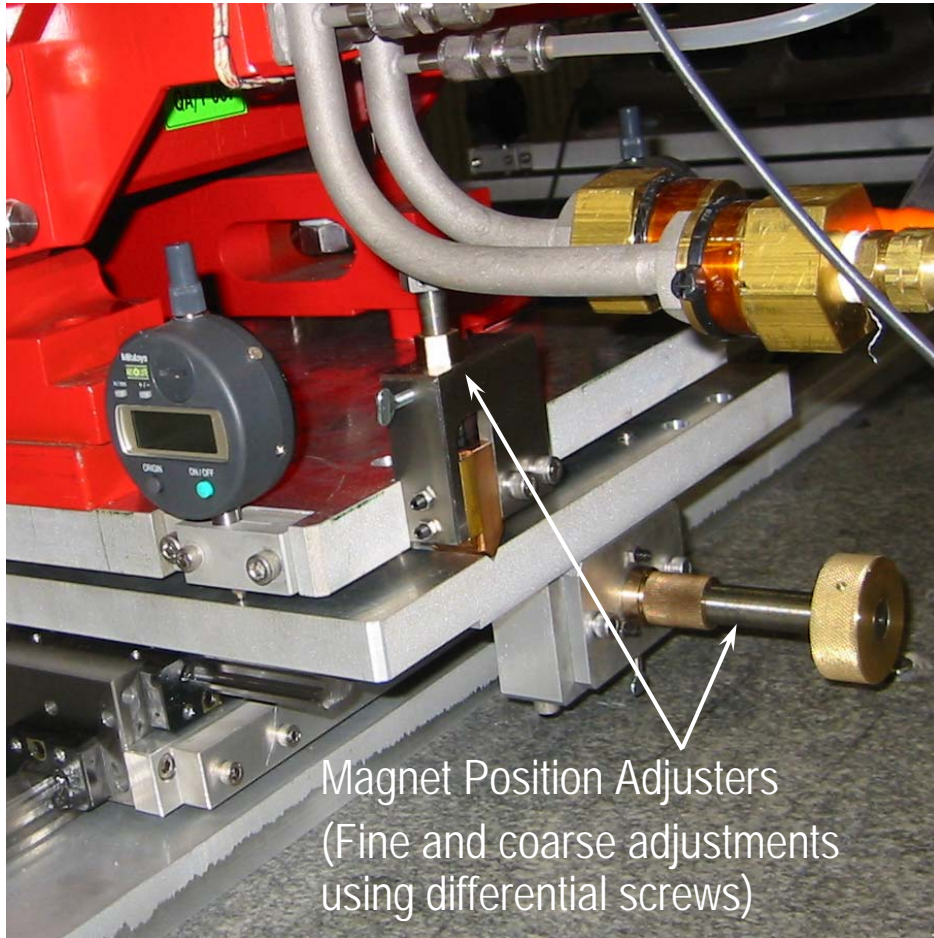
Fiducials relate the wire ends to the overall girder coordinate system.

New version has 4 fiducials



Wire Vibration Sensors

# Vibrating Wire R&D Setup: Manual Magnet Movers



Magnet Position Adjusters  
(Fine and coarse adjustments  
using differential screws)

First version with stainless steel parts did not work very smoothly. New version with Silicon-Bronze parts works well.



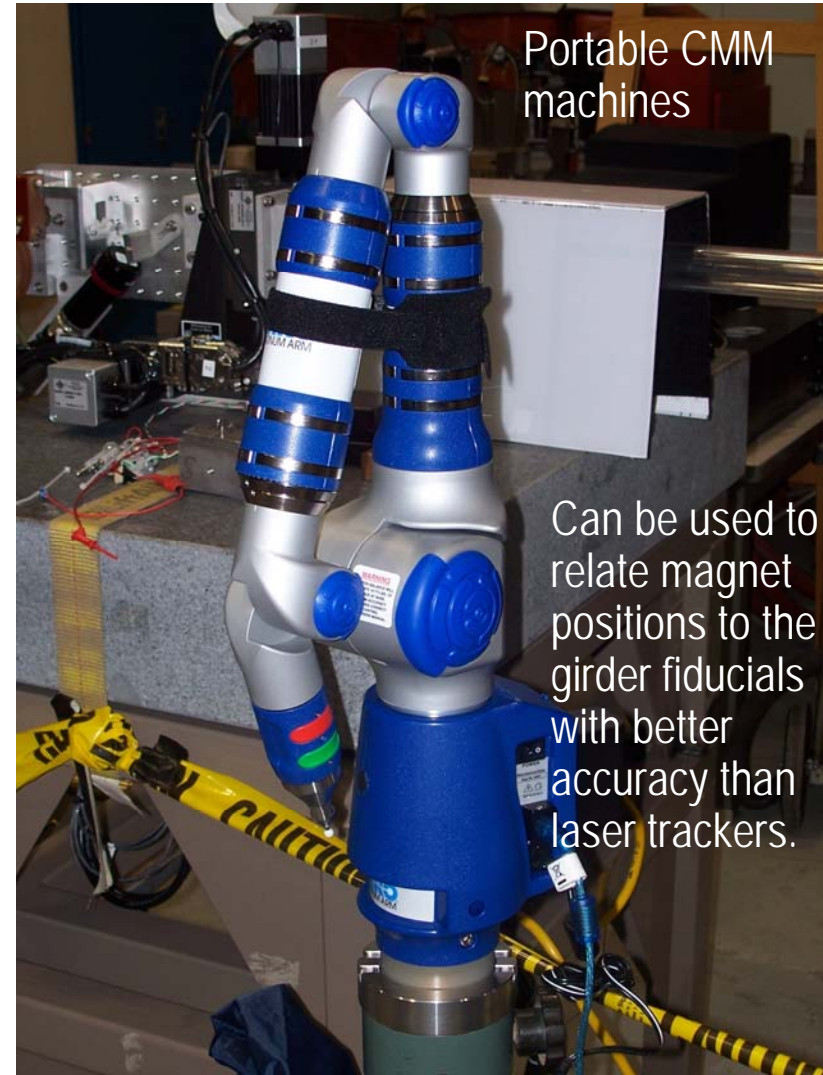
Dial indicators to monitor magnet motion.  
Mounting of horizontal indicators is now  
improved from an earlier version.



# Survey Equipment



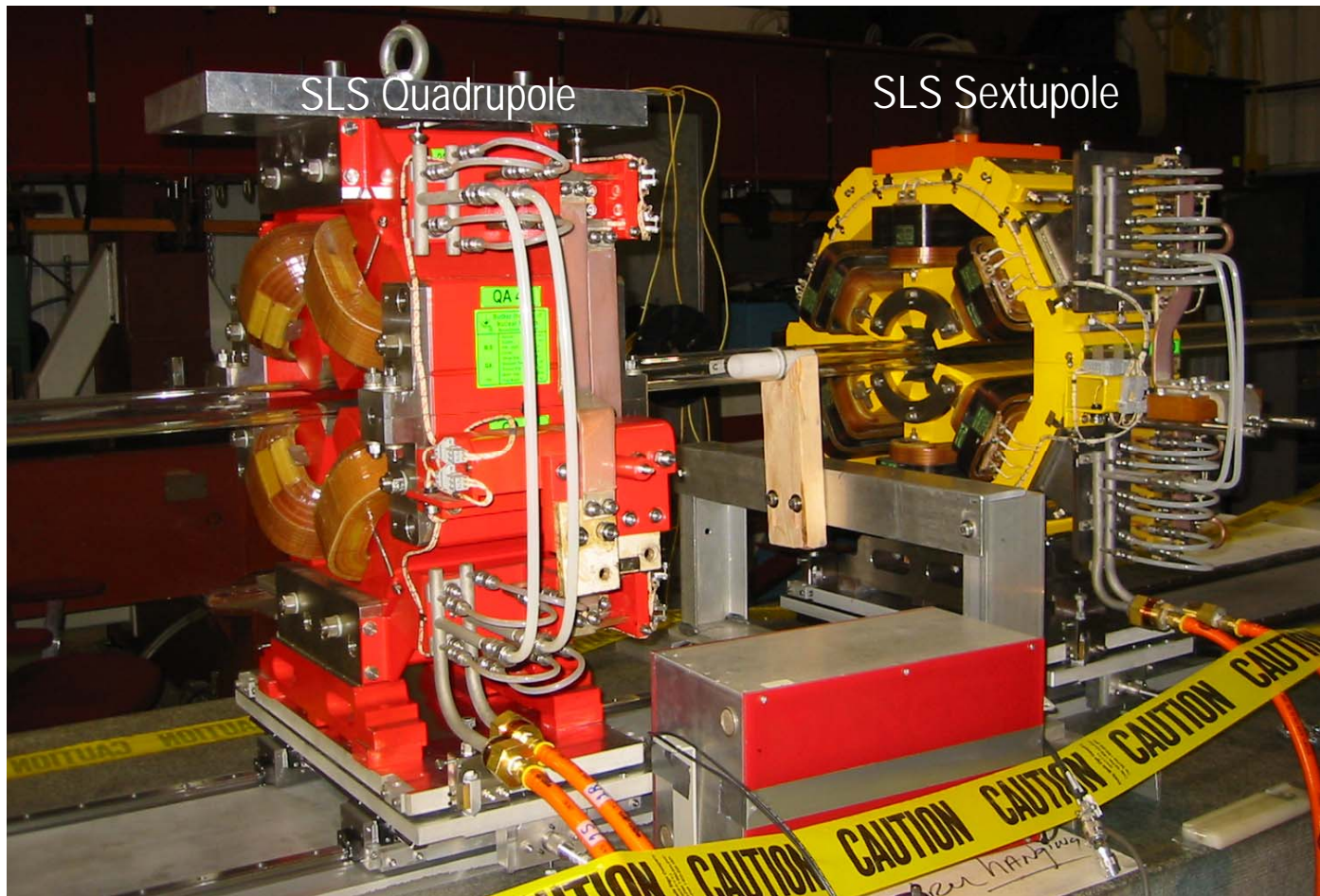
Laser Trackers  
To be used for survey of girder and wire fiducials.



Portable CMM machines

Can be used to relate magnet positions to the girder fiducials with better accuracy than laser trackers.

# SLS Magnets in the Vibrating Wire Setup



SLS Quadrupole  
at 80 A:

$$\int_{-\infty}^{\infty} \frac{dB_y}{dx} dz = 3.19 \text{ T}$$

$$\frac{dB_y}{dx} = 13.8 \text{ T/m}$$

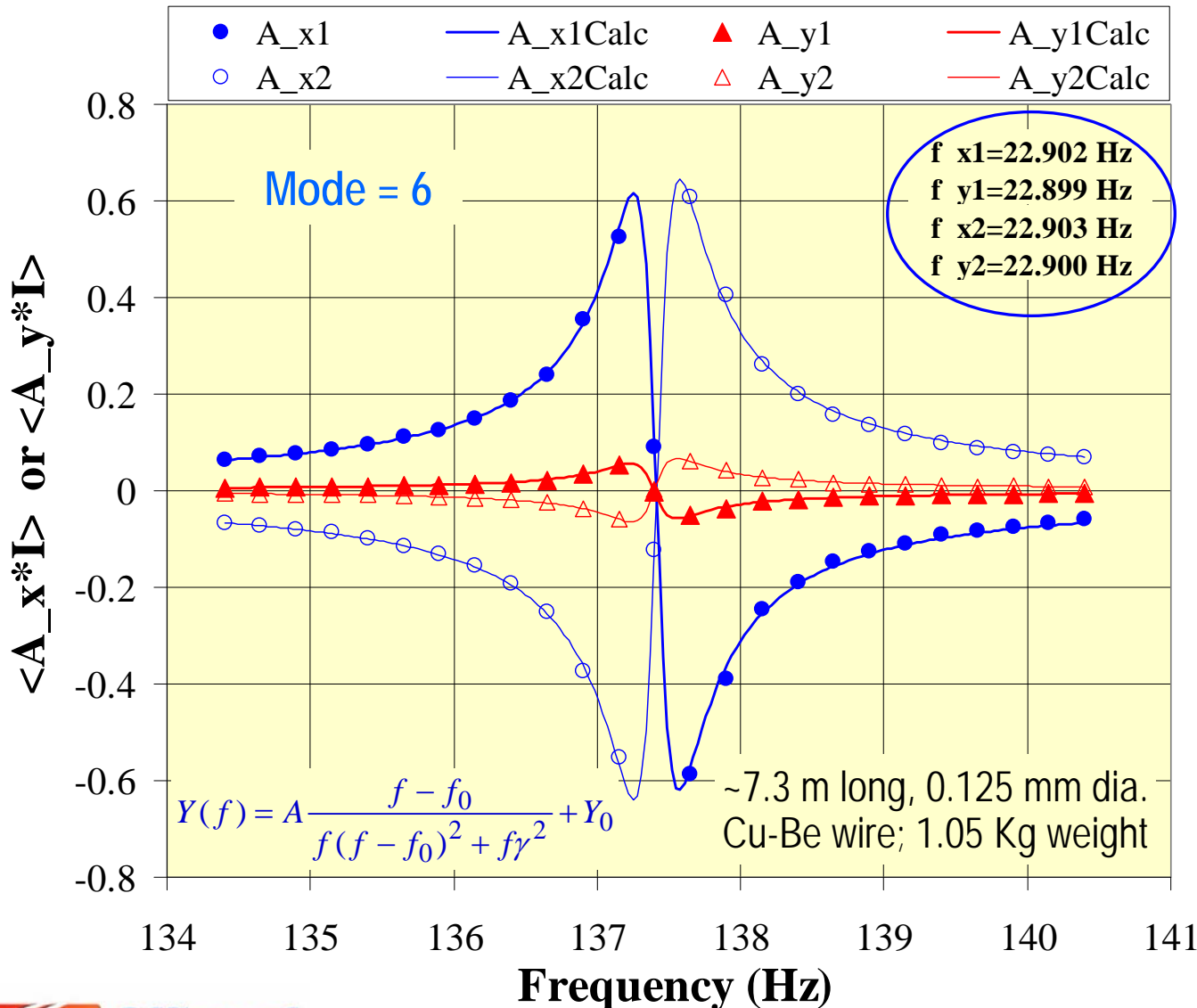
SLS Sextupole  
at 80 A:

$$\int_{-\infty}^{\infty} \frac{d^2 B_y}{dx^2} dz = 94.2 \text{ T/m}$$

$$\frac{d^2 B_y}{dx^2} = 430 \text{ T/m}^2$$

Magnets can be run at currents up to 140 A, but saturation begins at ~80 A

# Resonant Frequency and Wire Sag



$$f_0 = \frac{1}{2L} \sqrt{\frac{T}{m_\ell}} \quad \begin{array}{l} T = \text{Tension} \\ L = \text{Length} \end{array}$$

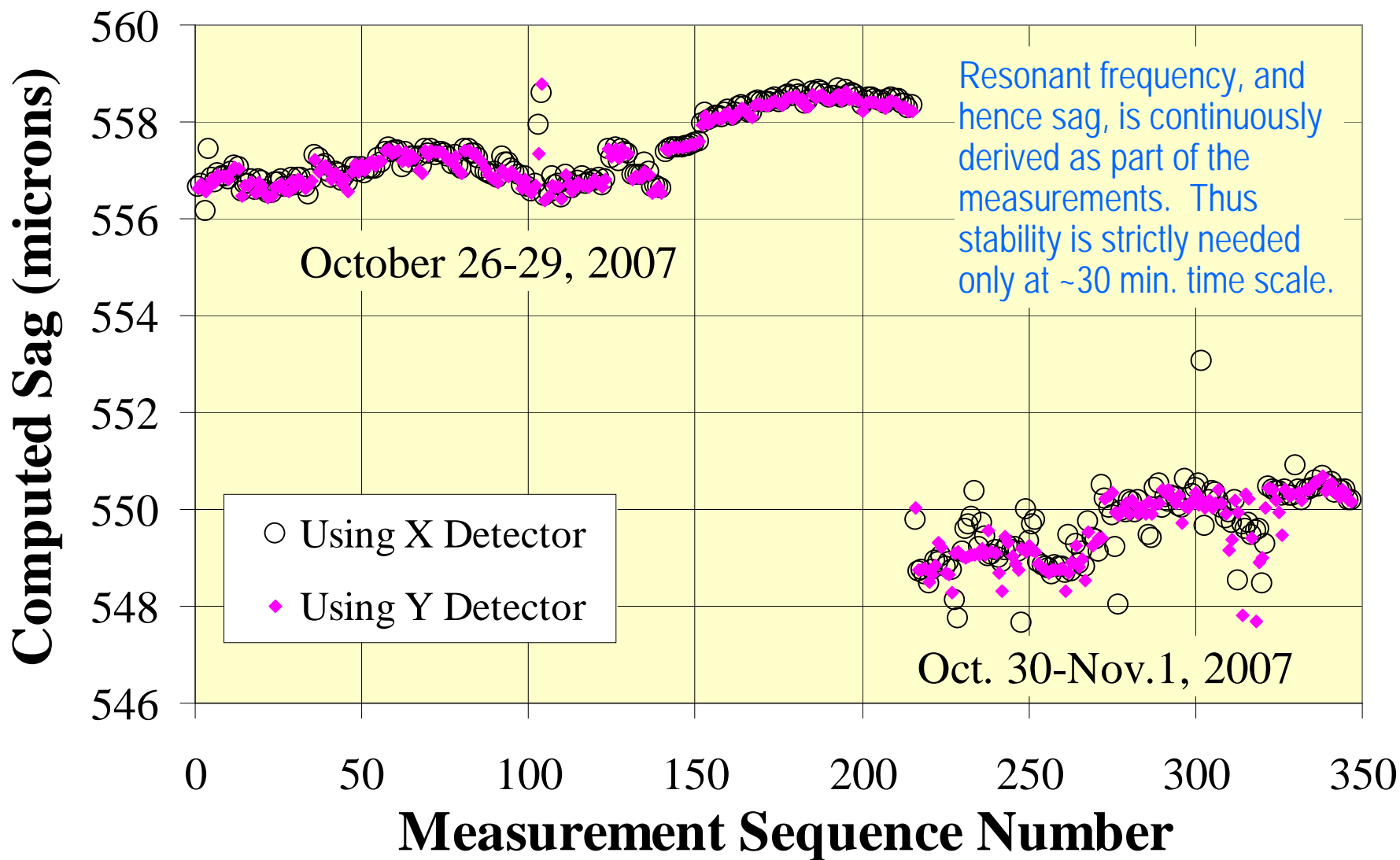
$$\text{Sag} = \frac{m_\ell g L^2}{8T} \quad \begin{array}{l} m_\ell = \text{mass} \\ \text{per unit} \\ \text{length} \end{array}$$

$$\text{Sag} = \frac{g}{32 f_0^2}$$

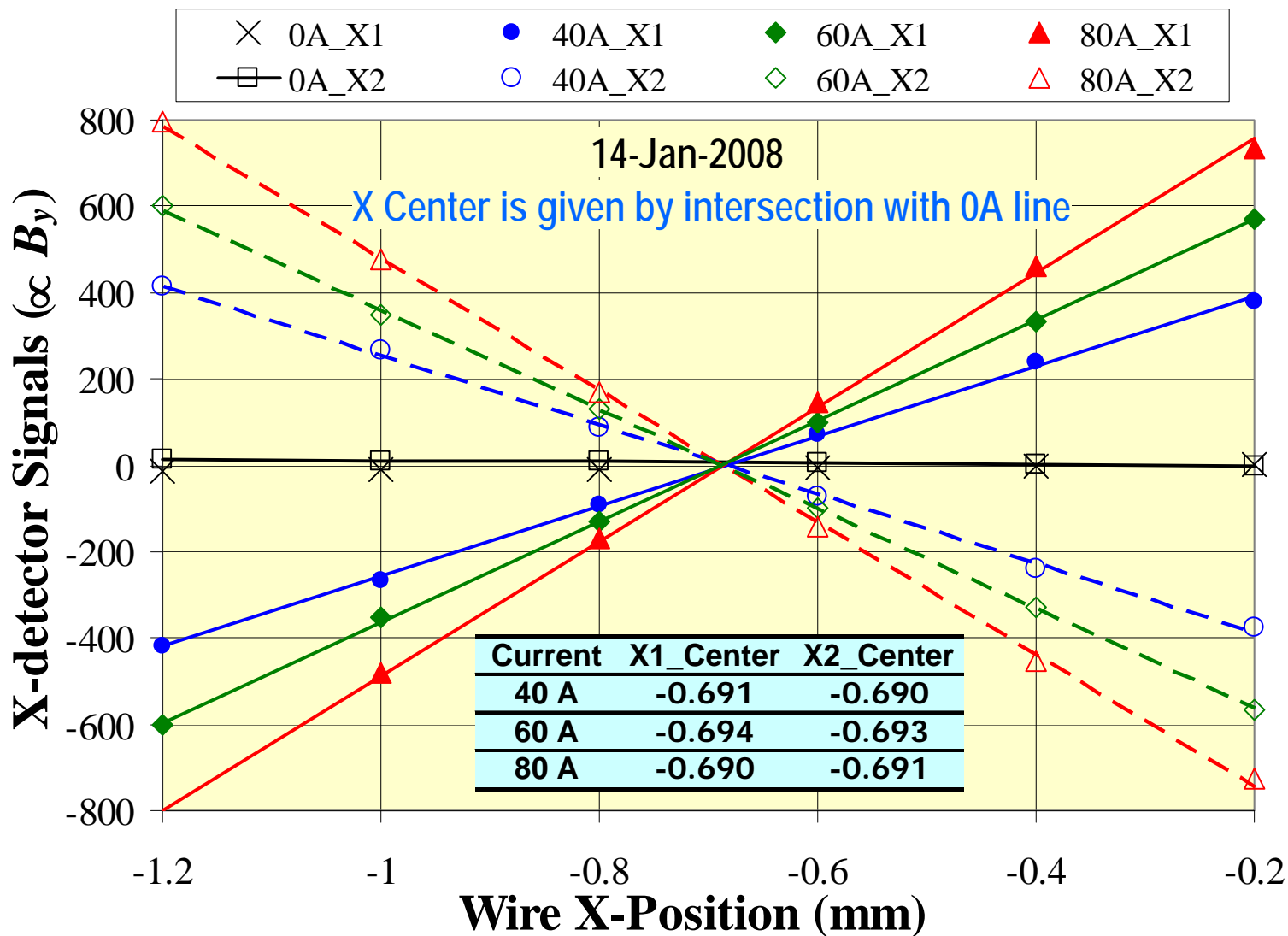
Correction for large wire sag (~550-600 microns for ~7.3 m length) is very important, which in turn requires a very precise knowledge of resonant frequency.

$\pm 0.02$  Hz  $\Rightarrow$   $\pm 1$  micron

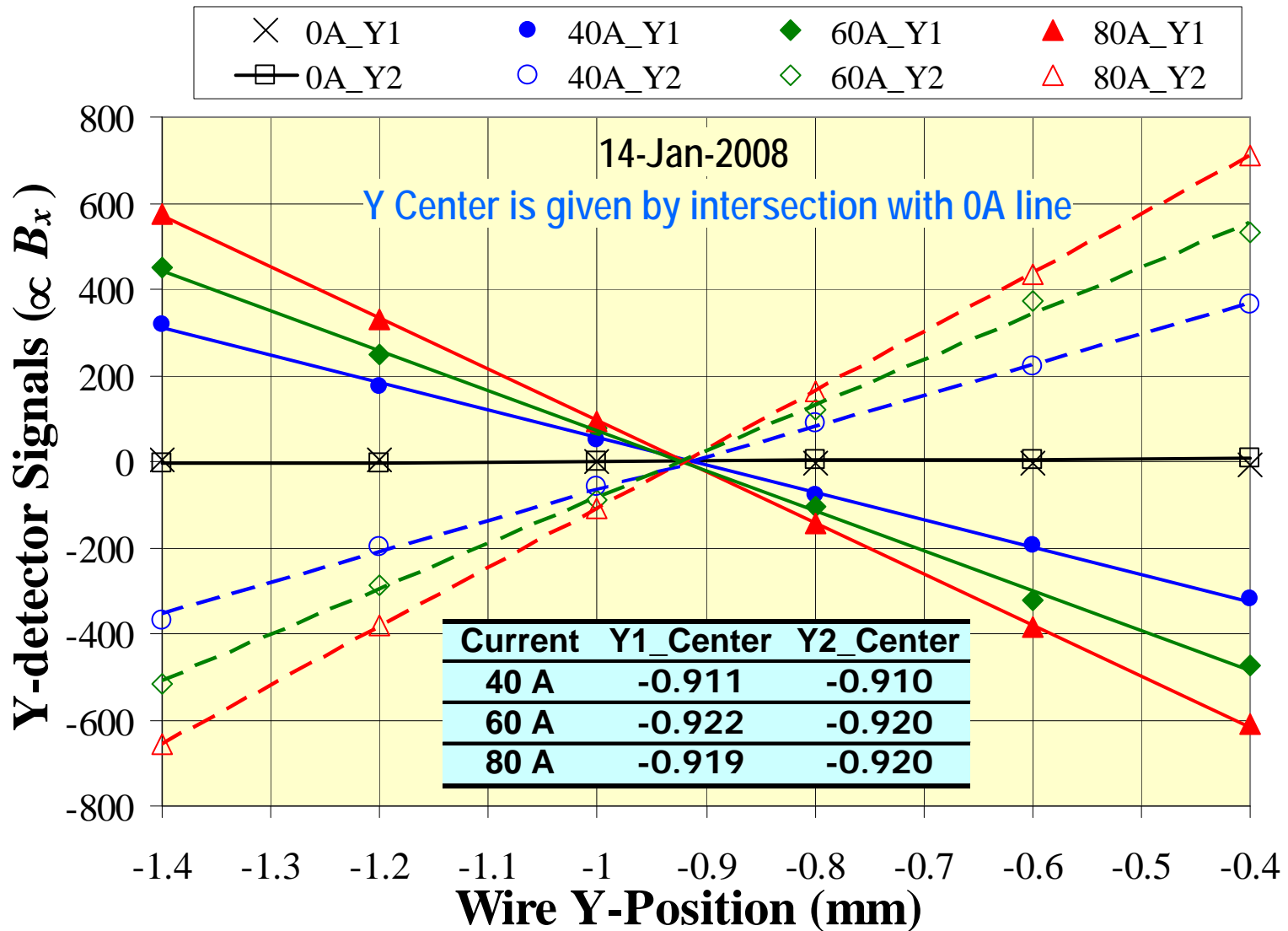
# Stability of Wire Sag Over Several Days



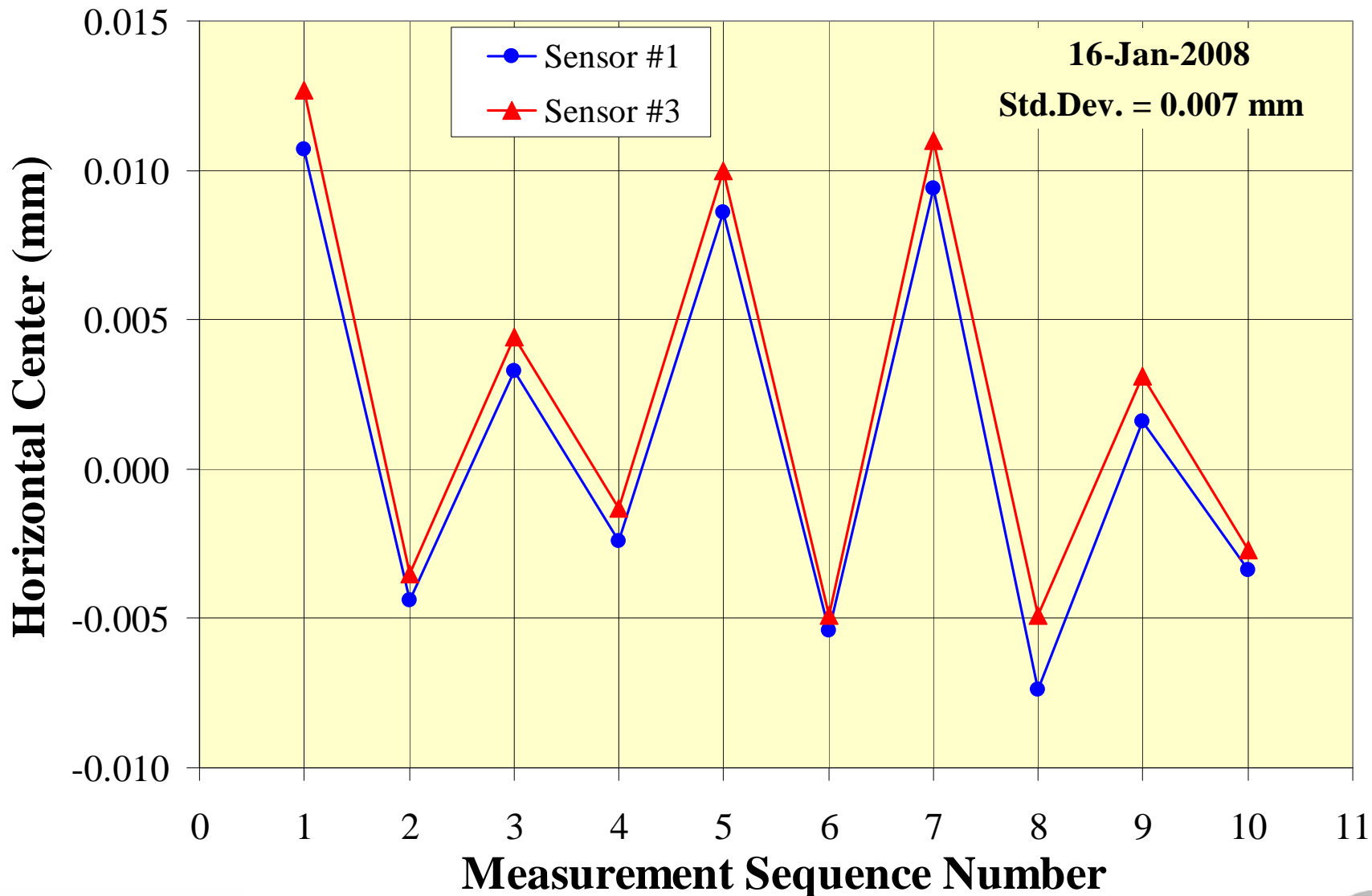
# Quadrupole Measurements: Horizontal Scans



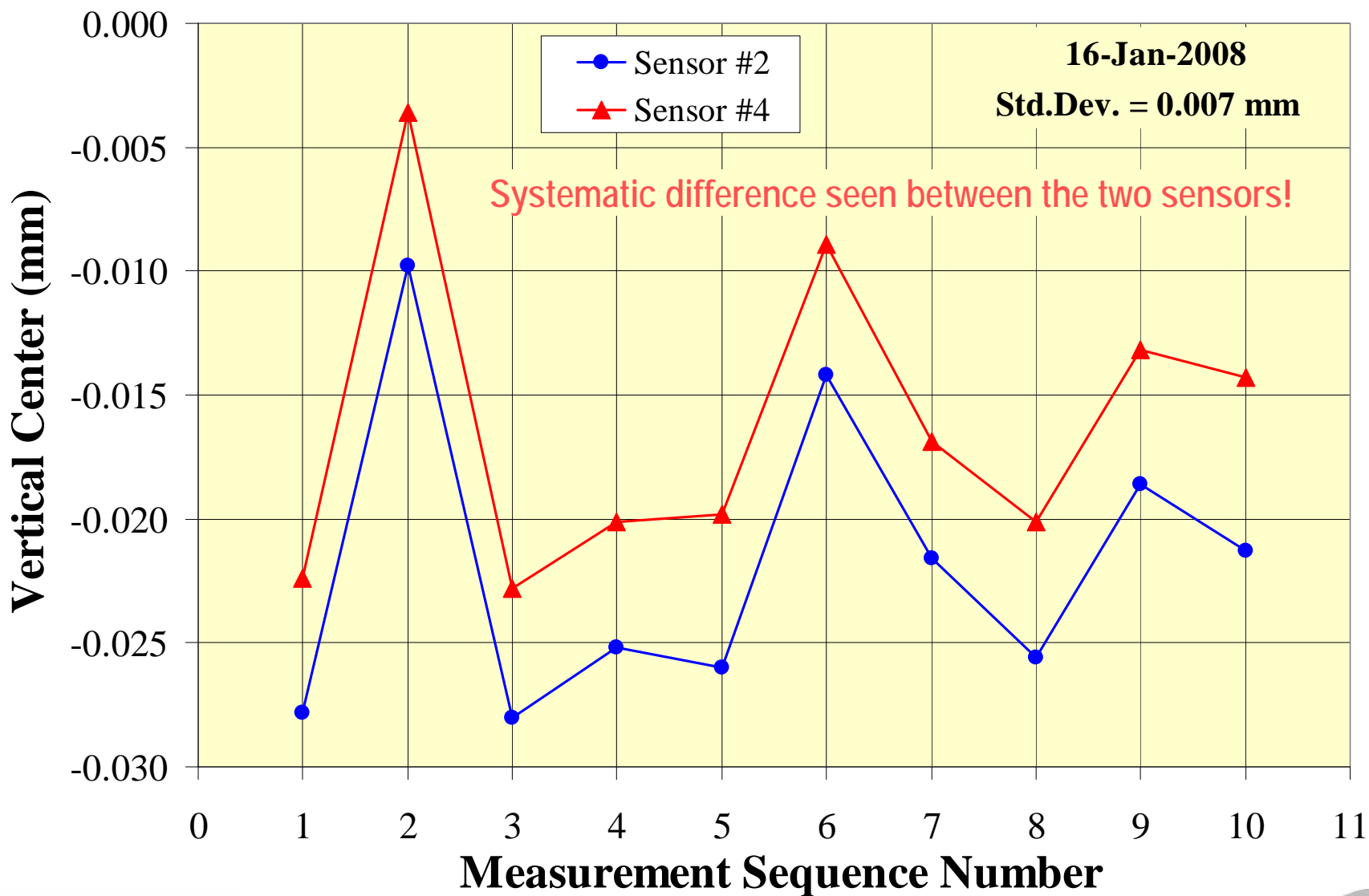
# Quadrupole Measurements: Vertical Scans



# Quadrupole Measurements Reproducibility



# Quadrupole Measurements Reproducibility



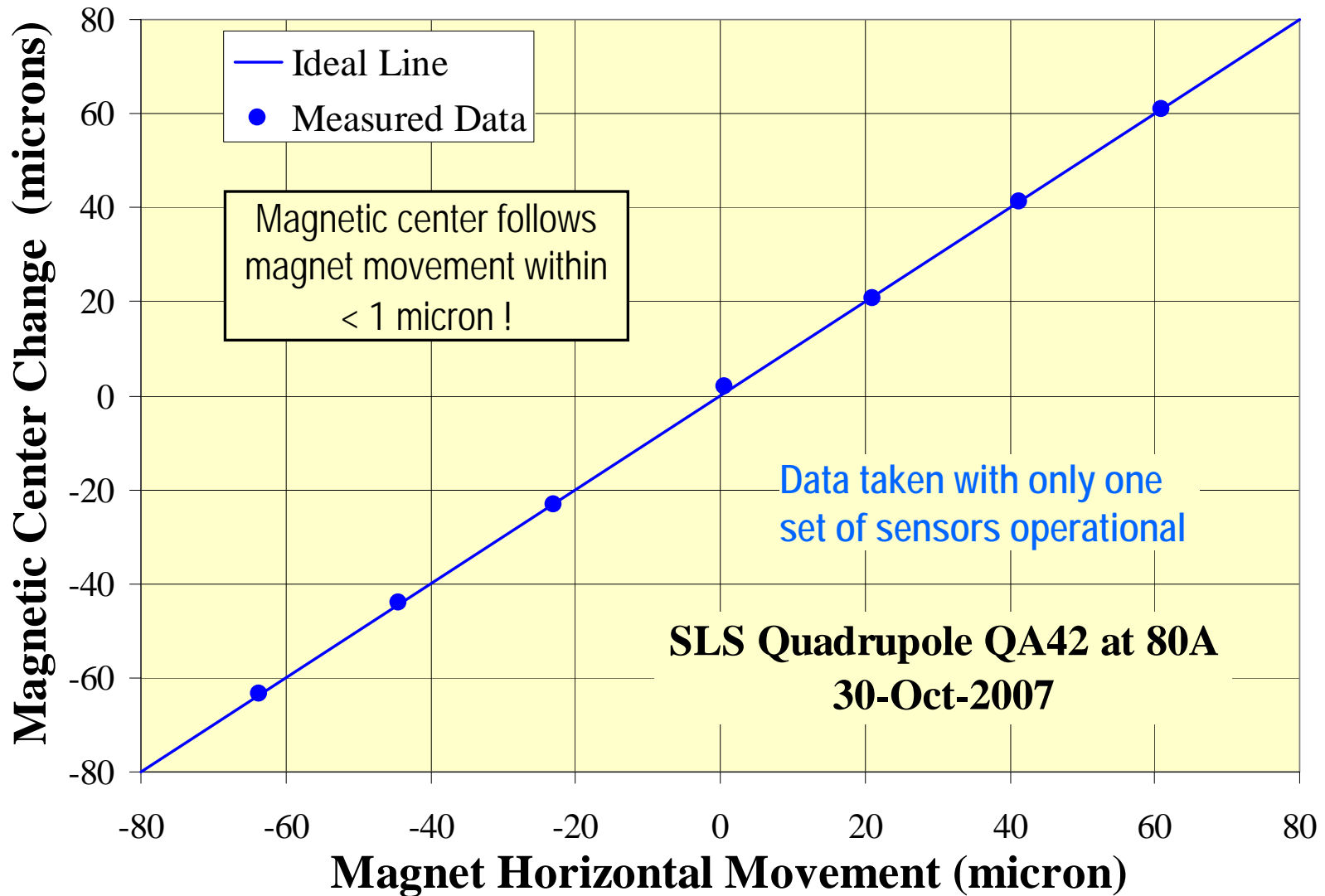


# Study of Measurement Resolution: Concept

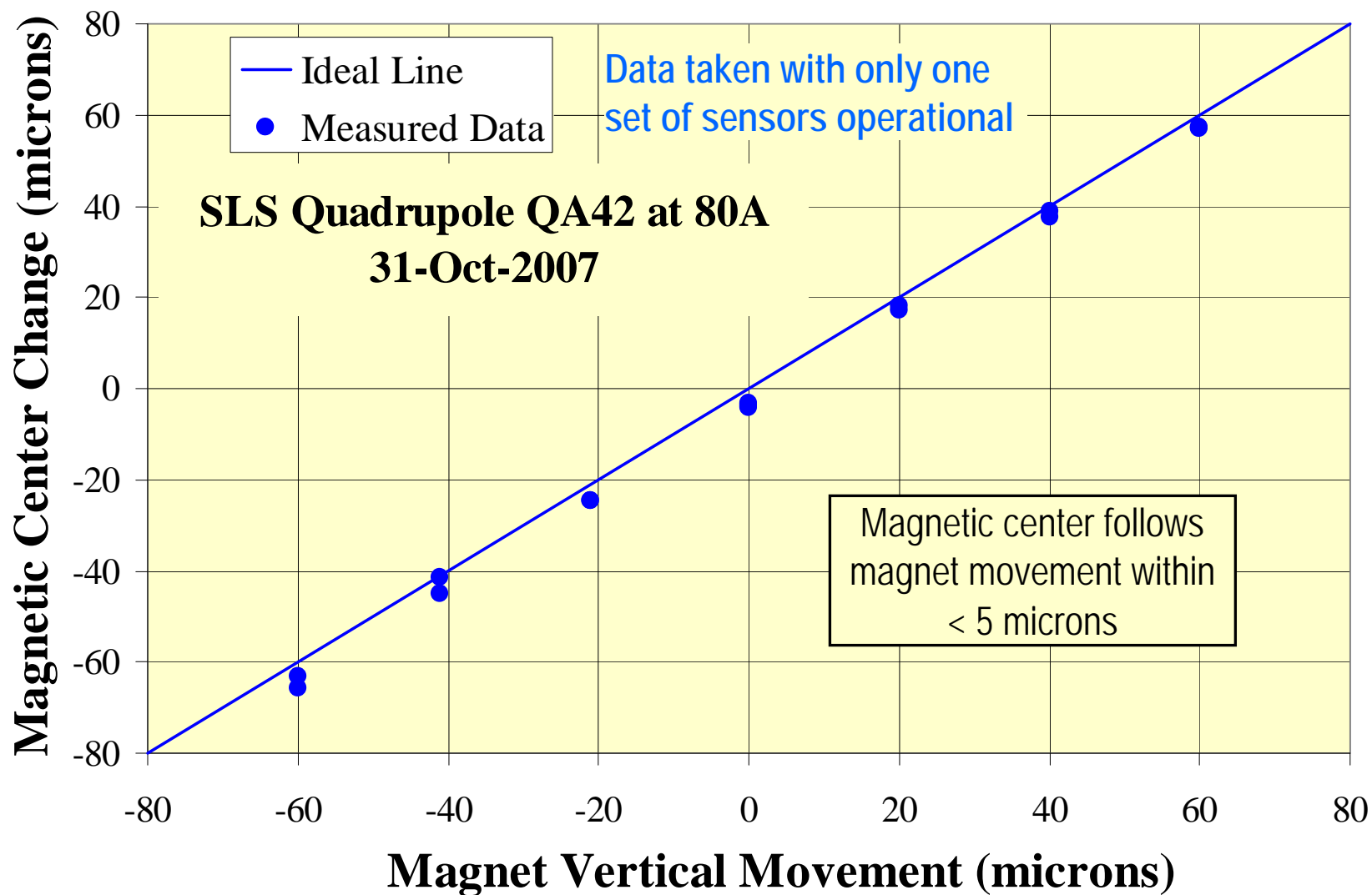
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- Measurements have been made in a SLS quadrupole and a SLS sextupole to study the measurement resolution achievable in each case.
- Magnetic center was first measured in the as-installed position of the magnet using vibrating wire technique.
- The magnet was then moved either horizontally or vertically by a known amount, as monitored by dial indicators.
- Vibrating wire measurements were made again and the results compared against dial indicators.

# Correlation with Magnet Moves (Quad; Horiz.)

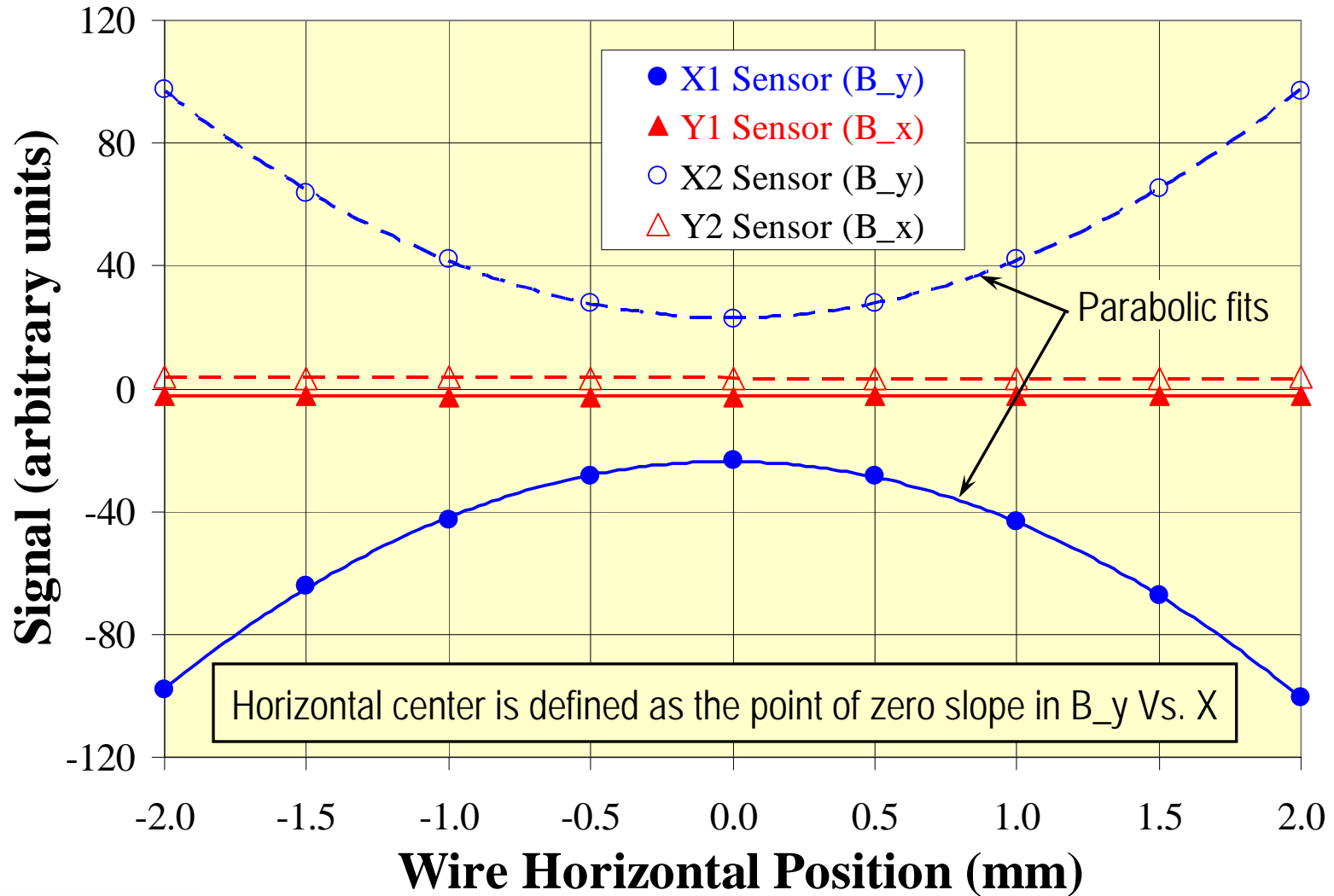


# Correlation with Magnet Moves (Quad; Vertical)



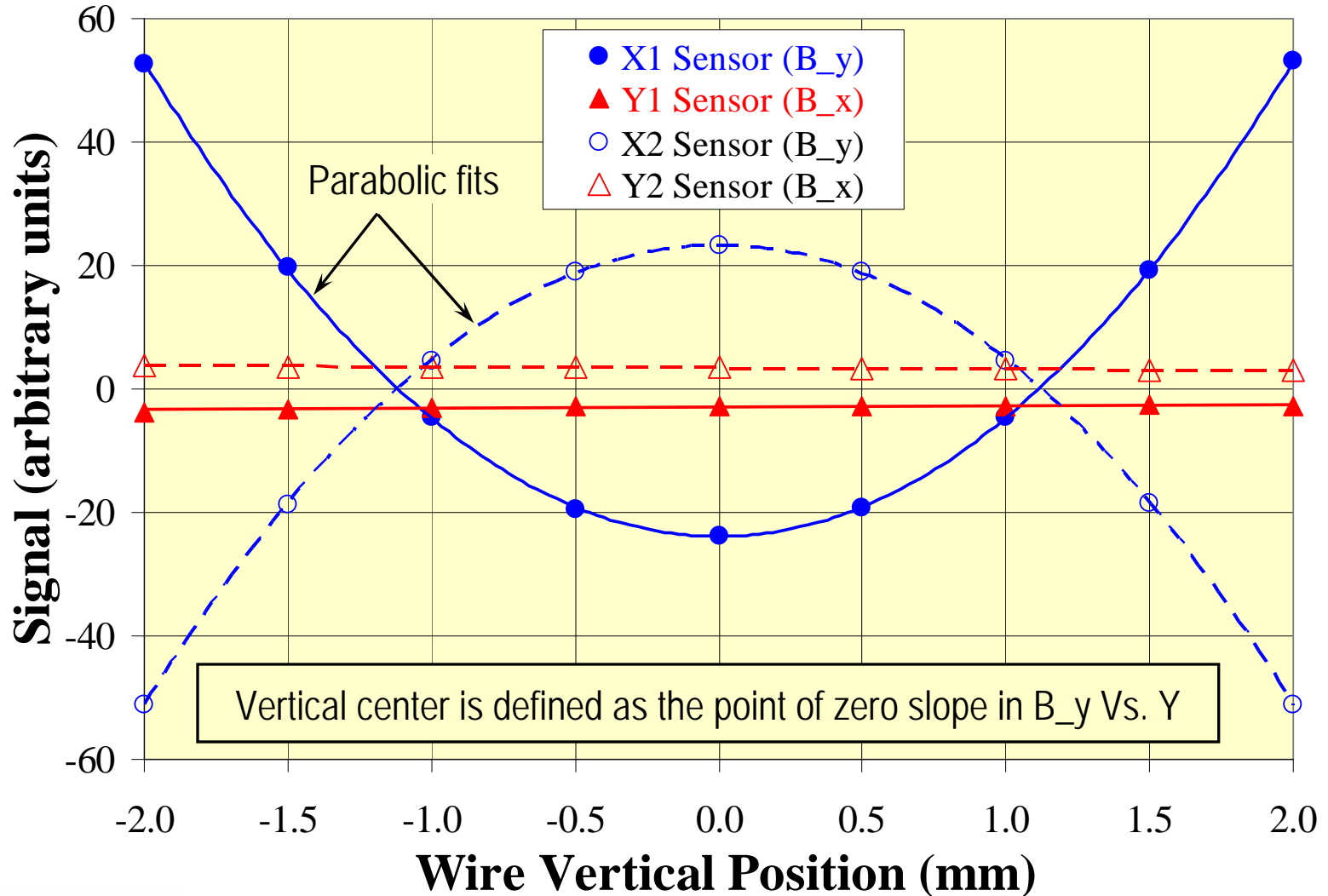
# Sextupole Measurements: Horizontal Scan

SLS Sextupole SR110 at 80 A (Mode = 6); 22-Jan-08

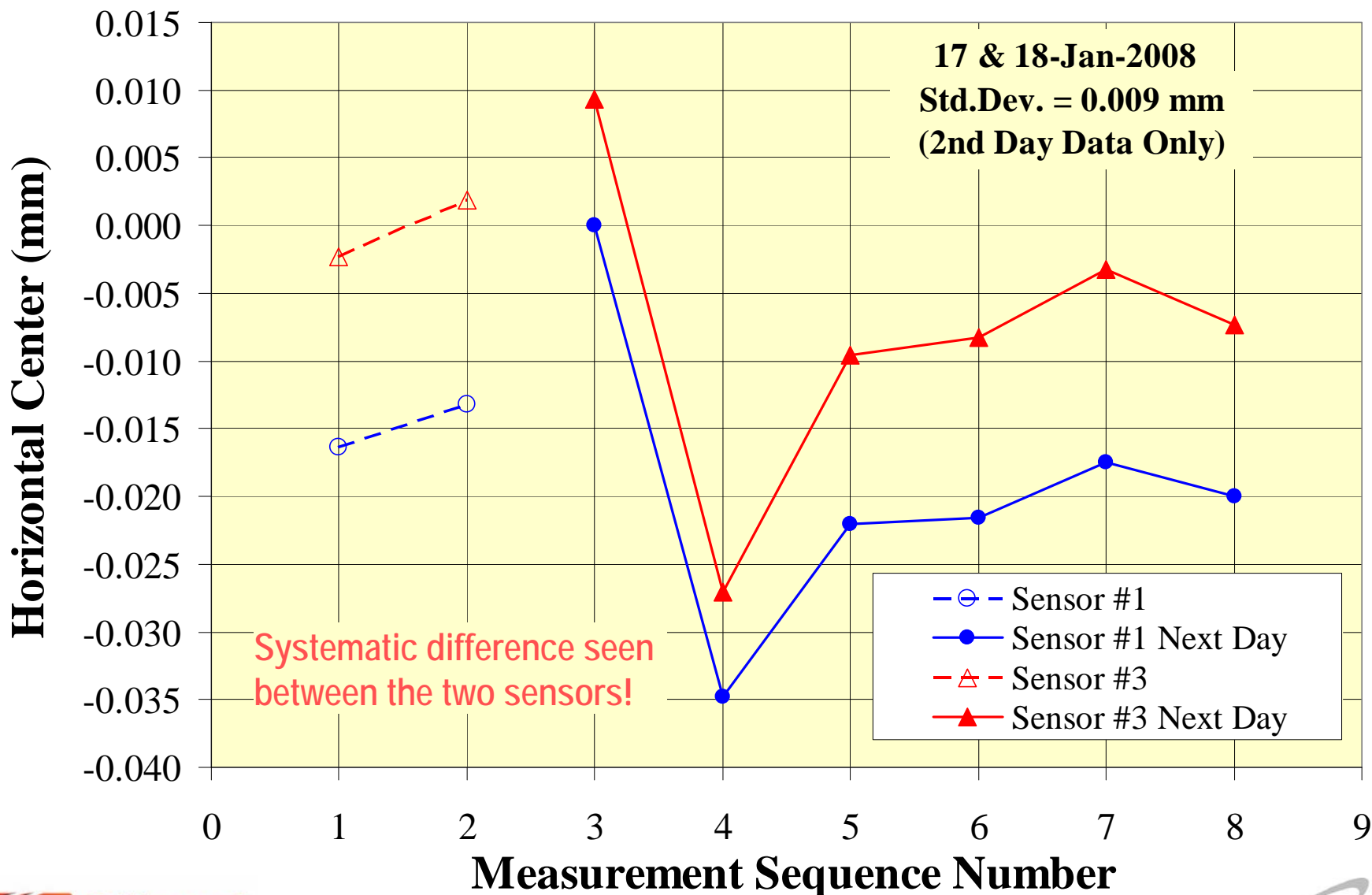


# Sextupole Measurements: Vertical Scan

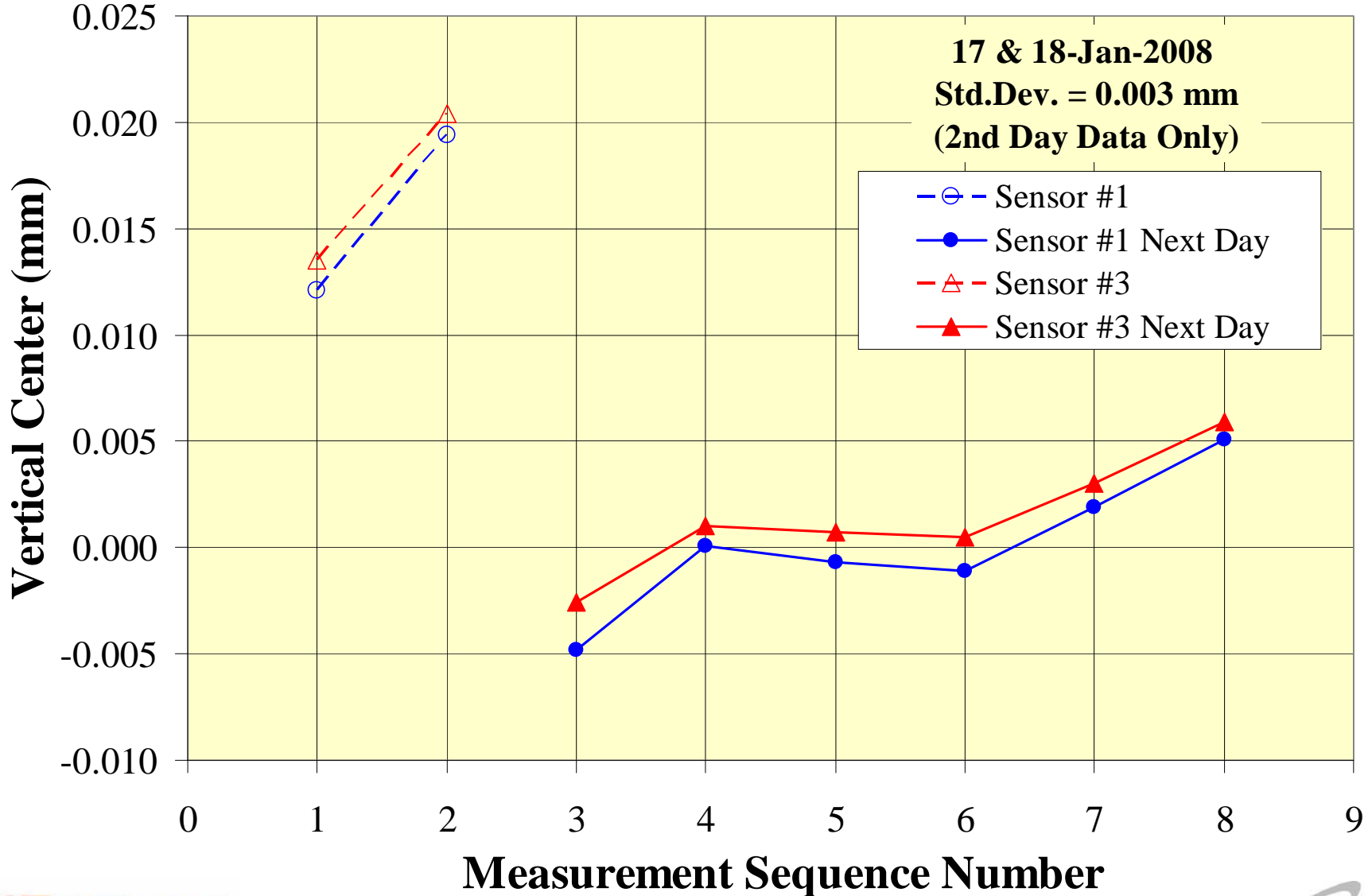
SLS Sextupole SR110 at 80 A (Mode = 6); 22-Jan-08



# Sextupole Measurement Reproducibility



# Sextupole Measurement Reproducibility



# Sextupole Measurements Using $B_x$ Instead of $B_y$

- Obtaining centers from  $B_y$  vs.  $X$  and  $B_y$  vs.  $Y$  plots uses only one set of sensors, and requires quadratic fits.
- One could also use scans of  $B_x$  vs.  $X$  (or  $Y$ ) for various values of  $Y$  (or  $X$ ). These plots are expected to be linear with slopes proportional to offsets in  $Y$  (or  $X$ ) direction.
- Doing three such scans allows to obtain centers from both  $B_x$  and  $B_y$  data. With 2 sets of sensors, one gets four values of magnetic center.

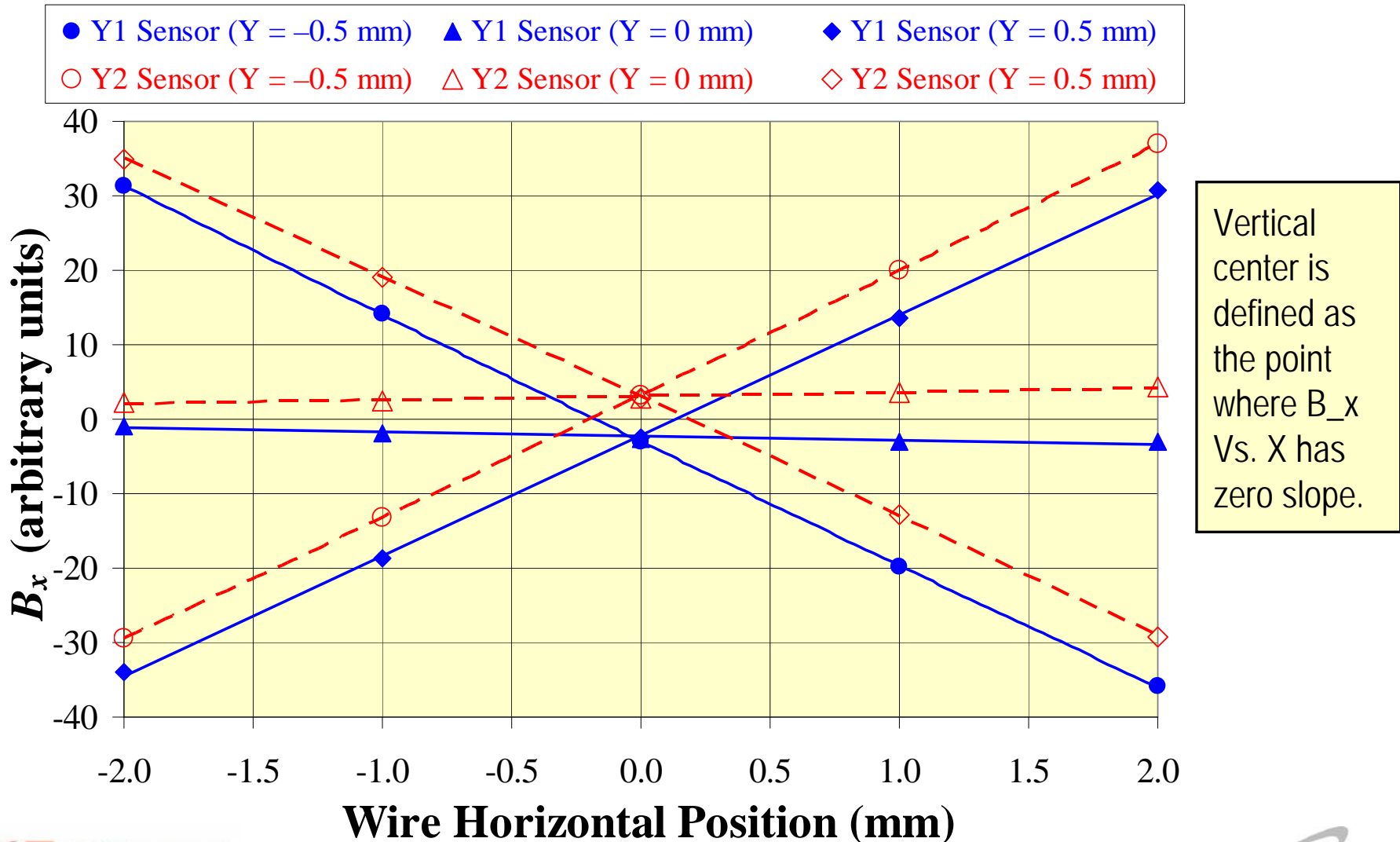
$$B_y = B_3 \left[ \frac{(x - x_0)^2 - (y - y_0)^2}{R_{ref}^2} \right]$$

$$B_x = 2B_3 \left[ \frac{(x - x_0)(y - y_0)}{R_{ref}^2} \right]$$



# Sextupole Measurements: $B_x$ vs. X Scans

SLS Sextupole SR110 at 80 A (Mode = 6); 23-Jan-08



# Comparison of Sextupole Data Using B\_x and B\_y

## SLS Sextupole at 80 A (23-Jan-2008)

Quantity	Sensors Used	B_x Data		B_y Data	
		Mode=6	Mode=8	Mode=6	Mode=8
X_Center (micron)	Pulley End	-11	-25	6	-8
	Fixed End	-11	-24	-11	-25
Y_Center (micron)	Pulley End	12	-3	-2	-3
	Fixed End	12	-2	1	2

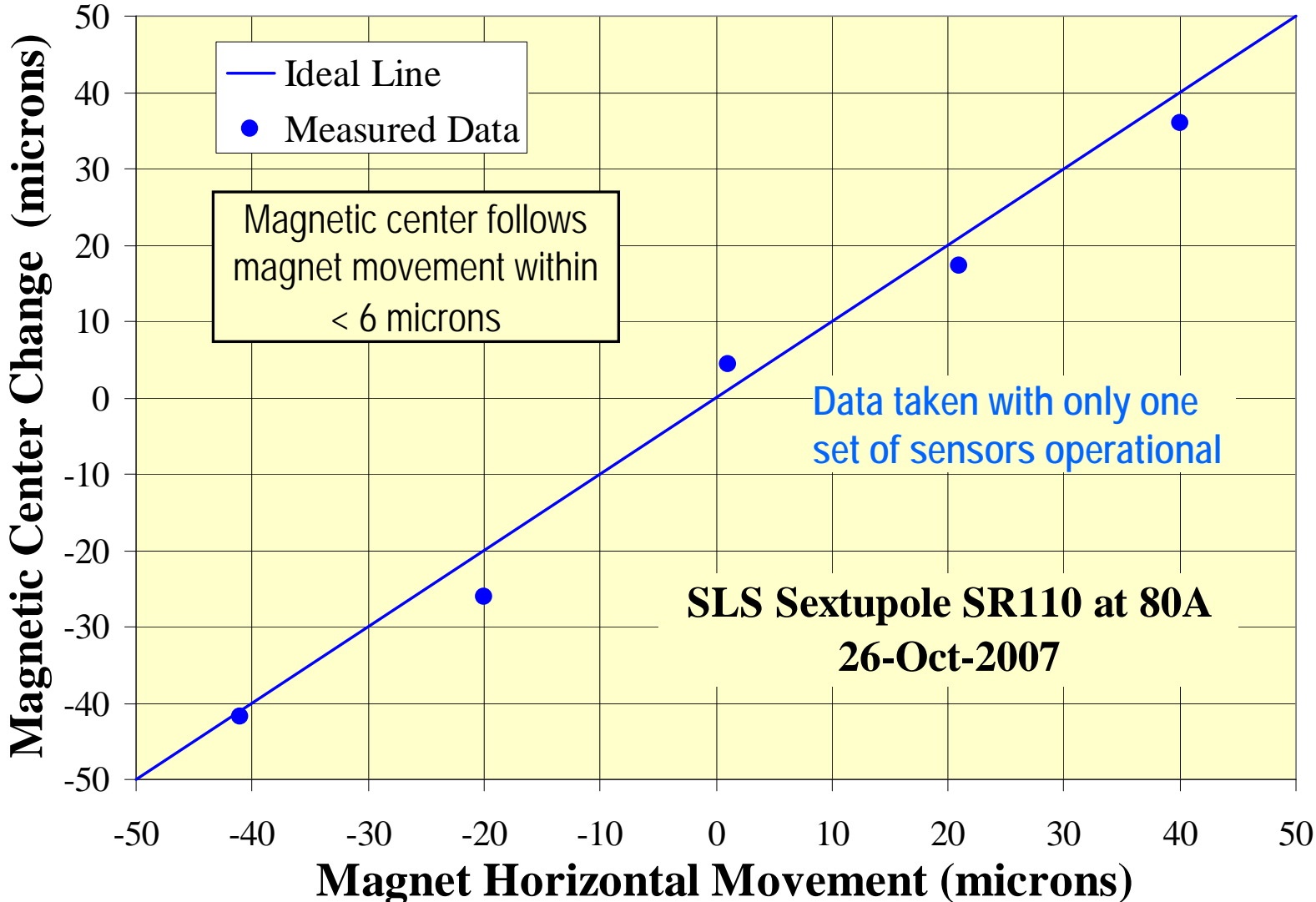
B\_x data from the two sensors show better consistency.  
 Systematic differences between results using two different modes are significant.

# Issue of Background Fields in Sextupole Meas.

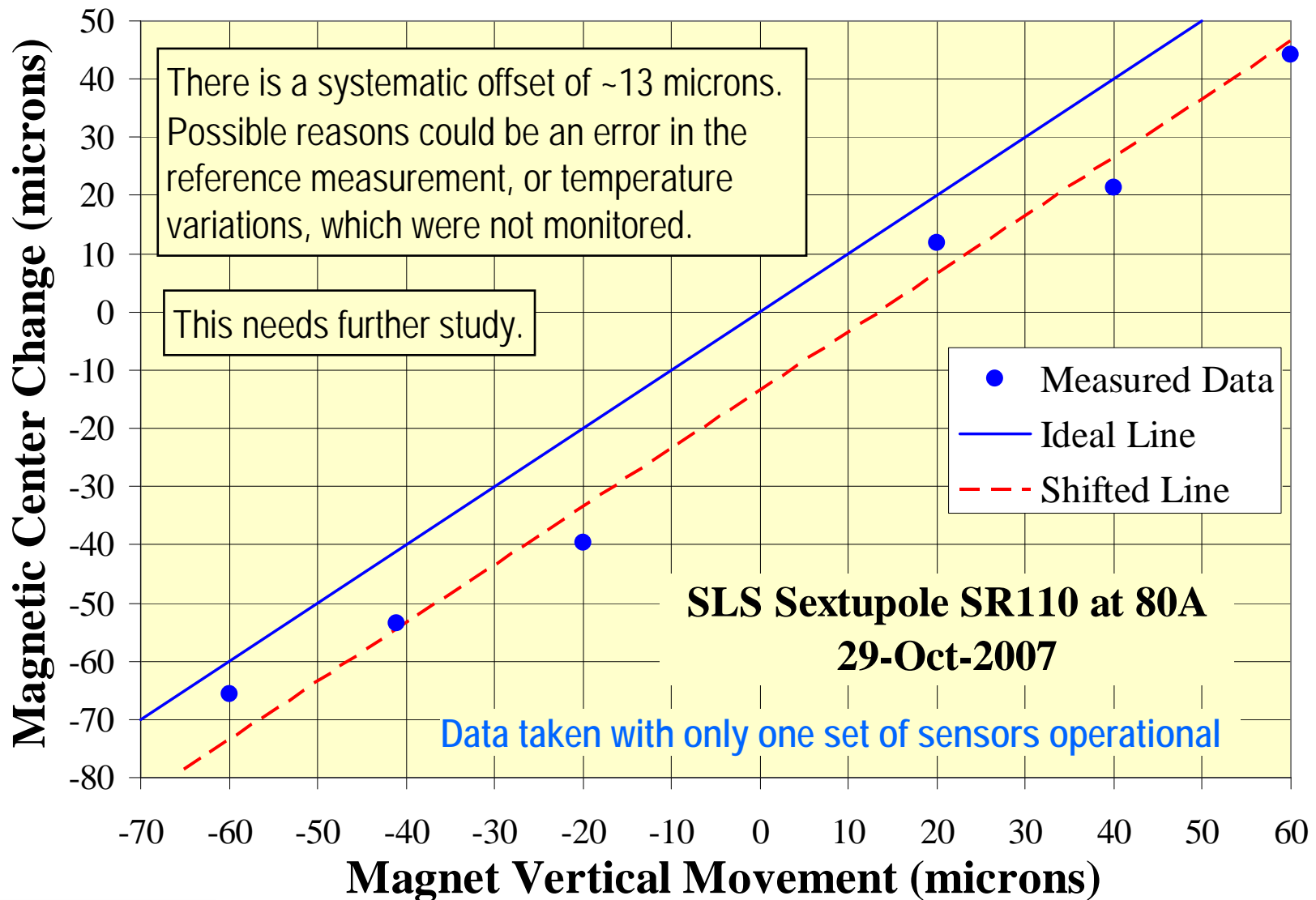
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- There is a significant quadrupole background field from quadrupole magnet(s) even when these are unpowered.
- Based on rotating coil data, the remnant integrated quadrupole field is  $\sim 0.02$  T in the SLS quadrupole.
- For a sextupole with integral field of 94.2 T/m at 80A, this could amount to a change in horizontal center by hundreds of microns, depending on quad position and mode used.
- The vertical center measurement is not affected because  $B_y$  (or  $B_x$ ) is independent of  $y$  (or  $x$ ) in a quadrupole field.
- Corrections must be made for this background field.

# Correlation with Magnet Moves (Sextupole; Horiz.)



# Correlation with Magnet Moves (Sextupole; Vertical)

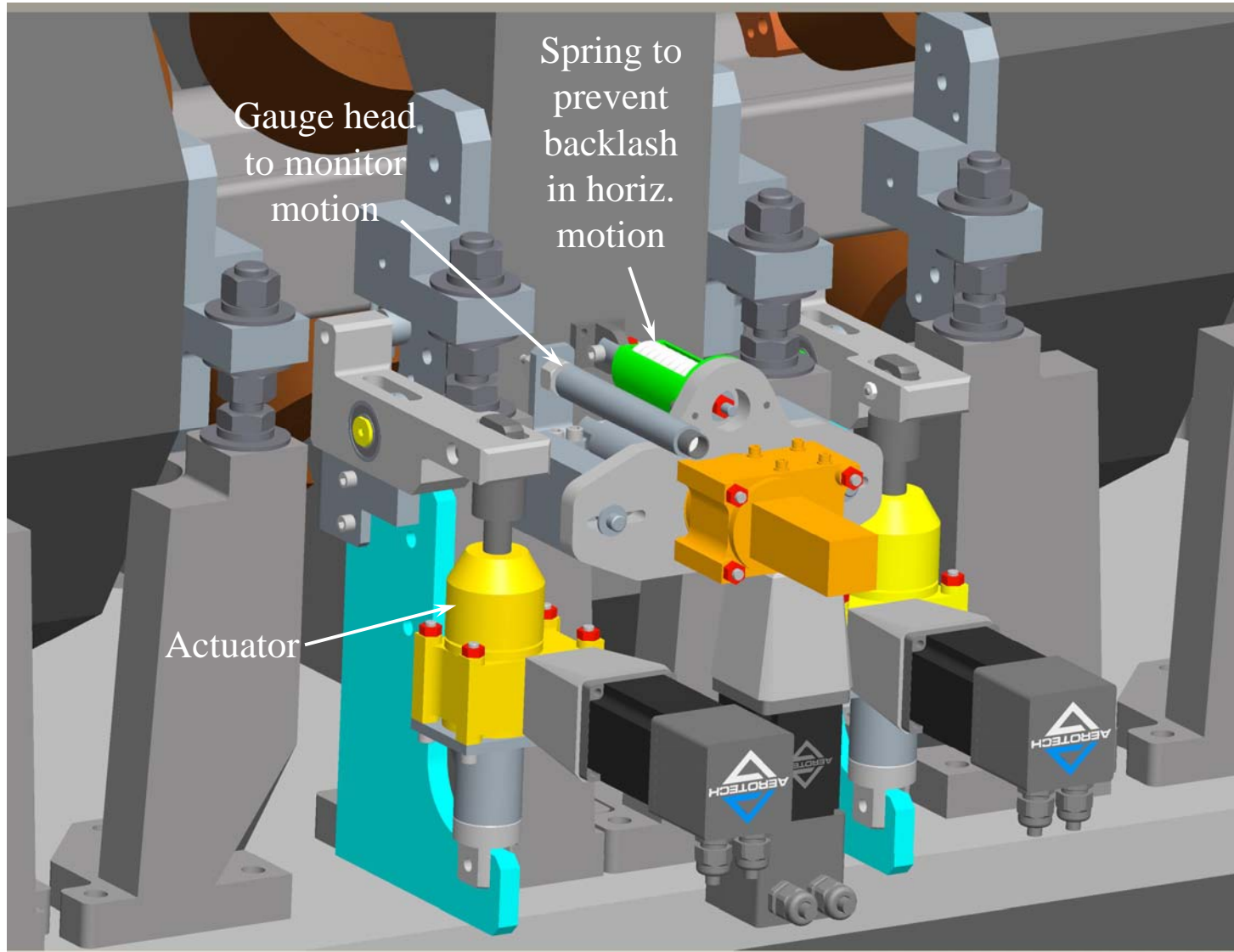


# Procedure for Multipole Alignment on a Girder

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- Install magnets on a girder, install vacuum chamber, and carry out a rough alignment.
- Set up girder on a vibrating wire test stand in a temperature controlled environment, and wait for steady temperature.
- Determine center of each magnet relative to the wire coordinates. Move the magnets to locate the magnetic centers on a line joining the two end points of the wire.
- Lock the magnets in place, while monitoring the magnet positions using displacement gauges.
- Survey the wire ends, and all girder and magnet fiducials (?) using laser trackers and portable CMM machines.

# Magnet Movers for Alignment on a Girder



Magnet movers will be installed on the girder, and then removed after the magnets are aligned and locked in place.

A test was performed to demonstrate ability to easily lock a magnet in place within 5-10 microns.

# Future Work

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- Study (and improve) the absolute accuracy of the measurements (better than ~10 microns desirable).
- Resolve various inconsistencies in detector responses.
- Survey of wire end V-notches relative to fiducials on test stand.
- Prototypes for motorized magnet movers.
- Integrate various components of hardware and software needed for measurements into a single, fully automated system for multipole alignment on a girder.



# Conclusions

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- A new vibrating wire R&D system has been designed, built and assembled.
- The R&D system has been used to measure a quadrupole and a sextupole received on loan from the Swiss Light Source.
- Unique feature of dual sensors allows extensive checks of consistency and systematic accuracy.
- Good correlation between magnet position and magnetic center has been shown (well within the required tolerance) for both quadrupole and sextupole magnets.
- Work is underway to further improve the accuracy of the system, and to automate the entire measurement and alignment sequence.

# Acknowledgements

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L. Rivkin, D. George

*Swiss Light Source*